

Last time

Solved Maxwell equations in Lorenz gauge:

$$\Phi(\vec{x}, t) = \frac{1}{4\pi\epsilon_0} \int d^3x' \frac{1}{|\vec{x} - \vec{x}'|} \rho(\vec{x}', t - \frac{|\vec{x} - \vec{x}'|}{c})$$

$$\vec{A}(\vec{x}, t) = \frac{\mu_0}{4\pi} \int d^3x' \frac{1}{|\vec{x} - \vec{x}'|} \vec{J}(\vec{x}', t - \frac{|\vec{x} - \vec{x}'|}{c})$$

Poynting's Theorem & Conservation of Energy and Momentum (cont'd)

Def.  $u \equiv \frac{1}{2} (\vec{E} \cdot \vec{D} + \vec{H} \cdot \vec{B})$  field energy density

Def.  $\vec{S} \equiv \vec{E} \times \vec{H}$  Poynting vector  
(flow of energy)

$$\frac{\partial u}{\partial t} + \vec{\nabla} \cdot \vec{S} = -\vec{J} \cdot \vec{E} \quad \text{energy conservation}$$

$$\frac{\partial u_{\text{mech}}}{\partial t} = \vec{J} \cdot \vec{E} \Rightarrow \frac{\partial u_{\text{field}}}{\partial t} + \frac{\partial u_{\text{mech}}}{\partial t} + \vec{\nabla} \cdot \vec{S} = 0$$



=> Definition Define Poynting vector (energy flow)

$$\vec{S} \equiv \vec{E} \times \vec{H}$$

$$\Rightarrow \frac{\partial u}{\partial t} + \vec{\nabla} \cdot \vec{S} = -\vec{J} \cdot \vec{E}$$

Statement of energy conservation.

$u \sim$  energy density of EM fields  $\Rightarrow u \rightarrow u_{field}$

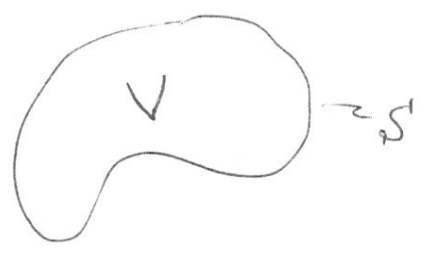
$\vec{J} \cdot \vec{E} \sim$  rate of <sup>EM</sup> energy change due to work done on charges:

$$\vec{J} \cdot \vec{E} = \frac{\partial u_{mech}}{\partial t} \leftarrow \begin{matrix} \text{mechanical} \\ \text{energy density} \end{matrix}$$

(momentum density)

$\vec{S}$   $\sim$  flow of energy in/out of the system:

$$\frac{\partial u_{field}}{\partial t} + \frac{\partial u_{mech}}{\partial t} = -\vec{\nabla} \cdot \vec{S}$$



=> integrate over V:

$$\frac{\partial E_{field}}{\partial t} + \frac{\partial E_{mech}}{\partial t} = - \oint_S da \cdot \vec{S}_n \sim \text{flow of energy through the border.}$$

(we assume that no particles move in/out of V!)

Momentum: force on a charge is

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \Rightarrow \text{"force density"}$$

is  $\vec{f} = \rho \vec{E} + \vec{J} \times \vec{B} \Rightarrow$  the change per unit time of the total momentum of all the

particles  $\vec{P}_{\text{mech}}$  is

$$\bullet \frac{d\vec{P}_{\text{mech}}}{dt} = \int d^3x [\rho \vec{E} + \vec{J} \times \vec{B}]$$

Now, let's work in vacuum:  $\rho = \epsilon_0 \vec{\nabla} \cdot \vec{E}$

$$\vec{J} = \frac{1}{\mu_0} \vec{\nabla} \times \vec{B} - \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\Rightarrow \frac{d\vec{P}_{\text{mech}}}{dt} = \int d^3x \left[ \epsilon_0 \vec{E} (\vec{\nabla} \cdot \vec{E}) + \epsilon_0 \vec{B} \times \frac{\partial \vec{E}}{\partial t} - \right.$$

$$\left. - \frac{1}{\mu_0} \vec{B} \times (\vec{\nabla} \times \vec{B}) \right] = \int d^3x \epsilon_0 \left[ \vec{E} (\vec{\nabla} \cdot \vec{E}) + \vec{E} \times \frac{\partial \vec{B}}{\partial t} - \right.$$

$$\bullet \left. - \frac{\partial}{\partial t} (\vec{E} \times \vec{B}) - c^2 \vec{B} \times (\vec{\nabla} \times \vec{B}) \right] = \begin{matrix} -\vec{\nabla} \times \vec{E} \\ \text{(Faraday)} \end{matrix}$$

$$= \epsilon_0 \int d^3x \left[ \vec{E} (\vec{\nabla} \cdot \vec{E}) + c^2 \vec{B} \cdot (\vec{\nabla} \cdot \vec{B}) - \right.$$

$$\left. - \vec{E} \times (\vec{\nabla} \times \vec{E}) - c^2 \vec{B} \times (\vec{\nabla} \times \vec{B}) \right] - \epsilon_0 \int d^3x \frac{\partial}{\partial t} (\vec{E} \times \vec{B})$$

Defining  $\vec{P}_{\text{field}} = \epsilon_0 \int d^3x \vec{E} \times \vec{B} = \frac{1}{c^2} \int d^3x \vec{E} \times \vec{H} = \frac{1}{c^2} \int \vec{S} d^3x$

we write

Poynting vector

$$\bullet \frac{d}{dt} \vec{P}_{\text{field}} + \frac{d}{dt} \vec{P}_{\text{mech}} = \epsilon_0 \int d^3x \left[ \vec{E} (\vec{\nabla} \cdot \vec{E}) + c^2 \vec{B} (\vec{\nabla} \cdot \vec{B}) - \right.$$

$$\left. - \vec{E} \times (\vec{\nabla} \times \vec{E}) - c^2 \vec{B} \times (\vec{\nabla} \times \vec{B}) \right]$$

$$\vec{E} \times (\vec{\nabla} \times \vec{E}) = \frac{1}{2} \vec{\nabla} (\vec{E} \cdot \vec{E}) - (\vec{E} \cdot \vec{\nabla}) \vec{E}$$

$$\Rightarrow \left[ \vec{E} (\vec{\nabla} \cdot \vec{E}) - \vec{E} \times (\vec{\nabla} \times \vec{E}) \right]_i = E_i \nabla_j E_j -$$

$$- \frac{1}{2} \nabla_i (E_j E_j) + E_j \nabla_j E_i = \nabla_j \left[ E_i E_j - \frac{1}{2} \delta_{ij} \vec{E}^2 \right]$$

Hence

$$i, j = 1, 2, 3$$

$$\left( \frac{d\vec{P}_{\text{field}}}{dt} + \frac{d\vec{P}_{\text{mech}}}{dt} \right)_i = \epsilon_0 \int d^3x \nabla_j \left[ E_i E_j - \frac{1}{2} \delta_{ij} \vec{E}^2 + \right.$$

$$\left. + c^2 \left( B_i B_j - \frac{1}{2} \delta_{ij} \vec{B}^2 \right) \right] \sim \text{surface term, responsible for momentum flow through the boundary}$$

**Definition** Define Maxwell stress tensor

(related to energy-momentum tensor) :  $i, j = 1, 2, 3$

$$T_{ij} = \epsilon_0 \left[ E_i E_j - \frac{1}{2} \delta_{ij} \vec{E}^2 + c^2 B_i B_j - \frac{c^2}{2} \delta_{ij} \vec{B}^2 \right]$$

Then

$$\frac{d}{dt} \left( \vec{P}_{\text{field}} + \vec{P}_{\text{mech}} \right)_i = \int_V d^3x \nabla_j T_{ij} = \oint_S da \cdot n_j T_{ij}$$

$$\text{Tr } T_{ij} = T_{ii} = \epsilon_0 \left[ -\frac{1}{2} \vec{E}^2 - \frac{c^2}{2} \vec{B}^2 \right] = -\frac{1}{2} \vec{D} \cdot \vec{E} - \frac{1}{2} \vec{B} \cdot \vec{H} =$$

= -u. ~ energy density.



Energy - Momentum tensor:

we studied:  $u \sim$  energy density

$\vec{S} \sim$  Poynting vector (energy flow)

$T_{ij} \sim$  Maxwell stress tensor (momentum flow)

These seemingly unrelated quantities form one tensor under Lorentz transformations, called energy-momentum tensor:

$$T^{\mu\nu} = \begin{pmatrix} u & S_x/c & S_y/c & S_z/c \\ S_x/c & -T_{11} & -T_{12} & -T_{13} \\ S_y/c & -T_{21} & -T_{22} & -T_{23} \\ S_z/c & -T_{31} & -T_{32} & -T_{33} \end{pmatrix}$$

where  $\mu, \nu = 0, 1, 2, 3$

on time component:  $x^0 = ct, x^1 = x, x^2 = y, x^3 = z$

all the above conservation laws read (no pt. charges, can be included in  $T^{\mu\nu}$ )

$$\frac{\partial}{\partial x^\mu} T^{\mu\nu} = 0$$

(summation over  $\mu$ )

$$T_\mu^\mu = u + T_i^i = u - u = 0 \sim \text{traceless}$$

$T_{11}, T_{22}, T_{33} \sim$  radiation pressure components

( $T_{ij}$  is the flux of the  $i$ th component of momentum density in the  $\hat{j}$  direction)

Classification of Physical Quantities by

Space-Time Symmetries.

A. Spatial rotations.

$i, j = 1, 2, 3$

$x_i \rightarrow x'_i = R_{ij} x_j$ ,  $R_{ij}$  - rotation matrix

$\vec{x}^T \vec{x} = \vec{x}'^T \vec{x}'$  under rotation  $\Rightarrow (R_{ij} x_j) (R_{ik} x_k) = x_i x_i$

$\Rightarrow R_{ij} R_{ik} = \delta_{jk} \Rightarrow (R^{-1})_{ij} = R_{ji}$   
 $\Rightarrow (\det R)^2 = 1$

$\det R = +1 \sim$  rotation w/o reflection ( $\det R = -1$ : rotation + reflection)

vectors:  $A_i \rightarrow A'_i = R_{ij} A_j$

tensors:  $T \rightarrow T'_{i_1 i_2 \dots i_n} = R_{i_1 j_1} R_{i_2 j_2} \dots R_{i_n j_n}$

(definition)  $n =$  rank of the tensor  $\cdot T_{j_1 j_2 \dots j_n}$

B. Spatial Reflection (parity)

$\vec{x} \rightarrow -\vec{x} \sim$  all vectors (or polar vectors)

transform like this

$\vec{z} = \vec{x} \times \vec{y} \Rightarrow \left. \begin{matrix} \vec{x} \rightarrow -\vec{x} \\ \vec{y} \rightarrow -\vec{y} \end{matrix} \right\} \Rightarrow \vec{z} \rightarrow \vec{z}$  axial vector  
(pseudovector)



Inversion is also called parity IP.

IP: vector  $\rightarrow$  -vector, axial vector  $\rightarrow$  axial vector  
 $p = -1$   $p = +1$

Tensor of rank N:  $IP T_{i_1 \dots i_N} = (-1)^N T_{i_1 \dots i_N}$

Pseudotensor of rank N:  $IP T_{i_1 \dots i_N} = (-1)^{N+1} T_{i_1 \dots i_N}$

[E.g.  $\vec{z} = \vec{x} \times \vec{y} \Rightarrow z_i = \epsilon_{ijk} x_j y_k \Rightarrow \epsilon_{ijk}$  has  $p = +1$   
 $\uparrow$   $\uparrow$   $\uparrow$   
 $p = +1$   $p = -1$   $p = -1$

$\Rightarrow p = (-1)^{3+1} \Rightarrow \epsilon_{ijk}$  is pseudotensor.]

pseudoscalar anyone?  $\vec{a} \cdot (\vec{b} \times \vec{c})$ .

C. Time reversal:  $t \rightarrow -t$

$\Pi \vec{x} = \vec{x}$ ,  $\vec{p} = \frac{d\vec{x}}{dt} \Rightarrow \Pi \vec{p} = -\vec{p} \sim T\text{-odd}$ .  
 $\uparrow$  T-even.

<u>Quantity</u>	<u>Tensor Rank</u>	<u>Parity</u>	<u>Time Reversal</u>
$\vec{x}$	vector	-1	1
$\vec{v} = d\vec{x}/dt$	vector	-1	-1
$\vec{p}$	vector	-1	-1
$\vec{L} = \vec{x} \times \vec{p}$	1	1	-1
$\vec{F} = m\vec{a}$	1	-1	1
$\vec{N} = \vec{x} \times \vec{F}$	1	1	1
E ~ energy	0	1	1

<u>Quantity</u>	<u>Tensor Rank</u>	<u>Parity</u>	<u>Time Reversal</u>
$\rho$	0	1	1
$\vec{J} (= \rho \vec{v})$	1	-1	-1
$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \Rightarrow$			
$\left. \begin{matrix} \vec{E} \\ \vec{P} \\ \vec{D} \end{matrix} \right\}$	1	-1	1
$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow$			
$\left. \begin{matrix} \vec{B} \\ \vec{M} \\ \vec{H} \end{matrix} \right\}$	1	1	-1
$\vec{S} = \vec{E} \times \vec{H}$	1	-1	-1
$T_{ij}$	2	1	1