

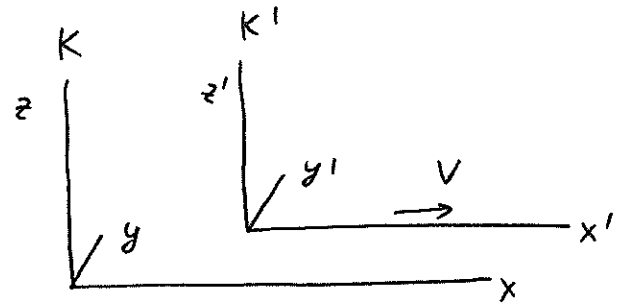
Last time

Special Theory of Relativity (cont'd)

Lorentz Transformations

$$x^0 = ct, \quad x^1 = x, \quad x^2 = y, \quad x^3 = z$$

$$\beta = \frac{v}{c}, \quad \gamma = \frac{1}{\sqrt{1-\beta^2}}$$



$$\begin{pmatrix} x'^0 \\ x'^1 \\ x'^2 \\ x'^3 \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix}.$$

$$\text{or } x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}, \quad \mu, \nu = 0, 1, 2, 3$$

Def. interval

$$ds^2 = c^2 dt^2 - d\vec{x}^2$$

it is Lorentz-invariant

Proper time:

$$d\tau = \frac{ds}{c}$$

(time in rest frame)

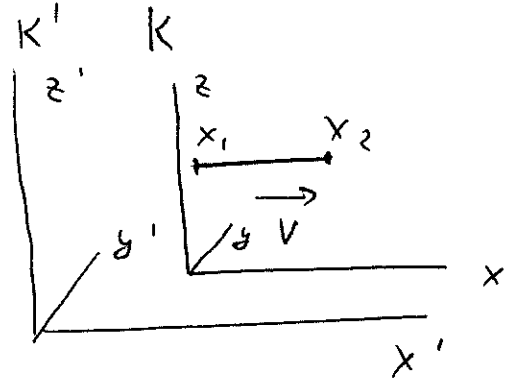
$$\tau_2 - \tau_1 = \int_{t_1}^{t_2} dt \sqrt{1-\beta^2(t)} \Rightarrow \Delta\tau \leq \Delta t \quad \text{time dilation}$$

Lorentz Contraction: $l = l_0 \sqrt{1-\beta^2}$, where

$l_0 = \text{proper length} = \text{length in rest frame}$

Lorentz Contraction.

Imagine a bar ^(rod) moving at constant velocity (see figure).



Proper length is defined

as its length in the rest frame of the bar (frame K).

$$\Rightarrow x_1 = \frac{x'_1 - vt'}{\sqrt{1 - \frac{v^2}{c^2}}}, \quad x_2 = \frac{x'_2 - vt'}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\Rightarrow \Delta x = x_2 - x_1 = \frac{\Delta x'}{\sqrt{1 - \frac{v^2}{c^2}}} = \frac{x'_2 - x'_1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

\Rightarrow if l_0 is proper length, $l_0 = \Delta x$

$$\Rightarrow l = \Delta x' \Rightarrow l = l_0 \sqrt{1 - \frac{v^2}{c^2}}$$

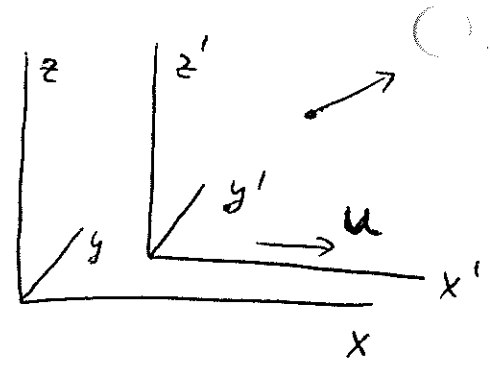
$\Rightarrow l \leq l_0$ Lorentz contraction.

\sim objects appear shorter in other frames.

Velocity Transformations.

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$$\left\{ \begin{array}{l} x = \gamma (x' + ut') \\ y = y' \\ z = z' \\ ct = (t'c + \beta x') \gamma \end{array} \right.$$



$$\Rightarrow V_x = \frac{dx}{dt} = \frac{dx' + ut'}{dt' + \frac{\beta}{c} dx'} = \frac{V_x' + u}{1 + \frac{uV_x'}{c^2}} = V_x$$

where $V_x' = \frac{dx'}{dt'}$

$$V_y = \frac{dy}{dt} = \frac{dy'}{\gamma (dt' + \frac{\beta}{c} dx')} = \frac{V_y'}{\gamma (1 + \frac{\beta}{c} V_x')} = \frac{V_y' \sqrt{1 - \frac{u^2}{c^2}}}{1 + \frac{uV_x'}{c^2}} = V_y$$

Similarly $V_z = \frac{V_z' \sqrt{1 - \frac{u^2}{c^2}}}{1 + \frac{uV_x'}{c^2}}$

($c \rightarrow \infty$ get Galilean $V_x = u_x' + u, V_y' = V_y, V_z' = V_z$)

Imagine the case when $V_x = V \cos \theta, V_y = V \sin \theta, V_z = 0$

$$\Rightarrow V_z' = 0, \tan \theta = \frac{V_y}{V_x} = \frac{V_y'}{\gamma (V_x' + u)} \Rightarrow$$

$$\Rightarrow \text{write } V_x' = V' \cos \theta' \\ V_y' = V' \sin \theta'$$

$$\Rightarrow \tan \theta = \frac{v' \sin \theta'}{\gamma (v' \cos \theta' + u)}$$

Light aberration: if the particle is

a photon $\Rightarrow v = v' = c \Rightarrow \tan \theta = \frac{\sin \theta'}{\gamma (\cos \theta' + \beta)}$ $\beta = \frac{u}{c}$
 $\gamma = \frac{1}{\sqrt{1-\beta^2}}$

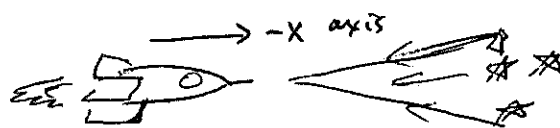
$$\Rightarrow v_x = \frac{v_x' + u}{1 + \frac{u v_x'}{c^2}} \Rightarrow \cos \theta = \frac{\cos \theta' + \beta}{1 + \beta \cos \theta'}$$

$$v_y = \frac{v_y'}{\gamma (1 + \frac{u v_x'}{c^2})} \Rightarrow \sin \theta = \frac{\sin \theta'}{\gamma (1 + \beta \cos \theta')}$$

\Rightarrow if $u \rightarrow c \Rightarrow \sin \theta \rightarrow 0, \cos \theta \rightarrow 1 \Rightarrow$

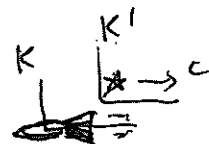
$\Rightarrow \theta \rightarrow 0 \Rightarrow$ For UR spaceship all stars appear in the small cone ahead,

at $\theta = 0$.



K - space ship frame, K' - universe, $\theta = 0$ means the light comes along $+x$ axis

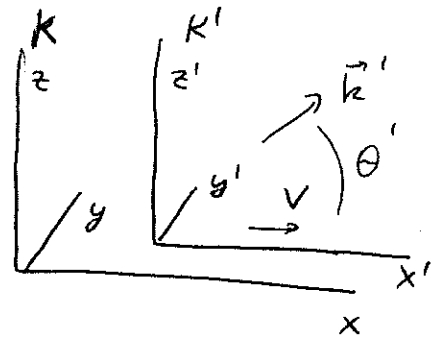
Four - vectors.
 $x_0 = ct, x_1 = x, x_2 = y, x_3 = z$
 (x_0, x_1, x_2, x_3) is a 4-vector.



Relativistic Doppler Shift.

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Consider a plane wave with frequency ω & wave vector \vec{k} in frame K . Assume that it has frequency ω' & wave vector \vec{k}' in frame K' .



The phase of the wave is a number

$$\Rightarrow \text{invariant} \Rightarrow \varphi = \omega t - \vec{k} \cdot \vec{x} = \omega' t' - \vec{k}' \cdot \vec{x}'$$

\Rightarrow if the boost is done in the x -direction

$$\Rightarrow k_y = k'_y, k_z = k'_z \quad (\text{as } y = y', z = z' \sim \text{can vary} \Rightarrow \text{equate the coefficients})$$

$$x' = \gamma(x - vt), \quad t' = \gamma\left(t - \frac{\beta}{c}x\right) \Rightarrow$$

$$\Rightarrow \underline{\omega t - k_x \cdot x} = \omega' \gamma\left(t - \frac{\beta}{c}x\right) - k'_x \cdot \underline{\gamma(x - vt)}$$

$$\omega = \gamma(\omega' + k'_x v)$$

$$k_x = \gamma\left(\omega' \frac{\beta}{c} + k'_x\right) \Rightarrow$$

$$\omega' = \gamma(\omega - v k_x)$$

$$k'_x = \gamma\left(k_x - \beta \frac{\omega}{c}\right)$$

For \vec{k} pointing in any random direction:

$$\text{define } k^0 = \omega/c, \quad k'^0 = \omega'/c \Rightarrow \vec{\beta} \equiv \vec{v}/c \Rightarrow$$

$$\Rightarrow \begin{cases} k'^0 = \gamma(k^0 - \vec{\beta} \cdot \vec{k}) \\ k'_{\parallel} = \gamma(k_{\parallel} - \beta k^0) \\ \vec{k}'_{\perp} = \vec{k}_{\perp} \end{cases}$$

where k_{\parallel} is component $\parallel \vec{v}$
 \vec{k}_{\perp} are components $\perp \vec{v}$.

For an EM wave: $|\vec{k}| = k^0 = \frac{\omega}{c}$, $|\vec{k}'| = k'^0 = \frac{\omega'}{c}$ (114)

\Rightarrow if the angle between \vec{k} and \vec{v} is θ in K and θ' in K' $\Rightarrow \omega' = \gamma(\omega - \beta \omega \cos \theta) \Rightarrow$

$$\Rightarrow \omega' = \gamma \omega (1 - \beta \cos \theta) \quad \text{Doppler shift}$$

$$\begin{cases} \frac{\omega'}{c} \cos \theta' = \gamma \left(\frac{\omega}{c} \cos \theta - \beta \cdot \frac{\omega}{c} \right) \\ \frac{\omega'}{c} \sin \theta' = \frac{\omega}{c} \sin \theta \end{cases}$$

$$\Rightarrow \tan \theta' = \frac{\sin \theta}{\gamma (\cos \theta - \beta)}$$

(cf. with light aberration.)

Four - vectors.

We have seen one example: $x^0 = ct$, $x^1 = x$, $x^2 = y$, $x^3 = z$

$$\begin{pmatrix} x_0' \\ x_1' \\ x_2' \\ x_3' \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

Definition A 4-vector A^M is a set of 4

quantities (A^0, A^1, A^2, A^3) , which under Lorentz transformation transform as

$$\begin{pmatrix} A^{0'} \\ A^{1'} \\ A^{2'} \\ A^{3'} \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix}.$$

$\Rightarrow A^M, M=0,1,2,3$ is a contravariant vector if it transforms according to:

$$A^{M'} = \frac{\partial x^{M'}}{\partial x^M} A^M \quad (\text{equivalent to above})$$

$\Rightarrow B_M, M=0, \dots, 3$ is a covariant vector

if
$$B_{M'} = \frac{\partial x^M}{\partial x^{M'}} B_M$$

Example: $\frac{\partial \varphi}{\partial x^M}$ is a covariant vector as

$$\frac{\partial \varphi}{\partial x^{M'}} = \frac{\partial x^M}{\partial x^{M'}} \frac{\partial \varphi}{\partial x^M}.$$

One can define tensors by

$$A^{M'} B^{N'} = \frac{\partial x^{M'}}{\partial x^M} \frac{\partial x^{N'}}{\partial x^N} A^M B^N \Rightarrow \text{rank two contravariant}$$

tensor would be $C^{M'N'} = \frac{\partial x^{M'}}{\partial x^M} \frac{\partial x^{N'}}{\partial x^N} C^{MN}$, etc.