

Last time

Four-vectors

(Def.) A'^μ :
$$A'^\mu = \frac{\partial x^\mu}{\partial x^\nu} A^\nu$$
 contravariant 4-vector
OR $A'^\mu = \Lambda^\mu_\nu A^\nu$ $\mu, \nu = 0, 1, 2, 3$

\Rightarrow always some over repeated indices (one upper, one lower)

(Def.) B_μ :
$$B_\mu = \frac{\partial x^\mu}{\partial x^\nu} B_\nu$$
 covariant 4-vector
or $B_\mu = \Lambda_\mu^\nu B_\nu$

(Def.) $A_\mu B^\mu = A_0 B^0 + A_1 B^1 + A_2 B^2 + A_3 B^3$

scalar product : it is Lorentz-invariant

(Def.) metric tensor $g_{\mu\nu}$:
$$\underbrace{ds^2 = g_{\mu\nu} dx^\mu dx^\nu}_{\text{interval}}$$

$$\Rightarrow g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \quad (\text{Minkowski space})$$

(Def.) g^{M0} by:
$$(g^{M2} g_{\alpha\nu} = \delta_M^\alpha)$$

$$\Rightarrow g^{M0} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} = g_{\mu\nu}$$

$A^\mu = g^{M0} A_0$ and $A_\mu = g_{\mu\nu} A^\nu$ \sim raises & lowers indices

metric tensor

Examples: $x^m = (ct, \vec{x})$, $x_\mu = (ct, -\vec{x})$

$\partial_\mu \equiv \frac{\partial}{\partial x^\mu} \Rightarrow \partial_\mu \varphi$ is a covariant 4-vector

$\partial^\mu \equiv \frac{\partial}{\partial x_\mu} \Rightarrow \partial^\mu \varphi$ contravariant
 φ a scalar

$\partial_\mu A^\mu$ = Lorentz invariant

$\partial_\mu \partial^\mu = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \vec{\nabla}^2$ is also Lorentz-invariant

\Rightarrow wave eq'n operator is Lorentz-invariant!

4-velocity

Def.

$$u^\mu \equiv \frac{dx^\mu}{d\tau}$$

$$\Rightarrow u^\mu = \gamma(c, \vec{v}), u_\mu u^\mu = c^2.$$

But: time is not a scalar!

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$\frac{dx^m}{dt} \sim \frac{dx^m}{dx^0} \sim$ not a Lorentz-vector.

\Rightarrow try proper time $d\tau = \frac{ds}{c} \Rightarrow u^{\mu} = \frac{dx^{\mu}}{d\tau}$ 4-velocity

$$\text{as } d\tau = \frac{dt}{\gamma} \Rightarrow u^0 = \frac{c dt}{dt/\gamma} = c\gamma$$

$$\vec{u} = \frac{d\vec{x}}{dt} \cdot \gamma = \gamma \cdot \vec{v} \Rightarrow u^{\mu} = \gamma(c, \vec{v})$$

Note $u_{\mu} u^{\mu} = c^2$.

Boost in terms of rapidity.

~~$$\begin{pmatrix} A'^0 \\ A'^1 \\ A'^2 \\ A'^3 \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix}$$~~

\Rightarrow Define rapidity η

~~$$\text{by } \beta = \tanh \eta = \frac{e^{\eta} - e^{-\eta}}{e^{\eta} + e^{-\eta}}$$~~

Define

light-cone coordinates

~~$$A^+ = \frac{A^0 + A^3}{\sqrt{2}}$$~~

~~$$A^- = \frac{A^0 - A^3}{\sqrt{2}}$$~~

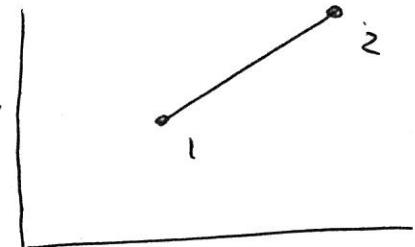
\Rightarrow then

~~$$A_{\mu} A^{\mu} = 2 A^+ A^- - (A^1)^2 - (A^2)^2$$~~

Relativistic Mechanics.

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Consider a free particle (moving along a straight line). We need to construct a Lorentz-invariant action for such a particle. It's characterized by a 4-vector $x^M \Rightarrow$ the



only Lorentz-invariant is the interval \Rightarrow

$$\Rightarrow \int_1^2 ds \quad (\text{can't have } \int f(s)^2 ds \sim \text{still infinitesimal})$$

the action as

$$\Rightarrow \text{write} \quad S = -A \cdot \int_1^2 ds$$

$$\text{As } ds^2 = c^2 dt^2 - (dx)^2 = dt^2 (1 - \beta^2(t)) \Rightarrow$$

$$\Rightarrow ds = dt \sqrt{1 - \beta^2(t)} \Rightarrow S = -A \int_{t_1}^{t_2} dt \sqrt{1 - \beta^2(t)}.$$

$$\Rightarrow \text{as } S = \int_{t_1}^{t_2} dt \cdot L, \text{ where } L \text{ is the}$$

Lagrangian,

$$\Rightarrow L = -Ac \sqrt{1 - \beta^2(t)}.$$

Now, in classical non-relativistic mechanics we know that $L = K - V$

\uparrow
kinetic energy \nwarrow potential energy

$$\Rightarrow \text{for a free } ^{NR} \text{ particle } V=0 \Rightarrow L = K = \frac{1}{2}mv^2$$

(We know that in non-relativistic (NR)

$$\text{limit : } K = \frac{1}{2}mv^2. \Rightarrow \text{as } \beta \rightarrow 0 \Rightarrow$$

$$\Rightarrow L = -Ac + \underbrace{Ac \frac{1}{2}\beta^2}_{\text{constant } \sim \text{drop, not important for dynamics}} + \dots$$

constant \sim drop, not important for dynamics

$$\Rightarrow Ac \frac{1}{2} \frac{v^2}{c^2} = \frac{1}{2}mv^2 \Rightarrow A = mc$$

$$\Rightarrow S = -mc \int_1^2 ds = -mc^2 \int_{t_1}^{t_2} dt \sqrt{1 - \beta^2(t)}$$

$$L = -mc^2 \sqrt{1 - \beta^2(t)}$$

action and
Lagrangian for a
free point particle

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The particle's Energy & Momentum.

The ^{free}₁ particle's degrees of freedom are coordinates \vec{x} & t . Momentum is defined

by: $p^i = \frac{\partial L}{\partial \dot{x}^i}$, where $i = 1, 2, 3$ and $\dot{x}^i = \frac{dx^i}{dt}$.

(know from classical mechanics).

$$\Rightarrow p^i = \frac{\partial L}{\partial v^i} = -mc^2 \frac{-\gamma v^i/c^2}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\Rightarrow \vec{p} = \frac{m\vec{v}}{\sqrt{1 - \frac{v^2}{c^2}}} = \gamma m\vec{v}$$

Energy is defined by $E = \vec{p} \cdot \vec{x} - L =$

$$= \vec{p} \cdot \vec{v} - L = \gamma m v^2 + mc^2 \sqrt{1 - \frac{v^2}{c^2}} =$$

$$= \gamma \left[mv^2 + mc^2 \left(1 - \frac{v^2}{c^2} \right) \right] = mc^2 \gamma$$

$$\Rightarrow E = mc^2 \gamma = \frac{mc^2}{\sqrt{1 - \frac{v^2}{c^2}}}.$$

(world's most famous formula)

Remember that $u^{\mu} = \gamma(c, \vec{v})$ ~ 4-velocity.

We now see that $(\frac{E}{c}, \vec{p}) = m\gamma(c, \vec{v}) \Rightarrow$

\Rightarrow we have a new 4-momentum four-vector:

$$p^{\mu} = m u^{\mu}$$

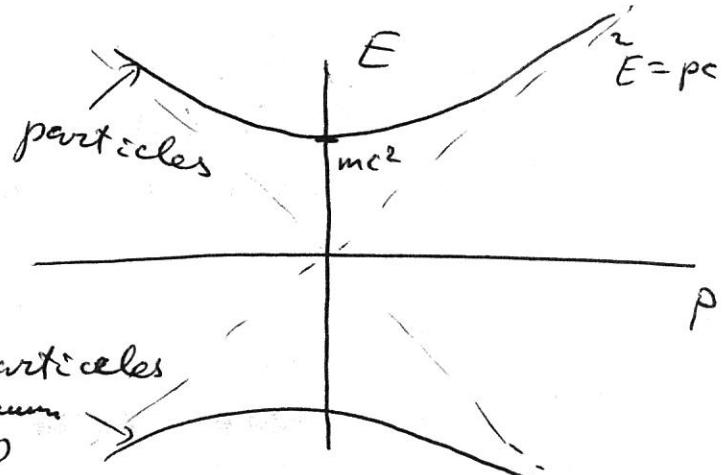
, where

$$p^0 = \frac{E}{c}$$

$$p^i = (\vec{p})^i$$

Note that $p_{\mu} p^{\mu} = m^2 u_{\mu} u^{\mu} = m^2 \gamma^2 (c^2 - v^2) = m^2 c^2 \Rightarrow \frac{E^2}{c^2} - \vec{p}^2 = m^2 c^2$ or

$$E^2 = \vec{p}^2 c^2 + m^2 c^4$$



4-vector p^{μ} transforms

in the usual way:

$$p^0 = \gamma(p^{0'} + \beta p^x)$$

$$p^x = \gamma(p^{x'} + \beta p^0)$$

$$p^y = p^{y'} \quad p^z = p^{z'}$$

(boost in x-direction)

Ref-

kinetic energy

$$\begin{aligned} T &= E(v) - E(0) = \\ &= mc^2 [\gamma_u - 1] \end{aligned}$$

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Newtonian mechanics: $\vec{F} = \frac{d\vec{P}}{dt}$ (force)

\Rightarrow define force as

$$f^M = \frac{dP^M}{d\tau}$$

$\Rightarrow \vec{F} = \frac{d\vec{P}}{dt} \propto \Rightarrow$ in NR limit gives
 "Newtonian result."

$$\frac{dP^0}{d\tau} = \propto \frac{dP^0}{dt}; \text{ Note that } f^M u_\mu = 0$$

$$(u_\mu f^M = u_\mu \frac{dP^M}{d\tau} = u_\mu m \frac{du^\mu}{d\tau} = \frac{1}{2} m \frac{d(u_\mu u^\mu)}{d\tau} =$$

$$= \frac{1}{2} m \frac{dc^2}{d\tau} = 0) \Rightarrow f^0 \cdot u^0 = \vec{f} \cdot \vec{v} \Rightarrow$$

$$\Rightarrow f^0 c = \vec{f} \cdot \vec{v} \Rightarrow f^0 = \frac{\vec{f} \cdot \vec{v}}{c} \Rightarrow \propto \frac{dP^0}{dt} = f^0 = \frac{\vec{f} \cdot \vec{v}}{c}$$

$$\Rightarrow \propto \frac{dE}{dt} = \vec{f} \cdot \vec{v} = \propto \vec{F} \cdot \vec{v} \Rightarrow \frac{dE}{dt} = \vec{F} \cdot \vec{v}$$

(\vec{F} is Newtonian NR force).

\Rightarrow 4-momentum is conserved in particle interactions.

$$\sum p_{\text{initial}}^M = \sum p_{\text{final}}^M$$