

Last time

Def.

$$\vec{P}_{\text{field}} = \int d^3x \frac{1}{c^2} \vec{S} = \int d^3x \frac{1}{4\pi c} \vec{E} \times \vec{B}$$

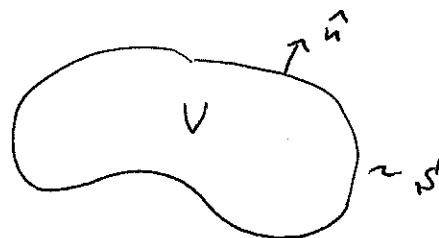
$$T_{EM}^{ij} = -\frac{1}{4\pi} [E^i E^j + B^i B^j - \frac{1}{2} \delta^{ij} (E^2 + B^2)]$$

Def. Maxwell stress tensor $\sigma^{ij} = -T_{EM}^{ij}$.

Momentum conservation:

$$\frac{d}{dt} (P_{\text{field}}^i + P_{\text{mech}}^i) = \oint_V d^3x \nabla^j \sigma^{ij} = \oint_S d\mathbf{q} n^i \sigma^{ij}$$

σ^{ij} ~ momentum flow into
the volume



in general, energy-momentum tensor is

$$T^{\mu\nu} = \left(\begin{array}{c|c} \text{energy density} & \text{momentum density} \\ \hline & c. \\ c. & \text{Maxwell stress} \\ \hline \text{momentum density} & - \text{tensor} \end{array} \right)$$

Energy - Momentum tensor:

we studied: $u \sim \text{energy density}$

$\vec{s} \sim \text{Poynting vector (energy flow)}$

$\sigma_{ij} \sim \text{Maxwell stress tensor (momentum flow)}$

These seemingly unrelated quantities form one tensor under Lorentz transformations, the energy-momentum tensor:

$$T^{\mu\nu} = \begin{pmatrix} u & s^1/c & s^2/c & s^3/c \\ s^1/c & -\sigma_{11} & -\sigma_{12} & -\sigma_{13} \\ s^2/c & -\sigma_{21} & -\sigma_{22} & -\sigma_{23} \\ s^3/c & -\sigma_{31} & -\sigma_{32} & -\sigma_{33} \end{pmatrix}$$

where $\mu, \nu = 0, 1, 2, 3$

On time component: $x^0 = tc, x^1 = x, x^2 = y, x^3 = z$

all the above conservation laws read

$$\boxed{\frac{\partial}{\partial x^\mu} T_{EM}^{\mu\nu} = \frac{1}{c} \delta_\mu^\nu F^{0\nu}} \quad (\text{summation over } \mu)$$

$$T_{\mu}^{\mu} = u + T_i^i = u - u = 0 \sim \text{traceless}$$

$T_{11}, T_{22}, T_{33} \sim \gamma$ radiation pressure components (78)
 $(T_{ij} \text{ is the flux of the } i\text{th component of momentum density in the } \hat{j} \text{ direction})$

Classification of Physical Quantities by

Space-Time Symmetries.

A. Spatial rotations.

$$i, j = 1, 2, 3$$

$$x_i \rightarrow (x'_i = R_{ij} x_j), R_{ij} \text{ - rotation matrix}$$

$$\vec{x}^1 \vec{x}^2 = \vec{x}^2 \text{ under rotation} \Rightarrow (R_{ij} x_j) (R_{ik} x_k) = x_i x_i$$

$$\Rightarrow (R_{ij} R_{ik}) = \delta_{jk} \Rightarrow (R^{-1})_{ij} = R_{ji} \Rightarrow \boxed{RR^T = 1 = RTR}$$

$\det R = +1 \sim \text{rotation w/o reflection}$ ($\det R = -1: \text{not a rotation}$)

$$\text{vectors: } A_i \rightarrow A'_i = R_{ij} A_j$$

$$\text{tensors: } T_{i_1 i_2 \dots i_n} \rightarrow T'_{i_1 i_2 \dots i_n} = R_{i_1 j_1} R_{i_2 j_2} \dots R_{i_n j_n}$$

(definition) $n = \text{rank of the tensor}$ $\cdot T_{j_1 j_2 \dots j_n}$

B. Spatial Reflection (parity)

$$(\vec{x} \rightarrow -\vec{x}) \sim \text{all vectors (or polar vectors)}$$

transform like this; now consider

$$\vec{z} = \vec{x} \times \vec{y} \Rightarrow \left. \begin{array}{l} \vec{x} \rightarrow -\vec{x} \\ \vec{y} \rightarrow -\vec{y} \end{array} \right\} \Rightarrow \vec{z} \rightarrow \vec{z} \quad \begin{array}{l} \text{axial vector} \\ (\text{pseudovector}) \end{array}$$

Inversion is also called parity IP.

IP: vector \rightarrow -vector, axial vector \rightarrow axial vector

$$p = -1$$

$$p = +1$$

Tensor of rank N : IP $T_{i_1 \dots i_N} = (-1)^N T_{i_1 \dots i_N}$

Pseudotensor of rank N : IP $T_{i_1 \dots i_N} = (-1)^{N+1} T_{i_1 \dots i_N}$

[E.g. $\vec{z} = \vec{x} \times \vec{y} \Rightarrow z_i = \epsilon_{ijk} x_j y_k \Rightarrow \epsilon_{ijk}$ has $p = +1$
 $\uparrow \quad \uparrow \quad \uparrow$
 $p = 1 \quad p = -1 \quad p = -1$
 $\Rightarrow p = (-1)^{3+1} = \epsilon_{ijk}$ is pseudotensor.]

pseudoscalar anyone? $\vec{a} \cdot (\vec{b} \times \vec{c})$.

C. Time reversal:

$$t \rightarrow -t$$

$\overline{\mathcal{T}} \vec{x} = \vec{x}, \vec{p} = \frac{d\vec{x}}{dt} \Rightarrow \overline{\mathcal{T}} \vec{p} = -\vec{p}$ ~ T-odd.
 \uparrow T-even.

<u>Quantity</u>	<u>Tensor Rank</u>	<u>Parity</u>	<u>Time Reversal</u>
\vec{x}	vector	-1	1
$\vec{v} = \frac{d\vec{x}}{dt}$	vector	-1	-1
\vec{p}	vector	-1	-1
$\vec{L} = \vec{x} \times \vec{p}$	1	1	-1
$\vec{F} = m\vec{a}$	1	-1	1
$\vec{N} = \vec{x} \times \vec{F}$ (torque)	1	1	1
Energy	0	1	1

<u>Quantity</u>	<u>Tensor Rank</u>	<u>Parity</u>	<u>Time Reversal</u>	(80)
ρ	0	1	1	
$\vec{J} (= \rho \vec{v})$	1	-1	-1	
$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \Rightarrow$				
\vec{E}	1	-1	1	
\vec{B}	1	1	-1	
$\vec{S} = \vec{E} \times \vec{H}$	1	-1	-1	
T_{ij}	2	1	1	