

Magnetostatics

⇒ main difference from electrostatics is due to absence of magnetic monopoles (no equivalent of point charges).

Instead one deals with magnetic dipoles.



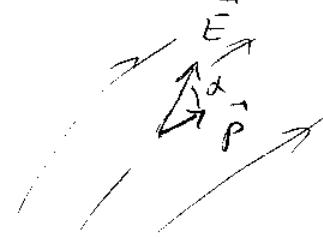
loop of current carries magnetic dipole \vec{m}

Torque on \vec{m} is $\vec{N} = \vec{m} \times \vec{B}$, where

\vec{B} is magnetic induction (aka magnetic flux density)

(Analogy to electric dipoles: if we have dipole \vec{p} in electric field \vec{E} :

$$\begin{aligned} W &= -\vec{p} \cdot \vec{E} = \\ &= -p E \cos \alpha \end{aligned}$$



torque is

$$N = + \frac{\partial W}{\partial \alpha} = p E \sin \alpha \Rightarrow \vec{N} = \vec{p} \times \vec{E}.$$

Continuity: if $\rho(\vec{x}, t)$ is charge density

and $\vec{J}(\vec{x}, t)$ is current density

$$(g = \frac{\text{charge}}{\text{volume}}, J = \frac{\text{charge} \cdot \text{velocity}}{\text{volume}})$$

\Rightarrow the change in total charge in enclosed volume V should be equal to the amount of charge that flowed in/out of the volume. Hence :

$$\Delta Q = \int_V d^3x [\rho(\vec{x}, t+dt) - \rho(\vec{x}, t)] = -\Delta t \oint_S da \cdot J_n$$

$$= -\Delta t \cdot \int_V d^3x \vec{\nabla} \cdot \vec{J}$$

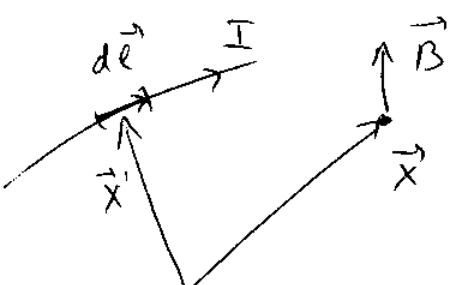
↑ divergence theorem

$$\Rightarrow \text{as } \rho(\vec{x}, t+\Delta t) - \rho(\vec{x}, t) \approx \Delta t \cdot \frac{\partial \rho}{\partial t}(\vec{x}, t)$$

$$\Rightarrow \boxed{\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{J} = 0}$$

in the static case $\frac{\partial \rho}{\partial t} = 0 \Rightarrow \boxed{\vec{\nabla} \cdot \vec{J} = 0}$.

Biot and Savart Law



$$d\vec{B} = \frac{\mu_0}{4\pi} I \frac{d\vec{l} \times (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3}$$

$$\frac{\mu_0}{4\pi} = 10^{-7} \frac{\text{Newtons}}{\text{Ampere}^2} \quad) \quad 1 \text{ Ampere} = 1 \text{ Coulomb} / 1 \text{ Second}$$

(11)

for a point charge q moving with velocity \vec{v} :

$$I d\vec{l} = q \vec{v} \Rightarrow \vec{B} = \frac{\mu_0}{4\pi} q \frac{\vec{v} \times \vec{x}}{x^3}.$$

Transforming current I into current density \vec{J}
via $I d\vec{l} = \vec{J} \cdot d^3x$ we write

$$\vec{B} = \frac{\mu_0}{4\pi} \int d^3x' \frac{\vec{J}(\vec{x}') \times (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3}$$

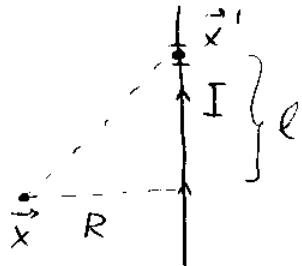
This is magnetic induction due to any current density $\vec{J}(\vec{x})$.

Example: a wire carrying current I :

$$|\vec{B}| = \frac{\mu_0}{4\pi} I \cdot \int_{-\infty}^{\infty} \frac{d\ell}{\ell^2 + R^2} \cdot \frac{R}{\sqrt{R^2 + \ell^2}} =$$

$\underbrace{\quad}_{\sin \text{ of the angle between } d\vec{\ell} \text{ & } (\vec{x} - \vec{x}')}}$

$$= \frac{\mu_0}{4\pi} I R \int_{-\infty}^{\infty} \frac{d\ell}{(\ell^2 + R^2)^{3/2}} = \frac{\mu_0}{2\pi} \frac{I}{R}.$$



Ampere's Law

The force on a current element $I_1 d\vec{l}_1$ due to magnetic field \vec{B} is

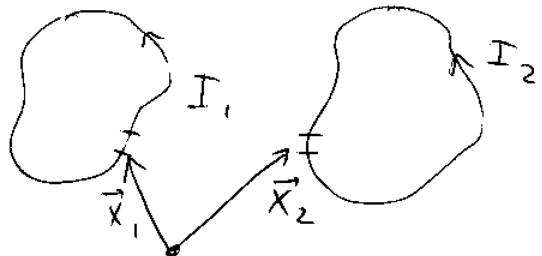
$$d\vec{F} = I_1 d\vec{l}_1 \times \vec{B}$$

For a point charge q moving with velocity \vec{v}

write $\vec{F} = q \vec{v} \times \vec{B}$ (Lorentz force)

Imagine two loops of current: the force on

loop #1 due to loop #2 is



$$\vec{F}_{12} = I_1 \int d\vec{l}_1 \times \vec{B}_2$$

Due to Biot & Savart law, $\vec{B}_2 = \frac{\mu_0}{4\pi} I_2 \int \frac{d\vec{l}_2 \times \vec{x}_{12}}{x_{12}^3}$

where $\vec{x}_{12} = \vec{x}_1 - \vec{x}_2$. Substituting:

$$\vec{F}_{12} = \frac{\mu_0}{4\pi} I_1 I_2 \iint \frac{d\vec{l}_1 \times (d\vec{l}_2 \times \vec{x}_{12})}{x_{12}^3}$$

$$\text{As } \frac{d\vec{l}_1 \times (d\vec{l}_2 \times \vec{x}_{12})}{x_{12}^3} = \frac{d\vec{l}_2 (d\vec{l}_1 \cdot \vec{x}_{12})}{x_{12}^3} - \frac{\vec{x}_{12} \cdot d\vec{l}_1 \cdot d\vec{l}_2}{x_{12}^3}$$

and, since $\vec{\nabla}_1 \frac{1}{|x_{12}|} = -\frac{\vec{x}_{12}}{|x_{12}|^3}$, the first term vanishes

and we write:

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$$\vec{F}_{12} = -\frac{\mu_0}{4\pi} I_1 I_2 \oint \oint \frac{d\vec{l}_1 \cdot d\vec{l}_2}{|\vec{x}_{12}|^3} \vec{x}_{12}$$

attractive
if $I_1 \parallel I_2$
repulsive if
 $I_1 \& I_2$ anti-
-parallel

Ampere's law of force between two current loops.

As $I d\vec{l} = \vec{J} d^3x \Rightarrow$ for two localized

current densities $\vec{F}_{12} = -\frac{\mu_0}{4\pi} \int d^3x_1 d^3x_2 \frac{\vec{J}_1(\vec{x}_1) \cdot \vec{J}_2(\vec{x}_2)}{|\vec{x}_{12}|^3} \vec{x}_{12}$.

For current density Ampere's law gives:

$$\vec{F} = \int d^3x \vec{J}(\vec{x}) \times \vec{B}(\vec{x})$$

The resulting torque is $\vec{N} = \int d^3x \vec{x} \times (\vec{J}(\vec{x}) \times \vec{B}(\vec{x}))$.

Differential Equations of Magnetostatics.

Start with Biot & Savart law.

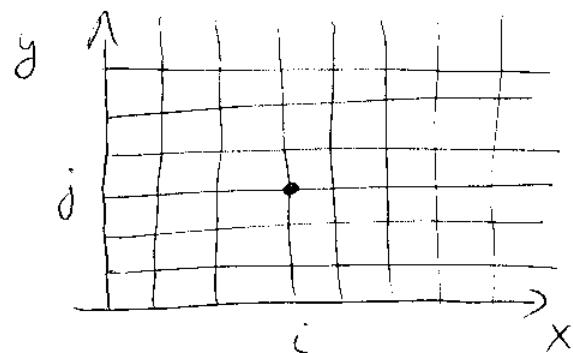
$$\vec{B}(\vec{x}) = \frac{\mu_0}{4\pi} \int d^3x' \frac{\vec{J}(\vec{x}') \times (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3} = -\frac{\mu_0}{4\pi} \int d^3x'$$

$$\vec{J}(\vec{x}') \times \vec{\nabla}_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) = \frac{\mu_0}{4\pi} \vec{\nabla}_x \times \int d^3x' \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|}$$

\Rightarrow we recast \vec{B} as a curl of some vector field.

Numerical Solution of Laplace Equation

Relaxation method



$$\nabla^2 \Phi = \frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} = 0$$

$$\frac{\partial \Phi}{\partial x} \rightarrow \frac{\Phi(i+1, j) - \Phi(i, j)}{\Delta x} \quad \begin{matrix} \leftarrow \text{lattice} \\ \text{spacing} \end{matrix}$$

$$\Phi \rightarrow \Phi(i, j)$$

$$\frac{\partial^2 \Phi}{\partial x^2} = \frac{\Phi(i+1, j) - 2\Phi(i, j) + \Phi(i-1, j)}{\Delta x^2} \quad \left. \begin{matrix} \text{put} \\ \Delta x = \Delta y = a \end{matrix} \right\}$$

$$\frac{\partial^2 \Phi}{\partial y^2} = \frac{\Phi(i, j+1) - 2\Phi(i, j) + \Phi(i, j-1)}{\Delta y^2}$$

$$\Rightarrow \nabla^2 \Phi = \frac{1}{a^2} \left[\Phi(i+1, j) + \Phi(i, j+1) + \Phi(i-1, j) + \Phi(i, j-1) - 4\Phi(i, j) \right] = 0$$

$$\Rightarrow \boxed{\Phi(i, j) = \frac{1}{4} [\Phi(i+1, j) + \Phi(i, j+1) + \Phi(i-1, j) + \Phi(i, j-1)]}$$

Algorithm: (1) Assign random values to Φ on a grid, with Φ on the boundary given by boundary conditions

(2) Average over nearest neighbours until you converge to the answer.

(Improvements: include diagonal neighbours, overrelaxation, etc.)