

Lecture Notes:

Small-x Evolution in DIS (Part II)

Previously:

- Reviewed the high-energy limit: eikonal kinematics + quantum evolution
- Formulated small-x evolution in DIS as a dipole cascade of  $\gamma^*$  wave function in the large- $N_c$  limit.
- Expressed dipole wave-fn. in the Mueller dipole model by a generating functional  $\mathcal{Z}$
- Wrote down evolution eqn. in  $\mathcal{Z}$ ,  $S$ , and  $N$  for small-x evolution.

BK equation:

$$\left[ \frac{\partial}{\partial Y} N(\underline{x}_{01}, \underline{b}, Y) = \frac{\alpha_s C_F}{\pi^2} \int d^2 x_2 \frac{x_{01}^2}{x_{02}^2 x_{21}^2} \left[ N(\underline{x}_{02}, \underline{b} + \frac{1}{2} \underline{x}_{21}, Y) + N(\underline{x}_{12}, \underline{b} + \frac{1}{2} \underline{x}_{20}, Y) - N(\underline{x}_{01}, \underline{b}, Y) - N(\underline{x}_{02}, \underline{b} + \frac{1}{2} \underline{x}_{21}, Y) \cdot N(\underline{x}_{12}, \underline{b} + \frac{1}{2} \underline{x}_{20}, Y) \right] \right]$$

- Neglecting the small differences in impact parameter, this is

$$\left[ \frac{\partial}{\partial Y} N(\underline{x}_{01}, Y) = \frac{\alpha_s N_c}{2\pi^2} \int d^2 x_2 \frac{x_{01}^2}{x_{12}^2 x_{20}^2} \left[ N(\underline{x}_{02}, Y) + N(\underline{x}_{12}, Y) - N(\underline{x}_{01}, Y) - N(\underline{x}_{12}, Y) \cdot N(\underline{x}_{02}, Y) \right] \right]$$

There are 2 fixed points of the BK eqn:

- |                        |                   |          |
|------------------------|-------------------|----------|
| • $N=0 = \text{const}$ | Transparent limit | Unstable |
| • $N=1 = \text{const}$ | Black disk limit  | Stable   |

- To get a feel for BK, consider the atrocious approximation of neglecting all  $x_T$  dependence:

$$\frac{dN(y)}{dy} = \omega(N - N^2) \quad \text{for } \omega > 0$$

- This reduces BK to a (separable) logistic eqn.. The solution is:

$$\frac{dN}{N - N^2} = \frac{-dN}{N(N-1)} = -dN \left( \frac{-1}{N} + \frac{1}{N-1} \right) = \omega dy$$

$$\rightarrow \int_{N_0}^N \left( \frac{1}{N} - \frac{1}{N-1} \right) dN = \int_0^y \omega dy$$

$$\rightarrow \left[ \ln \frac{N}{N-1} \right]_{N_0}^N = \omega y$$

$$\rightarrow \ln \left( \frac{N}{N-1} \cdot \frac{N_0-1}{N_0} \right) = \omega y$$

$$\rightarrow \frac{N}{N-1} = \left( \frac{N_0}{N_0-1} \right) e^{\omega y}$$

$$\rightarrow N \left[ 1 - \frac{N_0}{N_0-1} e^{\omega y} \right] = - \left( \frac{N_0}{N_0-1} \right) e^{\omega y}$$

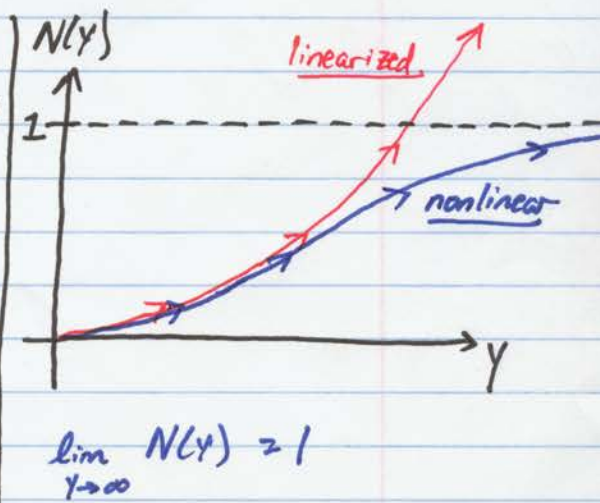
$$\rightarrow \boxed{N(y) = \frac{-N_0 e^{\omega y}}{N_0-1 - N_0 e^{\omega y}} = \frac{N_0 e^{\omega y}}{1 + N_0(e^{\omega y} - 1)}}$$

- If, instead, we had linearized the eqn. by dropping  $N^2$ , we would have

$$\frac{dN}{dy} = \omega N$$

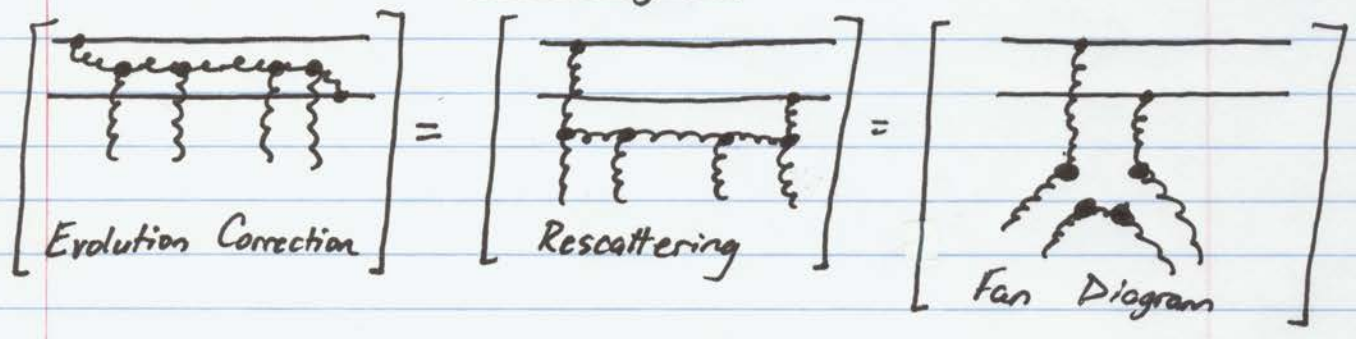
with exponential solution

$$\boxed{N(y) = N_0 e^{\omega y}}$$



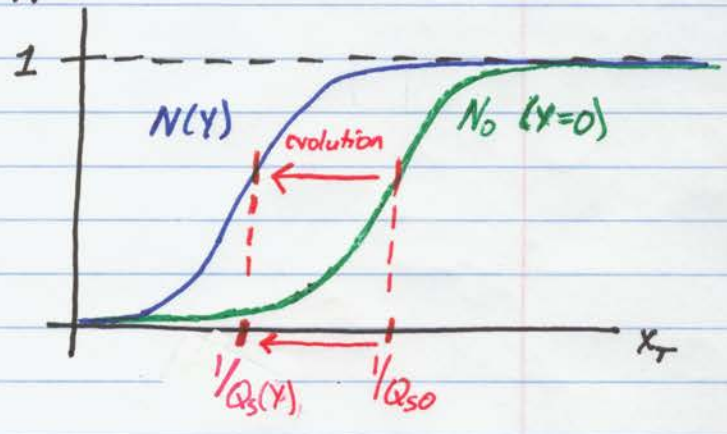
• Even in this oversimplified form, we see that the nonlinear term in the evolution eqn. cuts off the growth of  $N$  with  $Y$  (or  $s$ ) and restores unitarity.

• The nonlinear term corresponds to multiple rescattering in the form of fan diagrams which are resummed:



• The initial condition for BK is given by the quasi-classical Glauber-Mueller expression

$$N_0(x_T) = 1 - \exp\left[-\frac{1}{4} x_T^2 Q_s^2 \ln \frac{1}{x_T \Lambda}\right]$$



• The solution to BK will define a rapidity-dependent saturation scale  $Q_s(Y)$ :

$$N(x_T, Y) \equiv 1 - \exp\left[-\frac{1}{4} x_T^2 Q_s^2(Y) \ln \frac{1}{x_T \Lambda}\right]$$

• BK belongs to a universality class of equations. Many approximations will capture the correct onset of saturation, only changing the details of the "knee".

- There are no known exact solutions to BK, but we can solve for the asymptotic behavior near  $N=0$  and  $N=1$ .

## VII. The Dilute BFKL Limit

- For small dipoles  $x_T \rightarrow 0$ , the scattering amplitude is small,  $N \ll 1$ , so we can linearize the BK eqn. back to the BFKL eqn.

Drop the nonlinear  $N^2$  term:

$$\frac{\partial}{\partial Y} N(x_{01}, Y) = \frac{\alpha_s N_c}{2\pi^2} \int d^2 x_2 \frac{x_{10}^2}{x_{12}^2 x_{20}^2} \left[ N(x_{02}, Y) + N(x_{12}, Y) - N(x_{01}, Y) \right]$$

- As a further simplification, consider integrating out the angular dependence, so that  $N$  depends only on the dipole sizes:

$$\frac{\partial}{\partial Y} N(x_{01}, Y) = \frac{\alpha_s N_c}{2\pi^2} \int d^2 x_2 \frac{x_{10}^2}{x_{12}^2 x_{20}^2} \left[ N(x_{12}, Y) + N(x_{20}, Y) - N(x_{01}, Y) \right]$$

- The BFKL kernel (which is the same as in BK) possesses conformal symmetry. This strongly constrains the form of the eigenfunctions.

- Map the transverse plane to the complex plane:  
 $\rho \equiv x + iy$ ;  $\rho^* \equiv x - iy$
- The kernel is invariant under the conformal Möbius group:  

$$\rho \rightarrow \frac{a\rho + b}{c\rho + d} \quad \text{for all } a, b, c, d \in \mathbb{C}$$
 which includes rotations, translations, reflections,  
 and scale dilations.

- We can use the scaling properties to show that powers of the dipole size are eigenfunctions of the kernel:

$$N_2(x_T, Y) = x_T^\lambda \cdot f_\lambda(Y) \quad \text{for some } \lambda$$

Then

$$\begin{aligned} x_{10}^\lambda f_\lambda'(Y) &= \frac{\alpha_s N_C}{2\pi^2} \int d^2x_2 \frac{x_{10}^2}{x_{12}^2 x_{20}^2} [x_{12}^\lambda + x_{20}^\lambda - x_{10}^\lambda] f_\lambda(Y) \\ &= \frac{\alpha_s N_C}{2\pi^2} (x_{10}^\lambda) f_\lambda(Y) \cdot \int d^2x \frac{x_{10}^2}{x_{12}^2 x_{20}^2} \left[ \left(\frac{x_{12}}{x_{10}}\right)^\lambda + \left(\frac{x_{20}}{x_{10}}\right)^\lambda - 1 \right] \end{aligned}$$

$x_{10}^\lambda$  is an  
eigenfunction

This integral is  $x_{10}$ -independent  
and determines the eigenvalue:  
 $2\pi \cdot \chi(\lambda)$  for  $\lambda = 1 + 2i\nu$

$$x_{10}^{1+2i\nu} f_\lambda'(Y) = \frac{\alpha_s N_C}{2\pi^2} x_{10}^{1+2i\nu} f_\lambda(Y) \cdot 2\pi \chi(0, \nu) \quad \nu = \text{real}$$

where the eigenvalue is

$$\chi(0, \nu) = 2\psi(1) - \psi\left(\frac{1}{2} + i\nu\right) - \psi\left(\frac{1}{2} - i\nu\right) \quad \text{(See plot)} \quad \text{(Real)}$$

where  $\psi(z) \equiv \frac{d}{dz} \ln[\Gamma(z)]$  is the digamma function.

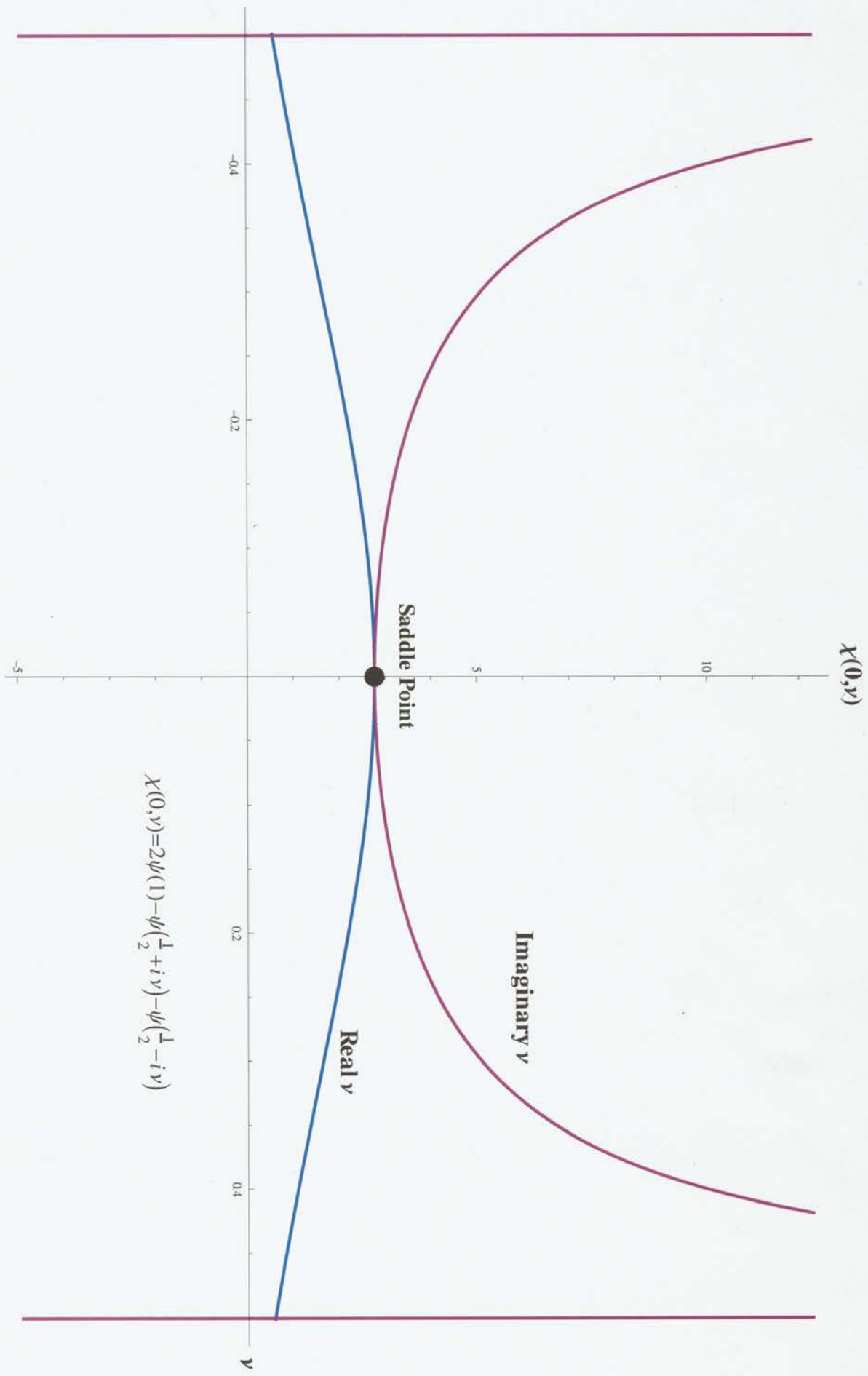
This gives

$$f_\lambda'(Y) = \frac{\alpha_s N_C}{\pi} \chi(0, \nu) f_\lambda(Y)$$

$$\hookrightarrow \underline{f_\lambda(Y) = C_\nu e^{\bar{\alpha}_s \chi(0, \nu) Y}} \quad (\bar{\alpha}_s \equiv \alpha_s N_C / \pi)$$

so the general solution of the BFKL eqn is

$$\begin{aligned} N(x_T, Y) &= \int d\nu C_\nu x_T^{1+2i\nu} e^{\bar{\alpha}_s \chi(0, \nu) Y} \\ &= \int d\nu \tilde{C}_\nu \exp[\bar{\alpha}_s \chi(0, \nu) Y + (1+2i\nu) \ln(x_T \alpha_{s0})] \end{aligned}$$



where the coefficients  $C_r$  are fixed by the initial condition

$$N(x_T, Y=0) = 1 - \exp\left[-\frac{1}{4} x_T^2 Q_{s0}^2\right]$$

See plot of  $\chi$

• We can approximate the behavior at large  $Y$  by using a saddle point expansion.

• The saddle point condition is

$$0 = \frac{d}{d\gamma} [\text{exponent}] = \left[ \bar{\alpha}_s \chi'(0, \gamma_{sp}) Y + 2i \ln(x_T Q_{s0}) \right] = 0$$

$$\gamma_{sp}^* \approx \frac{i \ln(x_T Q_{s0})}{14 \zeta(3) \bar{\alpha}_s Y}$$

which fixes the saddle point  $\gamma_{sp}$  near 0. Use the zero<sup>th</sup> order approximation of the  $dY$ -integral ( $\gamma = \gamma_{sp}$ ) to estimate

$$N(x_T, Y) \sim \exp\left[ \bar{\alpha}_s \chi(0, \gamma_{sp}) Y + (1 + 2i\gamma_{sp}) \ln(x_T Q_{s0}) \right] \approx 4 \ln 2$$

• Let's use these  $N \rightarrow 0$  asymptotics to estimate the transition to  $N \sim O(1)$  when the linear BFKL evolution breaks down:

$$N \sim O(1) \text{ when } \left[ \bar{\alpha}_s \chi(0, \gamma_{sp}) Y + (1 + 2i\gamma_{sp}) \ln(x_T Q_{s0}) \right] \approx 0$$

• Use this to define the rapidity-dependent saturation scale  $x_T = 1/Q_s(Y)$ :

- (1)  $\bar{\alpha}_s \chi'(0, \gamma_0) Y + 2i \ln Q_{s0}/Q_s(Y) = 0$
- (2)  $\bar{\alpha}_s \chi(0, \gamma_0) Y + (1 + 2i\gamma_0) \ln Q_{s0}/Q_s(Y) = 0$

where  $\gamma_0 = \gamma_{sp}$  at  $x_T = 1/Q_s(Y)$

• Dividing (1) and (2) gives

$$\frac{\chi'(0, \gamma_0)}{\chi(0, \gamma_0)} = \frac{Z_i}{1 + 2i\gamma_0}$$

and solving (1) for  $Q_s(Y)$  gives

$$\boxed{Q_s(Y) = Q_{s0} \exp\left[\bar{\alpha}_s Y \frac{\chi'(0, \gamma_0)}{Z_i}\right]} \\ = Q_{s0} \exp\left[\bar{\alpha}_s Y \frac{\chi(0, \gamma_0)}{1 + 2i\gamma_0}\right]$$

for  $\gamma_0 \approx 0$ ,  $\chi(0, 0) = 4 \ln 2$

$$\boxed{Q_s(Y) \approx Q_{s0} e^{2.77 \bar{\alpha}_s Y}}$$

This gives an estimate of the saturation scale that grows as  $e^Y$  or, equivalently, a power of  $s$ .

• Additionally, if we plug this back into the forward amplitude by writing

$$e^{\bar{\alpha}_s Y} = \left[Q_s(Y)/Q_{s0}\right]^{\frac{1+2i\gamma_0}{\chi(0, \gamma_0)}}$$

$$\Rightarrow N(x_T, Y) \sim (x_T Q_{s0})^{1+2i\gamma_{sp}} \left[e^{\bar{\alpha}_s Y}\right]^{\chi(0, \gamma_{sp})}$$

$$\sim (x_T Q_{s0})^{1+2i\gamma_{sp}} \left[\frac{Q_s(Y)}{Q_{s0}}\right]^{(1+2i\gamma_0) \frac{\chi(0, \gamma_{sp})}{\chi(0, \gamma_0)}}$$

IP  $x_T \ll 1/Q_s(Y)$ , then  $\gamma_0 \neq \gamma_{sp}$ . But if  $x_T \approx 1/Q_s(Y)$ , then  $\gamma_0 \approx \gamma_{sp}$ , and

$$\boxed{N(x_T, Y) \sim [x_T Q_s(Y)]^{1+2i\gamma_0}}$$

The amplitude is a function of a single scaling variable

$$\tau = x_T Q_s(Y) \quad \text{or} \quad \tau^{-1} \sim k_T / Q_s(Y)$$

which is a signature that the physics is dominated by a single scale  $Q_s(Y)$ . Remarkably, this is still true even outside of the saturation scale.



- This phenomenon is valid outside of the saturation regime and is known as extended geometric scaling.
- We can estimate where this breaks down by where the transition to the "double-logarithmic approximation" ( $\alpha_s Y \ln(x_T Q_{s0}) \sim 1$ ) occurs:

$$k_{geom} \approx Q_{s0} e^{5.75 \alpha_s Y} = Q_s(Y) \cdot \left[ \frac{Q_s(Y)}{Q_{s0}} \right]^{1.35}$$

- Thus there is a parametrically broad regime outside of saturation where the signature of saturation is still present:  $[Q_s(Y) \leq k_T \leq k_{geom}(Y)]$

### VIII. The Deep Saturation Limit

In the  $N \rightarrow 1$  asymptotic limit  $S \equiv 1 - N$  becomes small,  $S \ll 1$ , and we can perform a different linearization of the BK eqn: (near Black Disk Limit)

$$\frac{\partial}{\partial Y} [1 - S(x_{10}, Y)] = \frac{\alpha_s N_c}{2\pi^2} \int d^2 x_2 \frac{x_{10}^2}{x_{12}^2 x_{20}^2} \left[ \cancel{(1 - S(x_{12}, Y))} + \cancel{(1 - S(x_{20}, Y))} - \underbrace{(1 - S(x_{10}, Y)) - (1 - S(x_{12}, Y))(1 - S(x_{20}, Y))}_{1 - S(x_{12}, Y) - S(x_{20}, Y)} \right]$$

$$\rightarrow \frac{\partial}{\partial Y} S(x_{10}, Y) = -\frac{\alpha_s N_c}{2\pi^2} \int d^2 x_2 \frac{x_{10}^2}{x_{12}^2 x_{20}^2} S(x_{10}, Y)$$

where the integral uses a  $Y$ -dependent cutoff  $x_T \geq 1/Q_s(Y)$  in the UV.

$$\int_{x_T \rightarrow y_{Q_0}(Y)} d^2 x_2 \frac{x_{10}^2}{x_{12}^2 x_{20}^2} = 4\pi \ln[x_{01} Q_S(Y)] \quad , \text{ so}$$

$$\frac{\partial}{\partial Y} S(x_{01}, Y) = -2 \frac{a_S N_c}{\pi} \ln[x_{01} Q_S(Y)] \cdot S(x_{01}, Y)$$

• Define the scaling variable

$$\boxed{\xi \equiv \ln[x_T^2 Q_S^2(Y)]}$$

so that

$$\frac{\partial \xi}{\partial Y} = 2 \frac{\partial}{\partial Y} \ln Q_S(Y) = 2 \frac{\partial}{\partial Y} \left[ \bar{a}_S Y \frac{\chi(0, \gamma_0)}{1+2i\gamma_0} \right] = 2 \bar{a}_S \frac{\chi(0, \gamma_0)}{1+2i\gamma_0}$$

and

$$\begin{aligned} \frac{\partial}{\partial \xi} S(x_{01}, \xi) &= \frac{\partial S}{\partial Y} \frac{\partial Y}{\partial \xi} \\ &= \left[ -2 \bar{a}_S \cdot \frac{\xi}{2} S(x_{01}, \xi) \right] \left[ \frac{1+2i\gamma_0}{2 \bar{a}_S \chi(0, \gamma_0)} \right] \end{aligned}$$

$$\frac{\partial}{\partial \xi} S(x_{01}, \xi) = - \frac{1+2i\gamma_0}{2 \chi(0, \gamma_0)} \xi \cdot S(x_{01}, \xi)$$

which can be simply solved

$$\int_S^s \frac{dS}{S} = - \left( \frac{1+2i\gamma_0}{2 \chi(0, \gamma_0)} \right) \int_{\xi=0}^{\xi} d\xi \cdot \xi$$

to give

$$\boxed{S = S_0 \exp \left[ - \frac{1}{2} \left( \frac{1+2i\gamma_0}{2 \chi(0, \gamma_0)} \right) \xi^2 \right]}$$

or

$$N(x_T, Y) = 1 - \exp \left[ -\frac{1}{2} \left( \frac{1 + 2x_T}{27(1+x_T)} \right) \ln^2(x_T^2 Q_s^2(Y)) \right]$$

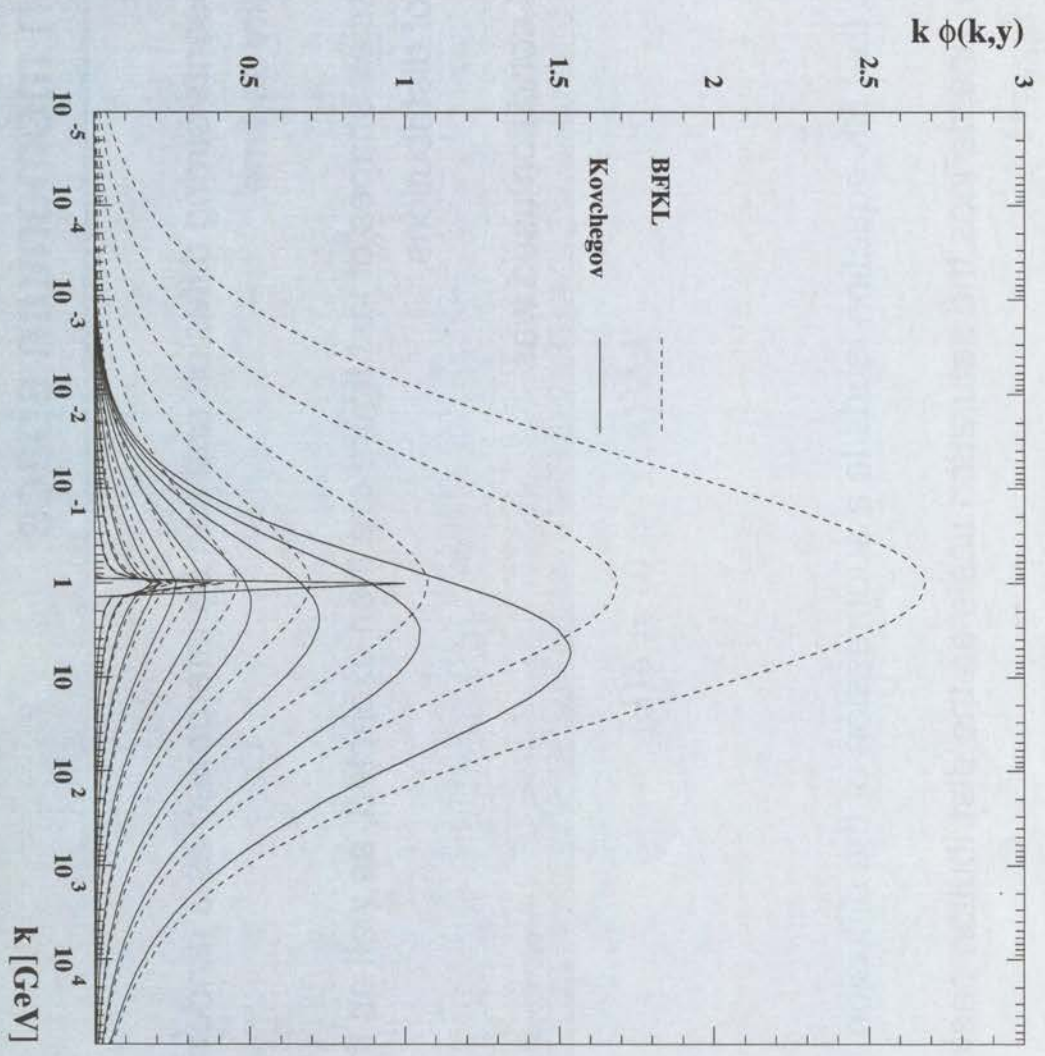
- Again,  $N$  is a function of a scaling variable  $\xi$  (or  $\tau = x_T Q_s(Y)$ ), which is a sign that the physics is dominated by a single scale  $Q_s(Y)$ .
- This feature is known as "geometric scaling".

Because of the universality, many solution strategies will work, differing only in the functional form of the "knee."

#### IX. Phenomenology

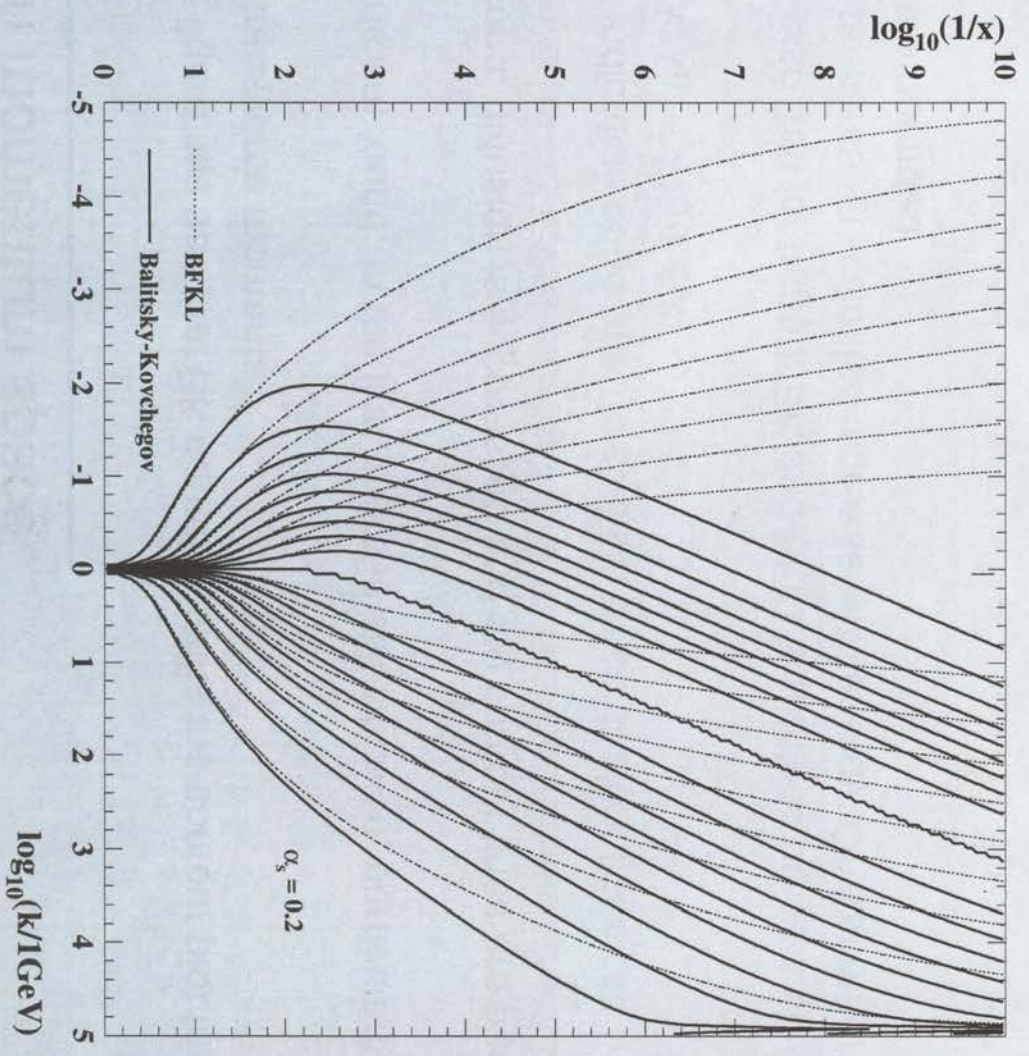
- Numerical solution of the BK eqn verifies all these features:
  - Unitarization:  $N \rightarrow 1$  as  $Y \rightarrow \infty$  due to multiple rescattering
  - Geometric scaling seen in data at HERA
  - Cuts off diffusion into the IR, ensuring the validity of perturbation theory.
- The current "state of the art" tool for fitting experimental data is the BK eqn with running coupling corrections. This numerical "rcBK" solution matches data very well.

# BK equation in momentum space



- Peak  $\sim Q_s(y)$  grows with  $Y$  in BK.
- Compared to BFKL, BK cuts off the diffusion of gluons into the IR.

# BK equation in momentum space

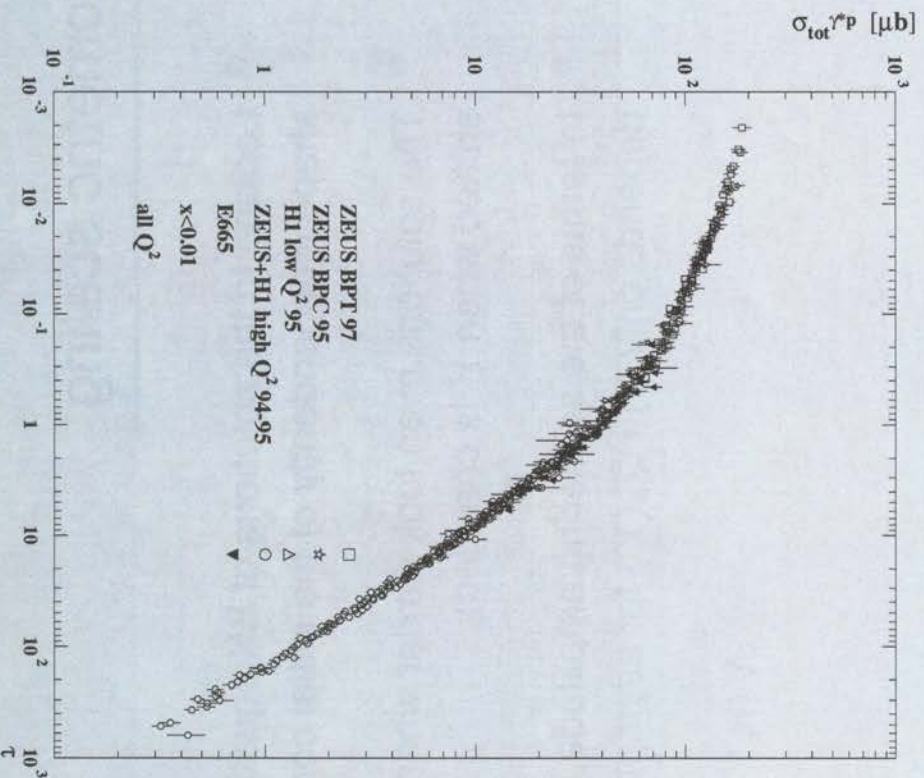


- BK moves into UV with increasing  $Y$ .
- Eliminates spread (diffusion) from BFKL, which would have drifted into the IR.



# Geometric scaling

- *Geometric scaling* is a phenomenological feature of DIS which has been observed in the HERA data on inclusive  $\gamma^* - p$  scattering, which is expressed as a scaling property of the virtual photon-proton cross section

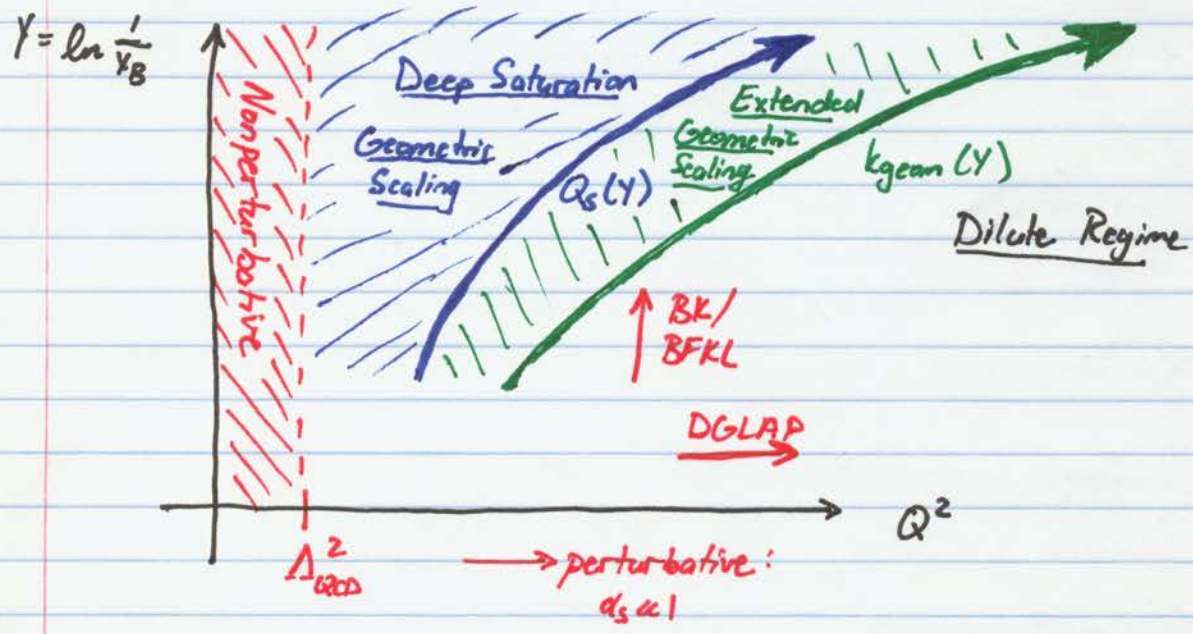


$$\sigma^{\gamma^*p}(Y, Q) = \sigma^{\gamma^*p}(\tau), \quad \tau = \frac{Q^2}{Q_s^2(Y)}$$

where  $Q$  is the virtuality of the photon,  
 $Y = \log 1/x$  is the total rapidity and  
 $Q_s(Y)$  is the saturation scale

[Stasto, Golec Biernat and Kwiecinsky,  
2001]

# Map of High Energy QCD:



- The BK eqn. corresponds to treating the nonlinear evolution by a mean-field approximation. While valid for a heavy nucleus, it is an approximation for a finite target.
- To go beyond BK, we need to include fluctuations and treat the whole  $n$ -gluon hierarchy without the large- $N_c$  limit. This gives rise to a similar but more difficult evolution equation: the
 

Sofilian-Marian	}	JIMWLK or "Jim Walk"
Iancu		
McLerran		
Weigert		
Leonidov		
Korner		

 equation, which will be discussed next.