R-L-C AC Circuits

What does AC stand for?

• AC stands for "Alternating Current". Most of the time however, we are interested in the voltage at a point in the circuit, so we'll concentrate on voltages here rather than currents. We encounter AC circuits whenever a periodic voltage is applied to a circuit. The most common periodic voltage is in the form of a sine (or cosine) wave: $V(t) = V_0 \cos \omega t$ or $V(t) = V_0 \sin \omega t$



In this notation V_0 is the *amplitude*: $V_0 = \text{Peak Voltage}(V_P)$

 $V_0 = 1/2$ Peak-to-Peak Voltage (V_{PP})

 $V_0 = \sqrt{2} \ V_{RMS} = 1.41 \ V_{RMS}$

Note: V_{PP} is easiest to read off scope. V_{RMS} is usually what multimeters read.

In this notation ω is the *angular frequency:* $\omega = 2\pi f$, with f = frequency of the waveform. The frequency (f) and period (T) are related by: T (sec) = 1/f (sec⁻¹) *Household line voltage* is usually 110-120 V_{RMS} (156-170 V_P), f = 60 Hz.

It is extremely important to be able to analyze circuits (systems) with sine or cosine inputs since (almost) any waveform can be constructed from a sum of sines and cosines. This is the "heart" of *Fourier analysis* (Simpson, Chapter 3). The response of a circuit to a complicated waveform (e.g. a square wave) can be understood by analyzing each of the individual sine or cosine components that make up the complicated waveform. Usually only a few of these components are important in determining the circuit's response to the input waveform.

R-C Circuits and AC waveforms

• There are many different techniques for solving AC circuits, all of them are based on Kirchhoff's laws. When we solve for the voltage and/or current in an AC circuit we are really solving a differential equation. The different circuit techniques are really just different ways of solving the same differential equation.

- brute force solution to differential equation
- complex numbers (algebra)
- Laplace transforms (integrals)

• We will solve the following RC circuit using the brute force method and complex numbers method.

Let the input (driving) voltage be $V(t) = V_0 \cos \omega t$ and we want to find $V_R(t)$ and $V_C(t)$.



Brute Force Method: Start with Kirchhoff's loop law: $V(t) = V_R(t) + V_C(t)$

$$V_0 \cos \omega t = IR + Q / C$$

= $RdQ(t) / dt + Q(t) / C$

We have to solve an inhomogeneous D.E. The usual way to solve such a D.E. is to assume the solution has the same form as the input:

 $Q(t) = \alpha \sin \omega t + \beta \cos \omega t$

Plug our trial solution Q(t) back into the differential equation: $V_0 \cos \omega t = \alpha R \omega \cos \omega t - \beta R \omega \sin \omega t + (\alpha / C) \sin \omega t + (\beta / C) \cos \omega t$

 $= (\alpha R\omega + \beta / C) \cos \omega t + (\alpha / C - \beta R\omega) \sin \omega t$ $V_0 = \alpha R\omega + \beta / C$ $\alpha / C = \beta R\omega$ $\alpha = \frac{RC^2 \omega V_0}{1 + (RC\omega)^2}$ $\beta = \frac{CV_0}{1 + (RC\omega)^2}$ We can now write the solution for $V_C(t)$: $V_C(t) = Q / C$ $= (\alpha \sin \omega t + \beta \cos \omega t) / C$ $= \frac{RC\omega V_0}{1 + (RC\omega)^2} \sin \omega t + \frac{V_0}{1 + (RC\omega)^2} \cos \omega t$

We would like to rewrite the above solution in such a way that only a cosine term appears. In this form we can compare it to the input voltage. From the previous page we have:

$$V_C(t) = \frac{RC\omega V_0}{1 + (RC\omega)^2} \sin \omega t + \frac{V_0}{1 + (RC\omega)^2} \cos \omega t$$
$$= \frac{V_0}{\sqrt{1 + (RC\omega)^2}} \left[\frac{RC\omega}{\sqrt{1 + (RC\omega)^2}} \sin \omega t + \frac{1}{\sqrt{1 + (RC\omega)^2}} \cos \omega t \right]$$

We get the above equation in terms of cosine only using the following dirty trick from basic trig:

 $\cos(\theta_1 - \theta_2) = \sin \theta_1 \sin \theta_2 + \cos \theta_1 \cos \theta_2$

We can now define an angle such that:

$$\cos\phi = \frac{1}{\sqrt{1 + (RC\omega)^2}}, \quad \sin\phi = \frac{RC\omega}{\sqrt{1 + (RC\omega)^2}}, \quad \tan\phi = RC\omega$$

Finally (!) we can write the desired expression for $V_C(t)$:

$$V_C(t) = \frac{V_0}{\sqrt{1 + (RC\omega)^2}} \cos(\omega t - \phi)$$

From the above expression we see that $V_C(t)$ and $V_0(t)$ are out of phase.

Using the above expression for $V_C(t)$, we obtain:

$$\begin{split} V_R(t) &= IR \\ &= R \frac{dQ}{dt} \\ &= RC \frac{dV_C}{dt} \\ &= \frac{-RC\omega V_o}{\sqrt{1+(RC\omega)^2}} \sin(\omega t - \phi) \end{split}$$

Again, we would like to have cosines instead of sines. We do this using:

 $-\sin\theta = \cos(\theta + \pi/2)$

Finally (!!) we have:

$$V_R(t) = \frac{RC\,\omega V_o}{\sqrt{1 + (RC\omega)^2}} \cos(\omega t - \phi + \frac{\pi}{2})$$

• Some things to note:

 $V_C(t)$, $V_R(t)$, and I(t) are all out of phase with the applied voltage.

I(t) and $V_R(t)$ are in phase with each other.

 $V_C(t)$ and $V_R(t)$ are out of phase by 90⁰.

The amplitude of $V_C(t)$ and $V_R(t)$ depend on ω .

Example: RC Circuit



Solving circuits with complex numbers:

PROS: don't explicitly solve differential equations (lots of algebra). can find magnitude and phase of voltage separately.CONS: have to use complex numbers! No "physics" in complex numbers.

• What's a complex number? (see Simpson, Appendix E, P835)

Start with $j = \sqrt{-1}$ (solution to $x^2 + 1 = 0$). A complex number can be written in two forms: X = A + jB, with A and B real numbers or $X = R e^{j\phi}$, with $R = (A^2 + B^2)^{1/2}$, and $\tan \phi = B / A$ (remember $e^{j\phi} = \cos \phi + j \sin \phi$) Define the complex conjugate of *X* as:

 $X^* = A - jB \quad \text{or} \quad X^* = R \ e^{-j\phi}$

The magnitude of *X* can be found from:

 $|X| = (XX^*)^{1/2} = (X^*X)^{1/2} = (A^2 + B^2)^{1/2}$

Suppose we have 2 complex numbers, X and Y with phases α and β respectively,

$$Z = \frac{X}{Y} = \frac{|X|e^{j\alpha}}{|Y|e^{j\beta}} = \frac{|X|}{|Y|}e^{j(\alpha-\beta)}$$

The magnitude of Z is just |X|/|Y|, while the phase of Z is $\alpha - \beta$.

• So why is this useful?

Consider the case of the capacitor and AC voltage:

$$V(t) = V_0 \cos \omega t$$

$$= \operatorname{Re} \operatorname{al} \left(V_0 e^{j\omega t} \right)$$

$$I(t) = C \frac{dV}{dt}$$

$$= -C\omega V_0 \sin \omega t$$

$$= \operatorname{Re} \operatorname{al} \left(j\omega C V_0 e^{j\omega t} \right)$$

$$= \operatorname{Re} \operatorname{al} \left(\frac{V_0 e^{j\omega t}}{1/j\omega C} \right)$$

$$= \operatorname{Re} \operatorname{al} \left(\frac{V}{X_C} \right) \qquad \text{with } V \operatorname{and} X_C \operatorname{complex}$$

We now have Ohm's law for capacitors using the capacitive reactance X_C .

$$X_C = \frac{1}{j\omega C}$$

We can make a similar case for the inductor (V = LdI / dt):

$$I(t) = \frac{1}{L} \int V_0 \cos \omega t \, dt$$

= $\frac{V_0 \sin \omega t}{L \omega}$
= $\operatorname{Re} \operatorname{al}\left(\frac{V_0 e^{j\omega t}}{j\omega L}\right)$
= $\operatorname{Re} \operatorname{al}\left(\frac{V}{X_L}\right)$ with V and X_L complex

We now have Ohm's law for inductors using the inductive reactance X_L :

 $X_L = j\omega L$

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• X_C and X_L act like frequency dependent resistors. However they also have a *phase* associated with them due to their complex nature.

 $\begin{array}{ll} X_L \Rightarrow 0 & \text{as } \omega \Rightarrow 0 & (\text{short circuit, DC}) \\ X_L \Rightarrow \infty & \text{as } \omega \Rightarrow \infty & (\text{open circuit}) \\ X_C \Rightarrow 0 & \text{as } \omega \Rightarrow \infty & (\text{short circuit}) \\ X_C \Rightarrow \infty & \text{as } \omega \Rightarrow 0 & (\text{open circuit, DC}) \end{array}$

• Back to the RC circuit. Allow voltages, currents, and charge to be complex $V_{in} = V_0 \cos \omega t$

= Re al
$$(V_0 e^{j\omega t})$$

= Re al $(V_R + V_C)$

= Re al $(V_R + V_C)$ We can write an expression for the charge (Q) taking into account the phase difference (ϕ) between applied voltage and the voltage across the capacitor (V_C) .

$$Q(t) = CV_C(t)$$

=
$$Ae^{j(\omega t - \phi)}$$

where Q and V_C are complex, A and C real.

We can find the complex current by differentiating the above:

$$I(t) = dQ(t) / dt$$

$$= j\omega A e^{j(\omega t - \phi)}$$

$$= j\omega Q(t)$$

$$= j\omega C V_C(t)$$

$$V_{in} = V_C + V_R$$

$$= V_C + IR$$

$$= V_C + j\omega C V_C R$$

$$V_C = \frac{V_{in}}{1 + j\omega R C}$$

$$= V_{in} \frac{\frac{1}{j\omega C}}{R + \frac{1}{j\omega C}}$$

$$= V_{in} \frac{X_C}{R + X_C}$$

The above looks like a voltage divider equation!!!!!

We can easily find the magnitude of V_C

$$|V_C| = \frac{|V_{in}||X_C|}{|R + X_C|}$$
$$= \frac{V_0 \frac{1}{\omega C}}{\sqrt{R^2 + (1/\omega C)^2}}$$
$$= \frac{V_0}{\sqrt{1 + (RC\omega)^2}}$$

which is the same as the result on page 3.

Is this solution the same as what we had when we solved by brute force?

$$V_{C} = \operatorname{Real}\left(\frac{V_{in}}{1+j\omega RC}\right)$$
$$= \operatorname{Real}\left(\frac{V_{0}e^{j\omega t}}{1+j\omega RC}\right)$$
$$= \operatorname{Real}\left(\frac{V_{0}e^{j\omega t}}{\sqrt{1+(\omega RC)^{2}}e^{j\phi t}}\right)$$

where ϕ is given by $\tan \phi = \omega RC$.

$$V_{C} = \operatorname{Real}\left(\frac{V_{0}e^{j(\omega t - \phi)}}{\sqrt{1 + (\omega RC)^{2}}}\right)$$
$$= \frac{V_{0}\cos(\omega t - \phi)}{\sqrt{1 + (\omega RC)^{2}}}$$

YES the solutions are identical.

• We can now solve for the voltage across the resistor.

Start with the voltage divider equation in complex form:

$$V_{R} = \frac{V_{in}R}{R + X_{C}}$$
$$|V_{R}| = \frac{|V_{in}|R}{|R + X_{C}|}$$
$$= \frac{V_{0}R}{\sqrt{R^{2} + (1/\omega C)^{2}}}$$
$$= \frac{V_{0}\omega RC}{\sqrt{1 + (\omega RC)^{2}}}$$

This amplitude is the same as the brute force differential equation case!

• Important note:

When we add complex voltages together we must take into account the phase difference between them. Thus, the sum of the voltages at a given time satisfy:

$$V_0^2 = |V_R|^2 + |V_C|^2$$
 and **not** $V_0 = |V_R| + |V_C|$

R-C Filters

• Filters:

Allow us to select (reject) wanted (unwanted) signals on the basis of their frequency structure.

Allow us to change the phase of the voltage or current in a circuit.

Define the gain (G) or transfer (H) function of a circuit:

 $G(j\omega) = H(j\omega) = V_{out} / V_{in}$ (j ω is often denoted by s).

G is independent of time, but can depend on ω , R, L, C.

For an RC circuit we can define G_R and G_C :

We can categorize the G's as follows:

	G_R	G_C
High Frequencies	\approx 1, no phase shift	$\approx 1/j\omega CR \approx 0$, phase shift
	high pass filter	
Low Frequencies	$\approx j\omega CR \approx 0$, phase shift	\approx 1, no phase shift
		low pass filter





• Decibels and Bode Plots:

Decibel (dB) describes voltage or power gain: $dB = 20 \log(V_{out} / V_{in})$

$$=10 \log(P_{out}/P_{in})$$

Bode Plot is a log-log plot with dB on the Y axis and $log(\omega)$ or log(f) on the X axis.

• 3 dB point or 3 dB frequency: (also called break frequency, corner frequency, 1/2 power point) At the 3 dB point:

$$\frac{V_{out}}{V_{in}} = \frac{1}{\sqrt{2}} \quad \text{since } 3 = 20 \log(V_{out} / V_{in})$$
$$\frac{P_{out}}{P_{in}} = \frac{1}{2} \quad \text{since } 3 = 10 \log(P_{out} / P_{in})$$
$$\omega RC = 1 \text{ for high or low pass filter}$$