

Joint Distributions -Two or More RVs

Section 5.1

- So far we discussed only a single RV
- In real (useful) experiments, we usually collect information on two or more quantities simultaneously
 - Pressure, Volume, Temperature
 - Service Times, # of A/C units
 - # of cars and # of trucks on a Hwy
 - fuel consumption and average speed traveled
 - height and weight
 - time until failure of two different components
- We need to be familiar with probabilistic modeling of two or more RV's
 - Prediction of one variable given the values of the other(s)

Joint Distribution for Discrete RV's

Def: The joint pmf of X and Y is a function $p(x, y)$ or $p_{XY}(x, y)$ satisfying:

$$p(x, y) = P(X = x, Y = y)$$

Genuine joint pmf:

Let A be a set of (x,y) pairs. Find the $P(A)$:

e.g. $A = \{(x,y): x + y = 5\}$ or $A = \{(x,y): x \geq 3, y \leq 4\}$

Example 5.1

X = auto policy deductible

Y = homeowner's policy deductible

...for a randomly selected person in an insurance pool

Joint Probability Table

$p(x, y)$		y		
		0	100	200
x	100	0.20	0.10	0.20
	250	0.05	0.15	0.30

Marginal Distributions

The **marginal pmf's** of X and Y, denoted by $p_X(x)$ and $p_Y(y)$ are

$$p_X(x) = \sum_y p(x, y) \quad \text{and} \quad p_Y(y) = \sum_x p(x, y)$$

$p(x, y)$		y		
		0	100	200
x	100	0.20	0.10	0.20
	250	0.05	0.15	0.30

Example -Transportation

- The joint probability distribution (pmf) of the number of cars, X , and the number of buses, Y , per signal cycle at a proposed left turn lane (as a two way table)

		# buses			
		y			
# cars	p(x,y)	0	1	2	Col. Sum
	0	.025	.015	.01	.05
	1	.050	.030	.02	.10
x	2	.125	.075	.05	.25
	3	.150	.090	.06	.30
	4	.100	.060	.04	.20
	5	.050	.030	.02	.10
	Row Sum	.5	.3	.2	1.00

Transportation Example - Continued

a. Probabilities of some events of interest:

$$P(\text{exactly one car and one bus during a signal cycle}) = p(1,1) =$$

$$P(\text{at most two cars and at most one bus}) = P(X \leq 2, Y \leq 1) = F(2,1) =$$

$$P(\text{fewer than two cars and at most one bus}) = P(X < 2, Y \leq 1) = F(1,1) =$$

$$P(\text{one car}) = p_x(1) =$$

$$P(\text{no bus}) = p_y(0) =$$

Event of interest- Functions of two variables

Suppose that the left turn lane is designed for a capacity of five cars.

Assume that one bus takes the space equivalent to that of three cars. Find the probability of an overflow during a signal cycle.

Transportation Example - Continued

b. **Marginal distributions.**
Marginal pmf of X:

Marginal pmf of Y:

c. **Independence:** Are X and Y independent random variables?

Note: Given only the marginal distributions, we can't find the joint distribution, unless we are told that X and Y are independent random variables.

d. **WARNING:** Small perturbations in joint probability, while keeping the same marginal distributions, can lead to the two variables being not independent.

Two Continuous RV's

Let X and Y be continuous RV's. A **joint pdf** $f(x,y)$ for these two random variables is a function satisfying:

$$f(x, y) \geq 0 \quad \text{and} \quad \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \, dx \, dy = 1$$

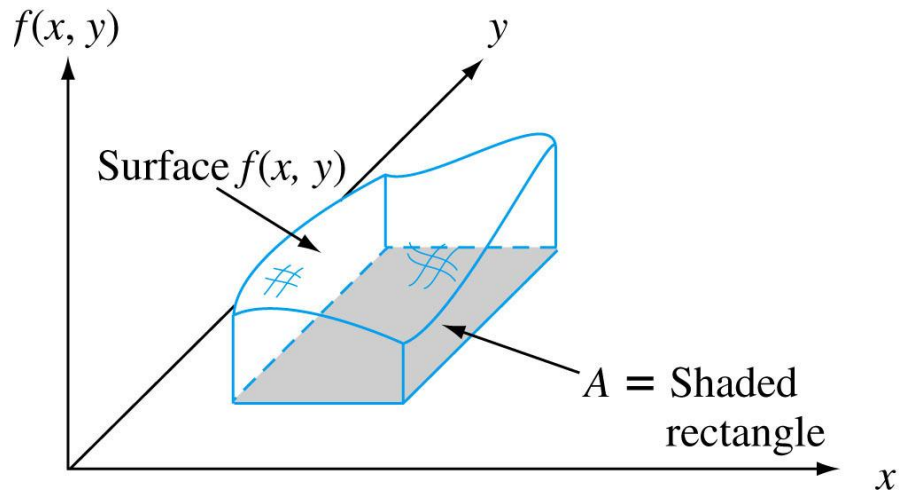
Let A be a region in two-dimensions:

Eg: A = rectangle = $\{(x,y): a \leq x \leq b, c \leq y \leq d\}$

CAUTION: This is NOT the area of the rectangle....

So, what is it?

Geometry



© 2007 Thomson Higher Education

Marginal Distributions

$$f_X(x) = \int_{-\infty}^{\infty} f(x, y) dy$$

$$f_Y(y) = \int_{-\infty}^{\infty} f(x, y) dx$$

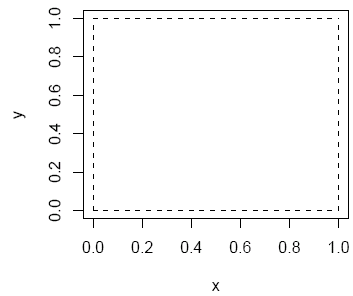
Example 5.3

Let X and Y have the joint density:

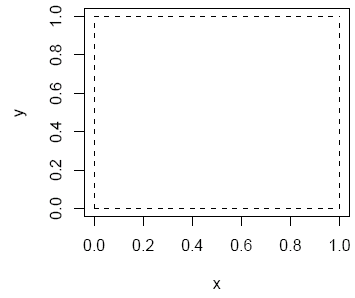
$$f_{XY}(x, y) = \begin{cases} k(x+y)^2 & 0 \leq x \leq 1, \quad 0 \leq y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

a) Find k

b) Find $P(X > Y)$ by first identifying the region of integration and then performing the integral



c) Find $P(|X - Y| \leq 0.5)$ by first identifying the region of integration



d) Find the marginal distribution of X: $f_x(x)$

e) Marginal distribution of Y:

Jointly Distributed Random Variables

Section 5.1 cont.

Two Discrete RV's

pmf

$$p(x, y) = P(X = x, Y = y)$$

Two Continuous RV's

pdf

$$f(x, y)$$

computing probabilities

$$P((X, Y) \in A) = \sum_{(x, y) \in A} p(x, y) \quad P((X, Y) \in A) = \int \int_A f(x, y) dx dy$$

marginal distributions

$$p_X(x) = \sum_y p(x, y)$$

$$f_X(x) = \int_{-\infty}^{\infty} f(x, y) dy$$

$$p_Y(y) = \sum_x p(x, y)$$

$$f_Y(y) = \int_{-\infty}^{\infty} f(x, y) dx$$

Independence of Two Random Variables

Recall: Two events E_1 and E_2 are said to be *independent* if

$$P(E_1 \cap E_2) = P(E_1) \cdot P(E_2)$$

Otherwise, they are *dependent*.

Interpretation: Knowing whether E_1 has occurred does not tell us anything about whether E_2 has occurred, i.e., $P(E_1 | E_2) = P(E_1)$

Two discrete RV's are said to be *independent* if

$$p(x, y) = p_X(x) \cdot p_Y(y)$$

Example

X = auto policy deductible

Y = homeowner's policy deductible

Joint Probability Table

		y		
		0	100	200
$p(x, y)$	100	0.20	0.10	0.20
	250	0.05	0.15	0.30

x	100	250	y	0	100	250
$p(x)$	0.5	0.5	$p(y)$	0.25	0.25	0.5

Two Continuous Random Variables

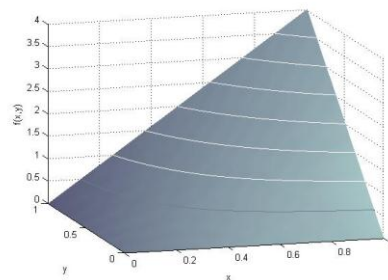
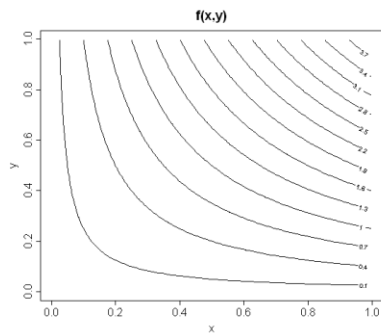
Two continuous RV's are said to be *independent* if

$$f(x, y) = f_X(x) \cdot f_Y(y)$$

Consequence of Independence:

Example

$$f(x, y) = 4xy \quad \begin{array}{l} 0 \leq x \leq 1 \\ 0 \leq y \leq 1 \end{array}$$



Example

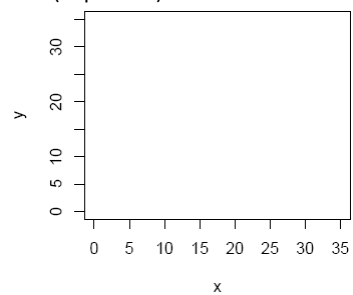
$$f(x, y) = 4xy \quad \begin{array}{l} 0 \leq x \leq 1 \\ 0 \leq y \leq 1 \end{array}$$

Marginal Distributions:

Another Example

A health-food store stocks two different brands of a certain type of grain. Let X = the amount (in pounds) of brand A on hand and Y = the amount (in pounds) of brand B on hand. Suppose the joint pdf of X and Y is

$$f_{XY}(x, y) = \begin{cases} kxy & x \geq 0, y \geq 0, 20 \leq x + y \leq 30 \\ 0 & \text{otherwise} \end{cases}$$



- a) First draw the region of positive density of and find the normalizing constant k .

b) Are X and Y independent?

Answer by first deriving the marginal pdf of each variable. **Hints:** The two marginal distributions are the same due to the symmetry of the problem (so you only need to compute one of the marginal distributions). Be careful: the marginal distributions are piecewise functions (there are two separate pieces you need to consider).

Note on Independence

Independent:

Not Independent:

Expected Values, Covariance, and Correlation

Section 5.2

As seen earlier

Discrete

$$E[h(X)] = \sum_x h(x) p(x)$$

Continuous

$$E[h(X)] = \int h(x) f(x) dx$$

Let $h(x,y)$ be a function of two variables (x,y) .

When X and Y are **discrete** and jointly distributed with **pmf** $p(x,y)$, then:

$$E[h(X, Y)] =$$

If X and Y are **continuous** and jointly distributed with **pdf** $f(x,y)$, then:

$$E[h(X, Y)] =$$

25

Example

5.14 (modified) Suppose (example 5.5) the marginal distribution of amount of almonds (X) and the marginal distribution of the amount of cashews (Y) in a 1-lb can of nuts are:

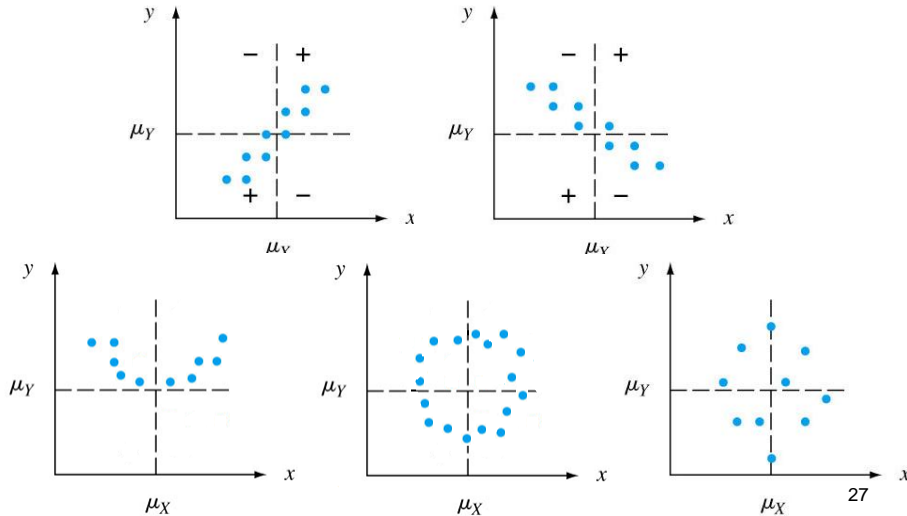
$$f_X(x) = \begin{cases} 12x(1-x)^2 & 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases} \quad f_Y(y) = \begin{cases} 12y(1-y)^2 & 0 \leq y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

If 1 lb of almonds cost the company \$1.00, 1 lb of cashews costs \$1.50, and 1 lb of peanuts costs \$0.50, then what is the expected total cost of a can?

26

Covariance

Covariance is a measure of **how strongly** two random variables are (linearly) related and whether this TREND is positive or negative



Covariance

$$\text{Cov}(X, Y) = E[(X - \mu_X)(Y - \mu_Y)] = E[XY] - \mu_X\mu_Y$$

Discrete Case:

Continuous
Case:

Problem with interpreting **covariance** as a measure of the strength of relationship between X and Y:

$$\text{Cov}(aX + b, cY + d) =$$

28

Correlation

$$\rho = \rho_{X,Y} = \frac{\text{Cov}(X, Y)}{\sigma_X \cdot \sigma_Y}$$

Correlation is a measure of how strongly two random variables are **linearly** related

- $-1 \leq \text{Corr}(X, Y) \leq 1$
- If $ac > 0$, $\text{Corr}(aX + b, cY + d) = \text{Corr}(X, Y)$
- If X and Y are independent, then $\rho = 0$, BUT
 $\rho = 0$ does not imply independence.
- $\rho = 1$ or $\rho = -1$ if and only if $Y = aX + b$ for some $a \neq 0$

29

Transportation Example - Continued

e. Expected Values and Variances of X, Y

of Cars in one signal cycle, $E(X)$, $\text{Var}(X)$

of Buses in one signal cycle, $E(Y)$, $\text{Var}(Y)$

f. Cov(X,Y) and Cor(X,Y)

Find $E(XY)$:

$\text{Cov}(X, Y) =$

$\text{Cor}(X, Y) =$