

Physics 7502: Homework Set No. 2

Due date: Tuesday, Jan. 26, 2016, 5:00pm
in PRB M2039 (Bowen Shi's office)

Total point value of set: 100 points

Note: All cross products in this problem set must be worked out with the help of the Levi-Civita tensor ε_{ijk} (ε_{ijk} is totally antisymmetric, i.e. it changes sign under interchange of any two indices, and $\varepsilon_{123} = 1$)! Remember $\sum_{n=1}^3 \varepsilon_{ijn} \varepsilon_{nkl} = \delta_{ik} \delta_{jl} - \delta_{il} \delta_{jk}$.

Problem 1 (10 pts.): Show that the definition of the orbital angular momentum operator $\hat{\mathbf{L}}$ is unambiguous, i.e. that you obtain the same operator (with identical effects on any state $|\psi\rangle$) if you start from the classical expressions $\mathbf{L} = -\mathbf{p} \times \mathbf{x}$ and $\mathbf{L} = \mathbf{x} \times \mathbf{p}$ and then substitute $\mathbf{x} \mapsto \hat{\mathbf{X}}$, $\mathbf{p} \mapsto \hat{\mathbf{P}}$. (Note the different order of multiplication and differentiation that you obtain in the two cases!)

Problem 2 (30 pts.): For *any* vector operator $\hat{\mathbf{v}}$ constructed from $\hat{\mathbf{X}}$ and $\hat{\mathbf{P}}$, prove that $[\hat{L}_i, \hat{v}_j] = i\hbar \sum_{k=1}^3 \varepsilon_{ijk} \hat{v}_k$. (Hint: Write $\mathbf{v} = a(\mathbf{x}^2, \mathbf{x} \cdot \mathbf{p}, \mathbf{p}^2) \mathbf{x} + b(\mathbf{x}^2, \mathbf{x} \cdot \mathbf{p}, \mathbf{p}^2) \mathbf{p} + c(\mathbf{x}^2, \mathbf{x} \cdot \mathbf{p}, \mathbf{p}^2) \mathbf{x} \times \mathbf{p}$ (where a, b, c are arbitrary functions). Derive commutation relations between the components of $\hat{\mathbf{L}}$ and those of $\hat{\mathbf{X}}$ and $\hat{\mathbf{P}}$ and show that $\hat{\mathbf{L}}$ commutes with the scalar operators $\hat{a}, \hat{b}, \hat{c}$. Proceed to show that $[\hat{L}_i, \hat{v}_j] = i\hbar \varepsilon_{ijk} \hat{v}_k$ (sum over k implied).)

Problem 3 (10 pts.): Prove the identity $\hat{\mathbf{L}} \times \hat{\mathbf{L}} = i\hbar \hat{\mathbf{L}}$ for the orbital angular momentum operator $\hat{\mathbf{L}} = \hat{\mathbf{X}} \times \hat{\mathbf{P}}$.

Problem 4 (20 pts.): From the definition $\hat{\mathbf{L}} = \hat{\mathbf{X}} \times \hat{\mathbf{P}}$, derive the following expressions in the position representation $\hat{\mathbf{P}} \rightarrow -i\hbar \nabla$ in spherical coordinates:

$$\begin{aligned}\hat{L}_x &\rightarrow L_1 = i\hbar (\sin \phi \partial_\theta + \cot \theta \cos \phi \partial_\phi), \\ \hat{L}_y &\rightarrow L_2 = i\hbar (-\cos \phi \partial_\theta + \cot \theta \sin \phi \partial_\phi), \\ \hat{L}_z &\rightarrow L_3 = -i\hbar \partial_\phi, \\ \hat{\mathbf{L}}^2 &\rightarrow \mathbf{L}^2 = -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right].\end{aligned}$$

Hint: It's easiest to prove the first three backwards. For the last, express \mathbf{L}^2 through $L_\pm = L_x \pm iL_y$ to simplify the algebra.

Problem 5 (10 pts.): Exercise 12.5.1 (Shankar, p. 325)

Problem 6 (10 pts.): Exercise 12.5.3 (Shankar, p. 329)

Problem 7 (10 pts.): Exercise 12.5.5, part (1) only (Shankar, p. 332)