

$T_{11}, T_{22}, T_{33} \sim$ radiation pressure components (16)

Classification of Physical Quantities by Space-Time Symmetries

A. Spatial rotations

$$x_\alpha \rightarrow x'_\alpha = R_{\alpha\beta} x_\beta, \quad R_{\alpha\beta} - \text{rotation matrix}$$

$$\vec{x}^2 = \vec{x}'^2 \text{ under rotation} \Rightarrow (R_{\alpha\beta} x_\beta)(R_{\alpha\gamma} x_\gamma) = x_\alpha x_\alpha$$

$$\Rightarrow (R_{\alpha\beta} R_{\alpha\gamma} = \delta_{\beta\gamma}) \Rightarrow (R^{-1})_{\alpha\beta} = R_{\beta\alpha}$$

$\det R = +1 \sim$ rotation w/o reflection

vectors: $A_\alpha \rightarrow A'_\alpha = R_{\alpha\beta} x_\beta$

tensors: $T_{\alpha_1 \alpha_2 \dots \alpha_n} \rightarrow T'_{\alpha_1 \alpha_2 \dots \alpha_n} = R_{\alpha_1 \beta_1} R_{\alpha_2 \beta_2} \dots R_{\alpha_n \beta_n}$

(definition) $\cdot T_{\beta_1 \dots \beta_n}$

B. Spatial Reflection

$$\vec{x} \rightarrow -\vec{x} \text{ on all } \underline{\text{vectors}} \text{ (or polar vectors)}$$

transform like this

$$\vec{z} = \vec{x} \times \vec{y} \Rightarrow \left. \begin{array}{l} \vec{x} \rightarrow -\vec{x} \\ \vec{y} \rightarrow -\vec{y} \end{array} \right\} \Rightarrow \vec{z} \rightarrow \vec{z} \quad \underline{\text{axial vector}} \\ \text{(pseudovector)}$$

Inversion is also called parity IP.

IP: vector \rightarrow -vector, axial vector \rightarrow axial vector
 $p = -1$ $p = +1$

Tensor of rank N : $IP T_{\alpha_1 \dots \alpha_N} = (-1)^N T_{\alpha_1 \dots \alpha_N}$

Pseudotensor of rank N : $IP T_{\alpha_1 \dots \alpha_N} = (-1)^{N+1} T_{\alpha_1 \dots \alpha_N}$

[E.g. $\vec{z} = \vec{x} \times \vec{y} \Rightarrow z_\alpha = \epsilon_{\alpha\beta\gamma} x_\beta y_\gamma \Rightarrow \epsilon_{\alpha\beta\gamma}$ has $p = +1$
 $\Rightarrow p = (-1)^{3+1} \Rightarrow \epsilon_{\alpha\beta\gamma}$ is pseudotensor.]

C. Time reversal: $t \rightarrow -t$

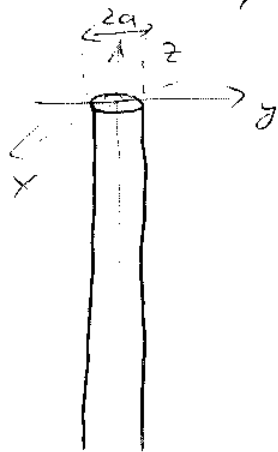
$\Pi \vec{x} = \vec{x}$, $\vec{p} = \frac{d\vec{x}}{dt} \Rightarrow \Pi \vec{p} = -\vec{p} \sim T\text{-odd}$
 \uparrow T-even.

<u>Quantity</u>	<u>Tensor Rank</u>	<u>Parity</u>	<u>Time Reversal</u>
\vec{x}	vector	-1	1
$\vec{v} = d\vec{x}/dt$	vector	-1	-1
\vec{p}	vector	-1	-1
$\vec{L} = \vec{x} \times \vec{p}$	1	1	-1
$\vec{F} = m\vec{a}$	1	-1	1
$\vec{N} = \vec{x} \times \vec{F}$	1	1	1
$E \sim \text{energy}$	0	1	1

<u>Quantity</u>	<u>Tensor Rank</u>	<u>Parity</u>	<u>Time Reversal</u>
ρ	0	1	1
$\vec{J} (= \rho \vec{v})$	1	-1	-1
$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \Rightarrow$			
$\left. \begin{matrix} \vec{E} \\ \vec{D} \end{matrix} \right\}$	1	-1	1
$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow$			
$\left. \begin{matrix} \vec{B} \\ \vec{M} \\ \vec{H} \end{matrix} \right\}$	1	1	-1
$\vec{S} = \vec{E} \times \vec{H}$	1	-1	-1
$T_{\alpha\beta}$	2	1	1

Dirac Monopole

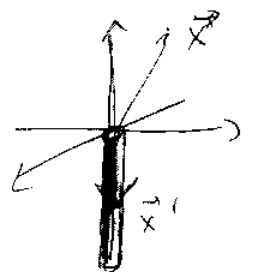
Consider a half-infinite ideal solenoid; it has current I and N loops per unit length. Each loop carries magn. moment



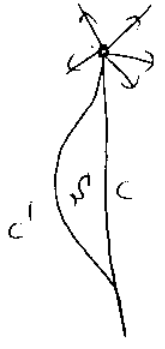
$$d\vec{m} = I \pi a^2 \hat{z} \quad \text{Assume that } a \text{ is tiny} \Rightarrow$$

$$\Rightarrow \vec{A}(\vec{x}) \approx \frac{\mu_0}{4\pi} \int \frac{d\vec{m}' \times (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3}$$

where $dm = I \pi a^2 N dz$



Deform the solenoid: if $g = \pi \mu_0 a^2 I N \Rightarrow \vec{A}(\vec{x}) = \frac{g}{4\pi} \int_C d\vec{x}' \times \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3}$ (21)



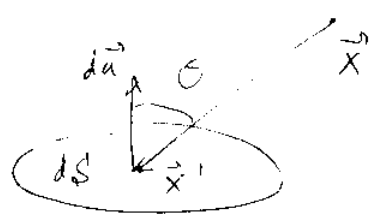
$$\vec{A}' - \vec{A} = \frac{g}{4\pi} \oint_{c'-c} d\vec{x}' \times \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3} = -\frac{g}{4\pi} \oint_{c'-c} d\vec{x}' \times \vec{\nabla}_x \frac{1}{|\vec{x} - \vec{x}'|} =$$

$$= \frac{g}{4\pi} \vec{\nabla} \times \oint_{c'-c} d\vec{x}' \frac{1}{|\vec{x} - \vec{x}'|} = \frac{g}{4\pi} \vec{\nabla} \times \int_{S'} da' \hat{n}' \frac{1}{|\vec{x} - \vec{x}'|} =$$

$$= \frac{g}{4\pi} \int_{S'} da' \nabla'^2 \frac{1}{|\vec{x} - \vec{x}'|} - \frac{g}{4\pi} \nabla_i \int da' \hat{n}'_i \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3} =$$

$-4\pi \delta(\vec{x} - \vec{x}')$
"0" if \vec{x} not on S'

$$= \frac{g}{4\pi} \nabla_i \int da' \frac{\vec{x}' - \vec{x}}{|\vec{x} - \vec{x}'|^3} = \frac{g}{4\pi} \nabla_i \int da' \vec{\nabla}' \frac{1}{|\vec{x} - \vec{x}'|} =$$



$$= \left| \text{as } \nabla_i = -\nabla'_i \right. = -\frac{g}{4\pi} \vec{\nabla} \int da' \cdot \vec{\nabla}' \frac{1}{|\vec{x} - \vec{x}'|} =$$

$$= \frac{g}{4\pi} \vec{\nabla} \int da' \cdot \frac{\vec{x}' - \vec{x}}{|\vec{x} - \vec{x}'|^3} = \frac{g}{4\pi} \vec{\nabla} \mathcal{R}$$

$d\mathcal{R} = \frac{dS' \cos \theta}{|\vec{x} - \vec{x}'|^2} \Rightarrow \mathcal{R}$ is the ~~spatial~~ ^{solid} angle subtended by $c'-c$

$\Rightarrow \vec{A}' = \vec{A} + \frac{g}{4\pi} \vec{\nabla} \mathcal{R} \sim$ gauge transform, physics is the same

Fermions: $\psi \rightarrow \psi' = \psi e^{i \frac{e}{\hbar} \Lambda}$ under gauge

transform $\vec{A} \rightarrow \vec{A} + \vec{\nabla} \Lambda \Rightarrow \psi' = \psi e^{i \frac{e}{\hbar} g \mathcal{R} \frac{1}{4\pi}}$

\Rightarrow if $\mathcal{R} \rightarrow \mathcal{R} \pm 4\pi \Rightarrow$ for ψ to be single-valued need

$\frac{e g}{\hbar} = 2\pi n$, n - integer \sim discrete magnetic charge g