

Population structured by space & trait.

[Perthame-Souganidis (2016); Lam-Lou (2017)]

$$u = u(x, z, t), \quad x \in D, \quad z \in \mathbb{R}, \quad t > 0$$

$$\begin{cases} \partial_t u = \Theta(z) \Delta_x u + u \left(m(x) - \int_0^1 u(x, z, t) dz \right) + \varepsilon^2 \partial_{zz} u & \begin{matrix} x \in D \\ z \in \mathbb{R} \\ t > 0 \end{matrix} \\ n \cdot \nabla_x u = 0 & x \in \partial D, \quad z \in \mathbb{R}, \quad t > 0 \\ u(x, z, t) = u(x, z+1, t) \end{cases}$$

We will analyze the equilibrium solution. $u = u_\varepsilon(x, z)$

$$(0) \begin{cases} \Theta(z) \Delta_x u_\varepsilon + u_\varepsilon (m(x) - f_\varepsilon(x)) + \varepsilon^2 \partial_{zz} u = 0 & (x, z) \in D \times \mathbb{R} \\ n \cdot \nabla_x u_\varepsilon = 0 & (x, z) \in \partial D \times \mathbb{R} \\ u_\varepsilon(x, z) = u_\varepsilon(x, z+1) & (x, z) \in D \times \mathbb{R} \end{cases}$$

where $f_\varepsilon(x) = \int_0^1 u_\varepsilon(x, z) dz$.

Theorem Suppose ① $m(x)$ is positive, nonconst.

② $\Theta(z)$ is cont., positive and 1-periodic.

③ there exists a unique $\hat{z} \in [0, 1]$ st.

$$\inf_{\mathbb{R}} \Theta = \Theta(\hat{z}).$$

Let u_ε be any positive sol. of (1), then as $\varepsilon \rightarrow 0$,

$$u_\varepsilon(x, z) \rightarrow \delta_0(z - \hat{z}) \hat{\Theta}(x) \text{ in distribution sense in } D \times [0, 1],$$

where $\hat{\Theta}(x)$ is the unique positive sol. of

$$\Theta(\hat{z}) \Delta \hat{\Theta} + \hat{\Theta} (m(x) - \hat{\Theta}) = 0 \text{ in } D \quad n \cdot \nabla \hat{\Theta} = 0 \text{ on } \partial D.$$

Lemma 1 For $\varepsilon > 0$ small,

$$\|p_\varepsilon\|_{W^{2,p}(D)} \leq C$$

and $0 < \frac{1}{2} \inf_D m \leq p_\varepsilon(x) \leq 2 \sup_D m$ in $x \in D$.

pf First, we show $\|p_\varepsilon\|_{C(\bar{D})} \leq C$.

$$\Delta_x p_\varepsilon + \varepsilon^2 P_\varepsilon + Q_\varepsilon (m(x) - p_\varepsilon) = 0 \text{ in } D, \quad n \cdot \nabla p_\varepsilon \text{ in } \partial\Omega.$$

$$\text{where } P_\varepsilon(x) = \int_0^1 \frac{1}{\Theta(z)} \partial_{z\bar{z}} u_\varepsilon dz = \int_0^1 \left(\frac{1}{\Theta(z)}\right)_{z\bar{z}} u_\varepsilon dz$$

$$Q_\varepsilon(x) = \int_0^1 \frac{1}{\Theta(z)} u_\varepsilon dz$$

Note that $|P_\varepsilon(x)| \leq C_0 Q_\varepsilon(x)$, $C_0 = \frac{\sup |(\frac{1}{\Theta})_{z\bar{z}}|}{\inf (\frac{1}{\Theta})}$.

$$\Delta_x p_\varepsilon + Q_\varepsilon [m(x) - p_\varepsilon(x) + O(\varepsilon^2)] = 0 \text{ in } D, \quad n \cdot \nabla p_\varepsilon \text{ on } \partial D$$

$$\Rightarrow -O(\varepsilon^2) + \inf_D m \leq p_\varepsilon(x) \leq \sup_D m + O(\varepsilon^2)$$

$\Rightarrow \|p_\varepsilon\|_\infty \leq C$ and so is $|P_\varepsilon|$ and Q_ε .

Furthermore,

$$(1.1) \quad |\Delta_x p_\varepsilon| \leq \varepsilon^2 |P_\varepsilon| + Q_\varepsilon |m(x) - p_\varepsilon(x)|$$

RHS bounded in $L^p \forall p > 1 \Rightarrow \|p_\varepsilon\|_{W^{2,p}} \leq C (\|\Delta p_\varepsilon\|_\infty + \|p_\varepsilon\|_\infty)$.

In particular, Sobolev embedding implies

$p_\varepsilon \rightarrow p$ in $C^1(\bar{\Omega})$ up to subsequence. $\varepsilon_k \rightarrow 0$. #

Cor. \exists at least one positive equilibrium sol.

Pf. Fix $\varepsilon > 0$. For $\tau \in [0, 1]$

$$(P_\tau) \begin{cases} \textcircled{u}(\tau) \Delta_x u + u \left(m(x) - (1-\tau)u - \tau \int_0^1 u \, dz \right) + \varepsilon^2 \frac{\partial^2 u}{\partial z^2} = 0 & (x, z) \in D \times \mathbb{R} \\ n \cdot \nabla_x u = 0 & (x, z) \in \partial D \times \mathbb{R} \\ u(x, z) = u(x, z+1) & (x, z) \in D \times \mathbb{R}. \end{cases}$$

One can similarly find positive constant $C > 1$ which is independent of $\varepsilon > 0$ and $\tau \in [0, 1]$ and any positive solution \tilde{u} of (P_τ)

$$\frac{1}{C} \leq \int_0^1 \tilde{u}(x, z) \, dz \leq C$$

By Harnack principle, $\exists C'$ indep. of τ, \tilde{u}

$$\text{s.t.} \quad \frac{1}{C'} \leq \tilde{u}(x, z) \leq C'$$

Now, when $\tau = 0$, (P_0) is the diffusion logistic equation and has a (unique) positive sol.

One can then derive the existence of solution for (P_1) by a standard topological degree argument. See, e.g. [L. CVPDE (2007)].

Lemma 2. Suppose $f_\varepsilon \rightarrow f$ in $C^1(\bar{\Omega})$
 for some $f \in C^1(\bar{\Omega})$, then $m - f \neq \text{const}$ in Ω .

Pf Integrate (1) we deduce $\int_D f_\varepsilon (m - f_\varepsilon) dx = 0$.

If $m - f_\varepsilon \rightarrow c_0$, then $c_0 = 0$.

But (1.1) implies $\Delta_x f_\varepsilon = o(1)$ in D , $n \cdot \nabla f_\varepsilon = 0$ on ∂D

$\Rightarrow f = \lim f_\varepsilon = \text{const.} \Rightarrow m - f \neq \text{const.} \quad \#$

Lemma 3 There exists C indep. of ε such that

$$\varepsilon \left\| \frac{\partial_z u_\varepsilon}{u_\varepsilon} \right\|_{C(\bar{D} \times [0,1])} + \left\| \frac{\nabla_x u_\varepsilon}{u_\varepsilon} \right\|_{C(\bar{D} \times [0,1])} \leq C$$

Pf. Fix $z_0 \in \mathbb{R}$ and define.

$$U_\varepsilon(x, y) = u_\varepsilon(x, z_0 + \varepsilon y)$$

Then $\mathcal{L}_\varepsilon U_\varepsilon = -A_\varepsilon(y) \Delta_x U_\varepsilon - \partial_{zz} U_\varepsilon = h_\varepsilon(x) U_\varepsilon$

where $A_\varepsilon(y)$ and $h_\varepsilon(x)$ are bdd Lipschitz (unif. in ε).

and $0 < \inf(h) \leq A_\varepsilon(y) \leq \sup(h)$.

Apply Harnack Principle.

$$(3.1) \quad \sup_{D \times [-1,1]} U_\varepsilon \leq C \inf_{D \times [-1,1]} U_\varepsilon.$$

Sobolev embedding and L^p estimate implies

$$\begin{aligned} |\partial_z U_\varepsilon(x, 0)| + |\nabla_x U_\varepsilon(x, 0)| &\leq C \|U_\varepsilon\|_{W^{2,p}(D \times [-\frac{1}{2}, \frac{1}{2}])} \\ &\leq C \|U_\varepsilon\|_{L^p(D \times [-1, 1])} \\ &\leq C \sup_{D \times [-1, 1]} U_\varepsilon. \end{aligned}$$

$$|\partial_z U_\varepsilon(x, 0)| + |\nabla_x U_\varepsilon(x, 0)| \leq C \inf_{D \times [-1, 1]} U_\varepsilon \leq C U_\varepsilon(x, 0) \quad \forall x \in D$$

#

Introduce the WKB-ansatz.

$$W_\varepsilon(x, z) = -\varepsilon \log U_\varepsilon(x, z)$$

then

$$(*) \quad -\varepsilon \partial_{zz} W_\varepsilon + |\partial_z W_\varepsilon|^2 + m(x) - f_\varepsilon(x) = \mathcal{H}(z) \left(\frac{\Delta_x W_\varepsilon}{\varepsilon} - \frac{|\nabla_x W_\varepsilon|^2}{\varepsilon^2} \right)$$

$$|\partial_z W_\varepsilon| = \varepsilon \frac{|\partial_z U_\varepsilon|}{U_\varepsilon}, \quad |\nabla_x W_\varepsilon| = \varepsilon \frac{|\nabla_x U_\varepsilon|}{U_\varepsilon} \quad \text{in } D \times \mathbb{R}.$$

Only needed
After
Lemma 4

Lemma 4 $\{W_\varepsilon\}$ is precompact in $C(\bar{D} \times [0,1])$.

If $W_\varepsilon(x,z) \rightarrow w$, then $w = w(z)$ and $\inf_{[0,1]} w = 0$.

Pf. By Lemma 3, $\sup_{D \times [0,1]} \left[|\partial_z W_\varepsilon| + \frac{1}{\varepsilon} |\nabla_x W_\varepsilon| \right] \leq C$.

Together with $\int_0^1 \exp\left(-\frac{W_\varepsilon(x,z)}{\varepsilon}\right) dz$

equicontinuity

$$0 < \frac{1}{2} \inf m \leq \rho_\varepsilon(x) \leq 2 \sup m < +\infty,$$

We deduce by Ascoli theorem that

$\frac{W_\varepsilon(x,z)}{\varepsilon} \rightarrow w(z)$ in $C(\bar{D} \times [0,1])$ in a seq $\varepsilon_k \rightarrow 0$.
 where w is independent of x .

$\inf w > 0 \Rightarrow \rho_\varepsilon \rightarrow 0$ impossible.

$\inf w < 0 \Rightarrow \rho_\varepsilon \rightarrow +\infty$ impossible.

Here, $\inf_{[0,1]} w = \lim_{\varepsilon \rightarrow 0} \inf_{D \times [0,1]} W_\varepsilon = 0$.

#

Now, W_ε satisfies

$$(*) \quad -\varepsilon \partial_{zz} W_\varepsilon + |\partial_z W_\varepsilon|^2 + m(x) - \rho_\varepsilon(x) = \mathcal{H}(z) \left(\frac{\Delta_x W_\varepsilon}{\varepsilon} - \frac{|\nabla_x W_\varepsilon|^2}{\varepsilon^2} \right)$$

in $D \times \mathbb{R}$

Def For each $z \in \mathbb{R}$, and $h \in C(\bar{D})$, define

$\Lambda_h(z)$ and $x \mapsto \phi_h(x, z)$ to be the p.e.v. / p.e.f of

$$\begin{cases} \textcircled{H}(z) \Delta_x \phi = (m(x) - h(x)) \phi + \Lambda \phi = 0 & \text{in } D \\ n \cdot \nabla_x \phi = 0 & \text{on } \partial D \end{cases}$$

Recall $\textcircled{H}(z) > \textcircled{H}(\hat{z}) \quad \forall z \in [0, 1], z \neq \hat{z}$.

Suppose $W_\varepsilon(x, z) \rightarrow w(z)$ and $p_\varepsilon(x) \rightarrow p(x)$ uniformly.

Define $\psi(x, z) = \log \phi_p(x, z)$, then

$$-\textcircled{H}(z) (|\nabla_x \psi|^2 + \Delta_x \psi) = m(x) - p(x) + \Lambda_p(z).$$

Write $W_\varepsilon(x, z) := V_\varepsilon(x, z) - \varepsilon \psi(x, z)$,

$$\begin{aligned} -\varepsilon \left(\partial_{xx} V_\varepsilon + |\partial_z V_\varepsilon + o(1)|^2 + o(1) \right) + \underbrace{m(x) - p_\varepsilon} &= \textcircled{H}(z) \left(\frac{\Delta_x V_\varepsilon}{\varepsilon} - \Delta_x \psi - \frac{|\nabla_x V_\varepsilon|^2}{\varepsilon^2} + 2 \frac{\nabla_x V_\varepsilon \nabla_x \psi}{\varepsilon} - |\nabla_x \psi|^2 \right) \\ &= \textcircled{H}(z) \left(\frac{\Delta_x V_\varepsilon}{\varepsilon} + 2 \frac{\nabla_x V_\varepsilon \nabla_x \psi}{\varepsilon} - \frac{|\nabla_x V_\varepsilon|^2}{\varepsilon} \right) \\ &\quad + \underbrace{m(x) - p(x) + \Lambda_p(z)}. \end{aligned}$$

$$(*) \quad -\varepsilon \left(\partial_{xx} V_\varepsilon + |\partial_z V_\varepsilon + o(1)|^2 \right) = \textcircled{H}(z) \left(\frac{\Delta_x V_\varepsilon}{\varepsilon} - \frac{2 \nabla_x V_\varepsilon \nabla_x \psi}{\varepsilon} - \frac{|\nabla_x V_\varepsilon|^2}{\varepsilon^2} \right) + \Lambda_p(z) + o(1).$$

(Keep on board).

Lemma 5 $\Lambda_p(z) > 0$ if $z \in [0, 1] \setminus \{\hat{z}\}$

Pf. $V_\varepsilon(x, z) = W_\varepsilon(x, z) + o(1) \rightarrow W(z)$.

Fix an interval $[p, q] \subseteq \mathbb{R}$, take a test fun

$$\varphi(z) = \frac{1}{\sigma(z)}, \quad \sigma(z) > 0 \text{ in } (p, q), \quad \sigma(z) \equiv 0 \text{ in } \mathbb{R} \setminus (p, q).$$

then $V_\varepsilon(x, z) - \varphi(z)$ attains maximum point in $\bar{\Omega} \times [p, q]$.
wlog, $z_\varepsilon \rightarrow z_0 \in [p, q]$.
($x_\varepsilon, z_\varepsilon$).

$$(*) \Rightarrow |\varphi'(z_\varepsilon) + o(1)| + o(1) \leq \Lambda_p(z_\varepsilon)$$

letting $\varepsilon \rightarrow 0$, $0 \leq \Lambda_p(z_0) \Rightarrow \Lambda_p \geq 0$ in a dense set.

By continuity, $\Lambda_p(z) \geq 0 \quad \forall z \in \mathbb{R}$.

Since $m(x) - p(x) \neq \text{const}$, Λ_p is strictly increasing in x in diff. rate.
 $\forall z \neq \hat{z}$

$$\textcircled{1}(z) > \textcircled{1}(\hat{z}) \rightarrow \Lambda_p(z) > \Lambda_p(\hat{z}) \geq 0.$$

#

Lemma 6 $W(z) > 0$ for $z \in [0, 1] \setminus \{\frac{1}{2}\}$.

Pf. Suppose $W(z_0) = 0 \quad \exists z_0 \in [0, 1]$,

Then $W(z) + (z - z_0)^2$ has a strict local min. at $z = z_0$.

$\Rightarrow V_\varepsilon(x, z) + (z - z_0)^2$ has a local min $(x_\varepsilon, z_\varepsilon) \in \bar{D} \times \mathbb{R}$
s.t. $z_\varepsilon \rightarrow z_0$.

At the point $(x_\varepsilon, z_\varepsilon)$,

$$\varepsilon \left[(z - z_0)^2 \right]''_{z=z_\varepsilon} + \left| 2(z - z_0) + o(1) \right|^2 \geq \Lambda_p(z_\varepsilon) + o(1).$$

Letting $\varepsilon \rightarrow 0$, $0 \geq \Lambda_p(z_0) \Rightarrow z_0 = \frac{1}{2}$.

To conclude, for $z \neq \hat{z}$, $w(z) > 0$ and,

$$U_\varepsilon(x, z) = \exp\left(-\frac{w(z) + o(1)}{\varepsilon}\right) \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

and we claim that $p(x) = \lim_{\varepsilon \rightarrow 0} p_\varepsilon(x)$ is a

weak solution of
$$\begin{cases} -\mathbb{H}(\hat{z}) \Delta_x p = p(m-p) & \text{in } \Omega \\ n \cdot \nabla_x p = 0 & \text{on } \partial\Omega. \end{cases}$$

Indeed, rewrite (0.1) as

$$\mathbb{H}(\hat{z}) \Delta_x U_\varepsilon + U_\varepsilon(m(x) - p_\varepsilon(x)) = -(\mathbb{H}(z) - \mathbb{H}(\hat{z})) \Delta_x U_\varepsilon - \varepsilon^2 \partial_{zz} U_\varepsilon$$

Integrate in z .

$$\mathbb{H}(\hat{z}) \Delta p_\varepsilon + p_\varepsilon(m - p_\varepsilon) = -\int_0^1 (\mathbb{H}(z) - \mathbb{H}(\hat{z})) \Delta_x U_\varepsilon dz.$$

Multi. by a test fun $\varphi(x) \in C^1(\bar{D})$,

$$-\mathbb{H}(\hat{z}) \int_D \nabla p_\varepsilon \nabla \varphi + \int_D \varphi p_\varepsilon(m - p_\varepsilon) = R_\varepsilon.$$

where

$$|R_\varepsilon| = \left| \int_{D \times [0,1]} (\mathbb{H}(z) - \mathbb{H}(\hat{z})) \nabla_x U_\varepsilon \cdot \nabla_x \varphi dx dz \right|$$

$$\leq C \int_{D \times [0,1]} |z - \hat{z}| U_\varepsilon(x, z) dx dz \leq C \left(\int_{D \times [\hat{z} - \delta, \hat{z} + \delta]} + \int_{D \times [\hat{z} - \delta, \hat{z} + \delta]^c} \right)$$

$$\leq C \left(\delta \int_D p_\varepsilon dx + o(1) \right).$$

$$\Rightarrow \limsup_{\varepsilon \rightarrow 0} |R_\varepsilon| \leq C \delta \quad \forall \delta > 0 \Rightarrow |R_\varepsilon| \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

Therefore,

$$\textcircled{4}(\hat{z}) \int_D \nabla p \nabla \psi \, dx + \int_D \psi p(m-p) \, dx = 0 \quad \forall \psi \in C^1(\bar{D})$$

i.e. p is a weak solution \dagger .

$$\left\{ \begin{array}{l} \textcircled{4}(\hat{z}) \Delta p + p(m-p) = 0 \text{ in } \Omega \\ n \cdot \nabla p = 0 \text{ on } \partial\Omega \end{array} \right.$$

By uniqueness, $p = \mathcal{O}_{\hat{z}} \dots$ #

Remark. In fact, the limits $w(z) = \lim_{\varepsilon \rightarrow 0} w_\varepsilon(x, z)$

$$p(x) = \lim_{\varepsilon \rightarrow 0} p_\varepsilon(x)$$

satisfies a constrained Hamilton-Jacobi equation

$$\left\{ \begin{array}{l} |w'|^2 = \Lambda_p(z) \quad \text{for } 0 < z < 1 \text{ in viscosity sense} \\ \inf_{0 < z < 1} w(z) = 0 \end{array} \right.$$

To determine the "parameter" $p(x)$ who lies in $C(\bar{D})$, we use the reduction principle to deduce that

$$\Lambda_p(z) > 0 \quad \text{for } z \neq \hat{z} \quad \left(\hat{z} = \arg \min \textcircled{4} \right).$$

By property of viscosity sol, w can only attain minimum at $z = \hat{z} \Rightarrow w(z) > 0$ for $z \neq \hat{z}$

$$\Rightarrow u_\varepsilon(x, z) = \exp\left(-\frac{w(z) + o(1)}{\varepsilon}\right) \approx p(x) \delta(z - \hat{z})$$

Hence, p can be uniquely determined by the single species model.

Questions of Uniqueness & Stability of Equilibrium.

Case 1 $m(x) \neq \text{const.}$

In a slight variant of the problem (where $\Theta(z) = z$ and the periodic b.c. in z variable is substituted by a Neumann b.c.), it is proved that the positive equilibrium is locally asymptotically stable and unique when $0 < \varepsilon \ll 1$. The main idea is to show that every positive equilibrium is linearly stable, and use a topological degree argument.

Case 2 $m(x) \equiv 1$.

Consider time-dependent solutions $u(x, z, t)$ of

$$\begin{cases} \partial_t u - \varepsilon^2 \partial_{zz}^2 u = \Theta(z) \Delta_x u + u(1 - p(x, t)) & x \in D, z \in \mathbb{R}, t > 0 \\ \text{Neumann b.c. in } x, 1\text{-periodic in } z. \\ p(x, t) = \int_0^1 u(x, z, t) dz. \end{cases}$$

• $U(x, z) \equiv 1$ is a positive equilibrium.

• $V(u) := \int_D \int_0^1 (u-1 - \log u) dz dx$ is a Lyapunov function.

$$\begin{aligned}
\frac{d}{dt} V(u) &= \iint \partial_t u - \frac{\partial_t u}{u} dz dx \\
&= \iint u(1-p) - \frac{\varepsilon^2 \partial_{zz}^2 u + \Theta \Delta_x u}{u} - (1-p) dz dx \\
&= \iint (u-1)(1-p) dz dx - \iint \frac{\varepsilon^2 |\partial_z u|^2 + \Theta |\partial_x u|^2}{u^2} dz dx \\
&\leq - \int_D (1-p)^2 dx.
\end{aligned}$$

By LaSalle's invariance principle,

$u(\cdot, \cdot, t) \longrightarrow$ maximal invariance set of $\left. \begin{array}{l} \text{entire solutions} \\ \tilde{u}(x, z, t) \text{ for which } \int_0^1 \tilde{u}(x, z, t) dz \equiv 1 \end{array} \right\}$

i.e. $\tilde{u}(x, z, t)$ satisfies

$$\left\{ \begin{array}{l} \partial_t \tilde{u} = \varepsilon^2 \partial_{zz}^2 \tilde{u} + \Theta \Delta_x \tilde{u} \quad \text{in } D \times \mathbb{R} \times \mathbb{R} \\ u \cdot \nabla_x \tilde{u} = 0 \quad \partial D \times \mathbb{R} \times \mathbb{R} \\ \tilde{u}(x, z, t) = \tilde{u}(x, z+1, t), \tilde{u} > 0 \quad D \times \mathbb{R} \times \mathbb{R} \end{array} \right.$$

By uniqueness of principal Floquet bundle,

$$\tilde{u}(x, z, t) \equiv C \quad \exists C > 0.$$

Since $\int_0^1 \tilde{u} dz \equiv 1$, we deduce that $\tilde{u} \equiv 1$.

Conjecture, Global stability of equilibrium $\#$
holds in general.

Selection-Mutation Model in advective environment.

Consider the equilibrium solutions $u_\varepsilon(x, z)$ of

$$\left\{ \begin{array}{l} \partial_t u - \varepsilon^2 \partial_{zz} u = z \partial_{xx} u - g \partial_x u + u(m(x) - p_\varepsilon(x, t)) \quad 0 < x < L, z \in I, t > 0 \\ z \partial_x u - g u = 0 \quad x=0, L, z \in I, t > 0. \\ u = 0 \quad 0 < x \leq L, z \in \partial I, t > 0 \\ u(x, z, 0) = u_0(x, z). \end{array} \right.$$

where $I = [\underline{z}, \bar{z}] \subseteq (0, \infty)$.

Then under smallness assumptions on $|I|$, one can obtain:

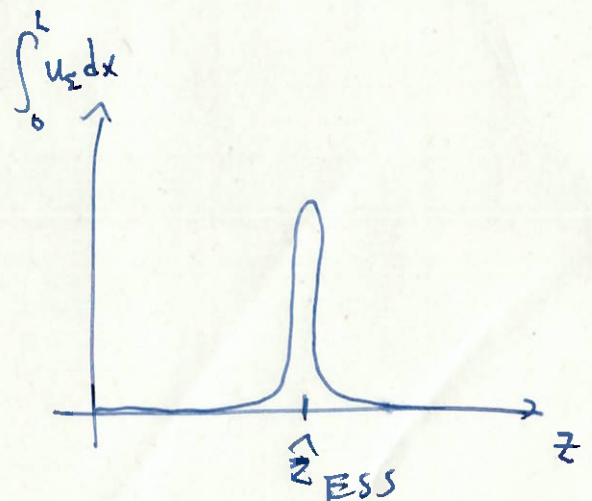
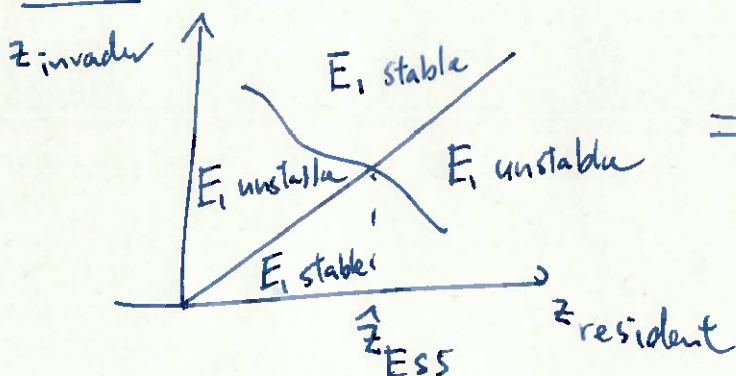
(ESS) If the adaptive dynamics of two-species model has a ESS $\hat{z} \in I$, then for $0 < \varepsilon \ll 1$,

$$u_\varepsilon(x, z) \rightarrow \mathcal{O}_{\hat{z}}(x) f(z - \hat{z}).$$

(Fixation) If the AD says slower diffusion (resp. faster diffusion) wins, then

$$u_\varepsilon(x, z) \rightarrow \mathcal{O}_{\underline{z}}(x) f(z - \underline{z}) \quad (\text{resp. } \mathcal{O}_{\bar{z}}(x) f(z - \bar{z}))$$

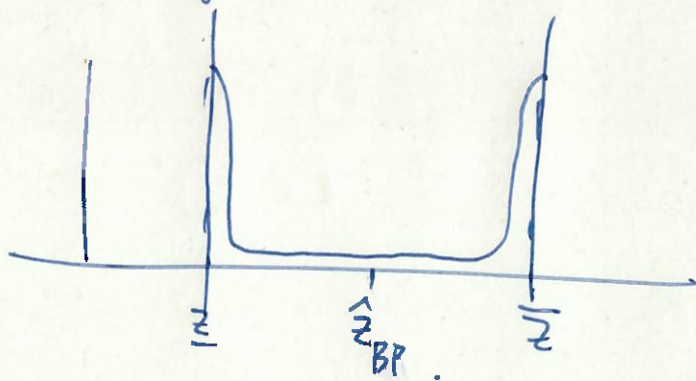
Recall



(Branching). If the AD has a branching point $\bar{z} \in \mathbb{I}$,

then $u_\varepsilon(x, z) \rightarrow U(x) \delta(z - \bar{z}) + V(x) \delta(z - \bar{z})$

where $(U(x), V(x))$ is a positive equilibrium of the underlying two-species competition model.



Lorz - Mirrahimi - Perthame. (2011).

$$\left\{ \begin{aligned} \varepsilon \partial_t u_\varepsilon - \varepsilon^2 \Delta u_\varepsilon &= u_\varepsilon (m(z) - p_\varepsilon(t)) && \text{for } z \in \mathbb{R}^n, t > 0 \\ p_\varepsilon(t) &= \int u_\varepsilon(z, t) dz. \\ u_\varepsilon(z, 0) &= \exp\left(-\frac{|z-z_0|^2 + o(1)}{\varepsilon}\right) \approx \delta(z-z_0) \end{aligned} \right.$$

Take $W_\varepsilon(x, z, t) = -\varepsilon \log u_\varepsilon(x, z, t)$

then

$$\left\{ \begin{aligned} \partial_t W_\varepsilon - \varepsilon \Delta W_\varepsilon + |\partial_z W_\varepsilon|^2 + m(z) - p_\varepsilon(t) &= 0 && z \in \mathbb{R}^n, t > 0 \\ W_\varepsilon(z, 0) = W_\varepsilon^0(z) &\approx (z-z_0)^2 \end{aligned} \right.$$

By establishing appropriate estimates, it can be

shown that $W_\varepsilon(z, t) \rightarrow w(z, t)$ in $C_{loc}(\mathbb{R}^n \times \mathbb{R}_+)$ and

$\exists p \in BV(\mathbb{R}_+)$ s.t. $p_\varepsilon(t) \rightarrow p(t)$ in $L^1_{loc}(\mathbb{R}_+)$.

$$\text{s.t. } \left\{ \begin{aligned} \partial_t w + |\partial_z w|^2 + m(z) - p(t) &= 0 && \text{in } \mathbb{R}^n \times \mathbb{R}_+ \text{ in viscosity sense} \\ \inf_{\mathbb{R}^n} w(\cdot, t) &= 0 && \forall t > 0. \end{aligned} \right.$$

$$W_\varepsilon(z, t) \xrightarrow{\varepsilon \rightarrow 0} p(t) \delta(z - \bar{z}(t)) \quad \text{s.t. } m(\bar{z}(t)) = p(t).$$

Canonical equation of Adaptive Dynamics

$$\frac{d}{dt} \bar{z}(t) = \left(-D^2 u(\bar{z}(t), t) \right)^{-1} \cdot \nabla m(\bar{z}(t)), \quad \bar{z}(0) = z_0.$$

§ Time-dependent problem

Difficulty: There is no reduction principle,
 how do we determine the parameter
 $\rho_\varepsilon(x, t)$??

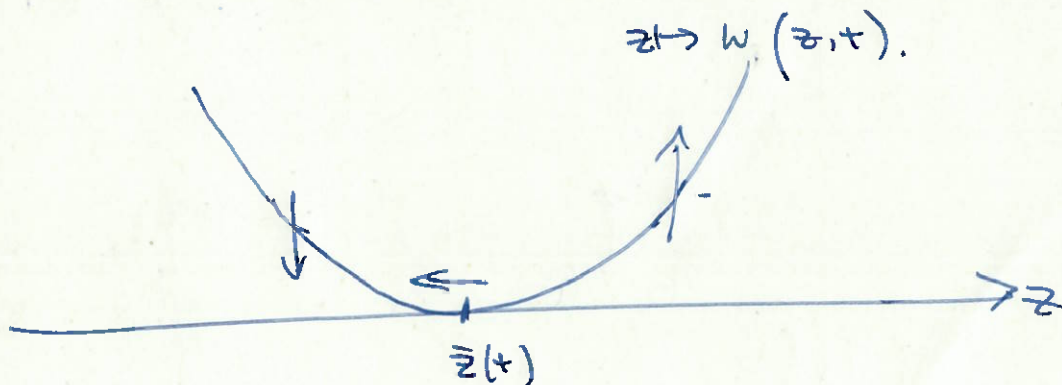
$$\varepsilon \partial_t \rho_\varepsilon - \Delta_x \int \Theta(z) u_\varepsilon dz = \rho_\varepsilon(m - \rho_\varepsilon) \text{ in } D \times (0, \infty)$$

Under additional assumption on Θ , mutation distance metric in the phenotypic space
 one can show that $w(z, t)$ retains convexity in z ,
 so one can show that (for specially chosen
 initial condition).

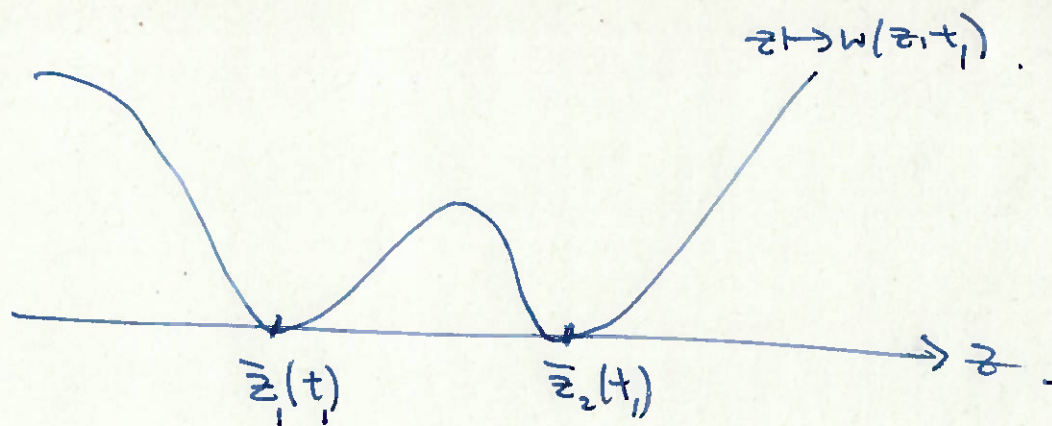
$$u_\varepsilon(x, z, t) = \int (z - \bar{z}(t)) \Theta_{\bar{z}(t)}(x),$$

where $\bar{z}(t) \in C_{loc}^1$ is the "unique" path s.t.
 certain Hamilton-Jacobi eq has a viscosity sol.

$$\left\{ \begin{array}{l} \partial_t w + |\partial_z w|^2 = \lambda(z, \bar{z}(t)) \quad \text{for } z \in \mathbb{R}, t > 0 \\ \inf_z w(\cdot, t) = 0 \quad \text{for } t > 0 \\ \lambda(z, \bar{z}) = \Lambda_{\Theta_{\bar{z}}}(z) \end{array} \right.$$



For the case $(1) \bar{z} = z$, $z \in [a, b] \subseteq (0, \infty)$,
 it seems that one will need the uniqueness
 result in [Calvez-L. (VPPE (2018))] and
 also the hypothesis that Dockey's conjecture
 holds for all $N \geq 3$ and all $0 < z_1 < \dots < z_n$,
 to handle



$t_2 = t_1 + \eta$

