

# Asymptotic Spreading of the Fisher-KPP Equation

We discuss the F-KPP model in 1-dim, unbounded domain.

$$(FKPP) \begin{cases} \overbrace{u_t - u_{xx}} = \overbrace{u(r(x,t) - u)} & \text{for } x \in \mathbb{R}, t > 0 \\ u(x, 0) = u_0(x) & \text{for } x \in \mathbb{R}, \end{cases}$$

where  $0 \leq u_0(x) \leq 1$ ,  $u \not\equiv 0$ , and  $u_0(x) = 0$  for all sufficiently large  $x$ .

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Def. We say that (F-KPP) has (right) spreading speed  $c_x > 0$  if

$$(a) \quad c > c_x \Rightarrow \lim_{t \rightarrow \infty} \sup_{x > ct} |u(x,t)| = 0$$

$$(b) \quad 0 < c < c_x \Rightarrow \liminf_{t \rightarrow \infty} \inf_{0 < x < ct} u(x,t) > 0 \quad (\text{in case } \inf r > 0)$$

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We will restrict our discussion to the following two cases:

$$(\text{Homogeneous environment}) \quad r(x,t) \equiv r_0$$

$$(\text{Shifting environment}) \quad r(x,t) = g(x - ct)$$

§ Homogeneous environment  $r(x,t) = r_0 > 0$

Traveling wave solutions

(F-KPP) admits a family of TW sol.  $\{u_c(x,t) : c \geq 2\sqrt{r_0}\}$

such that  $u_c(x,t) = p(x-ct)$ , where  $p(\xi)$

and satisfies 
$$\begin{cases} -c p' - p'' = p(r_0 - p) & \xi \in \mathbb{R} \\ p(-\infty) = r_0, & p(+\infty) = 0. \end{cases}$$

In particular,  $2\sqrt{r_0}$  is the minimal speed of TW sol.

Pf Phase-plane method :

$$\begin{cases} p' = q \\ q' = -c q - q(r_0 - q) \end{cases}$$

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We will show that the spreading speed  $c_x$  coincides with the minimal wave speed  $2\sqrt{r_0}$ .

Thm A [Kolmogorov et al. (1937); Aronson-Weinberger (1978)].

$$r(x,t) \equiv r_0 > 0 \quad \Rightarrow \quad \underline{c_x = 2\sqrt{r_0}},$$

Remark The coincidence of  $c_x$  with the minimal TW speed holds in much greater generality.

See [Weinberger (1982); Liang-Zhao (2007)].

Convergence to TW profile

$$\sup_{x > 0} \left| u(x,t) - \phi \left( x - 2\sqrt{r_0}t + \frac{3}{2\sqrt{r_0}} \log t + C_0 \right) \right| \xrightarrow{t \rightarrow \infty} 0 \quad \text{as } t \rightarrow \infty$$

$c_x t + \underline{o(t)}$

[Bramson, Mem. AMS (1983)]

[Hamel-Nolen-Roquesoffne-Ryzhik, Net. Het. Media (2013)]

[Nolen-Roquesoffne-Ryzhik, Chin. Ann. Math. (2017)]

We give a proof of Thm A by constructing super/subsolutions in the generalized sense.

Supersol For  $r_0 > 0$ ,  $\lambda > 0$ , define

$$\underline{\phi_{r_0, \lambda}(x, t) = e^{-\lambda(x-ct)}, \quad \text{where } \underline{c = \lambda + \frac{r_0}{\lambda}}.$$

$$\text{Then } \phi_t - \phi_{xx} - \phi(r_0 - \phi) \geq 0 \quad \forall x \in \mathbb{R}, t \geq 0.$$

Indeed,  $\phi_t - \phi_{xx} - \phi(r_0 - \phi)$

$$\geq \phi_t - \phi_{xx} - r_0 \phi$$

$$= \phi [\lambda c - \lambda^2 - r_0]$$

$$= 0$$



Subsol. For  $\underline{\alpha} \geq 0$ ,  $\underline{c} > 0$ ,  $\underline{r}_0 > 0$  and  $\underline{R} > 0$ , define

$$\psi(x,t) = \psi_{\alpha,c,r_0,R}(x,t) = \begin{cases} \exp(-\alpha t - \frac{c}{2}(x-ct)) \sin\left(\frac{x-ct}{R}\right), & 0 < \frac{x-ct}{R} < \pi \\ 0 & \text{otherwise.} \end{cases}$$



$$\alpha > -r_0 + \frac{c^2}{4}$$

Claim For  $\eta > 0$  such that  $\alpha \geq -r_0 + \frac{c^2}{4} + \frac{1}{R^2} + \eta$ ,

$(\eta\psi)_t - (\eta\psi)_{xx} - (\eta\psi)(r_0 - \eta\psi) \leq 0$  in  $\mathbb{R} \times (0, \infty)$  in the generalized sense.

Check In  $\{0 < \frac{x-ct}{R} < \pi\}$ ,

$$\begin{aligned} \psi_t - \psi_{xx} - r_0\psi &= -(\alpha + r_0)\psi + e^{-\alpha t - \frac{c}{2}(x-ct)} \left\{ \left[ \frac{c^2}{2} \sin(\cdot) - \frac{c}{R} \cos(\cdot) \right] - \left[ \frac{c^2}{4} \sin(\cdot) - \frac{c}{R} \cos(\cdot) - \frac{1}{R^2} \sin(\cdot) \right] \right\} \\ &= -(\alpha + r_0)\psi + \psi \left\{ \frac{c^2}{2} - \frac{c^2}{4} - \frac{1}{R^2} \right\} = \psi \left[ -\alpha - r_0 + \frac{c^2}{4} + \frac{1}{R^2} \right]. \end{aligned}$$

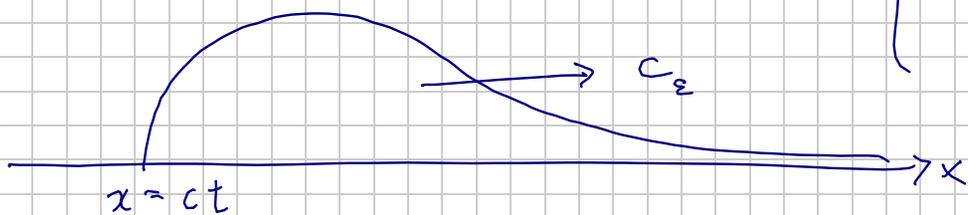
$$\underbrace{(\eta\psi)_t - (\eta\psi)_{xx} - \eta\psi(r_0 - \eta\psi)}_{\text{um}} = \eta\psi \left[ \underbrace{-\alpha - r_0 + \frac{c^2}{4} + \frac{1}{R^2}}_{\text{um}} + \eta\psi \right] \leq 0 \quad \boxed{0 \leq \psi \leq 1.}$$

Subsol Given  $\lambda \in (0, \sqrt{r_0})$  and any  $\varepsilon > 0$  suff small such that

$$\lambda < \sqrt{r_0 - \varepsilon} \quad \text{and} \quad 0 < \varepsilon < \frac{r_0 - \varepsilon}{\lambda} - \lambda$$

Let  $C = C_\varepsilon = \lambda + \frac{r_0 - \varepsilon}{\lambda}$ , then  $\varepsilon < C - 2\lambda$ .

Define  $p(x,t) = p_{r_0, \lambda, \varepsilon}(x,t) = \begin{cases} e^{-\lambda(x-ct)} - e^{-(\lambda+\varepsilon)(x-ct)} & \text{for } x-ct > 0 \\ 0 & \text{for } x-ct \leq 0. \end{cases}$



Note that  $\sup p \leq 1$ .

Claim For  $0 < \eta \leq \varepsilon$ ,  $(\eta p)_t - (\eta p)_{xx} - (\eta p)(r_0 - \eta p) \leq 0$ , in gen. sense.

Check  $p_t - p_{xx} - (r_0 - \varepsilon)p$

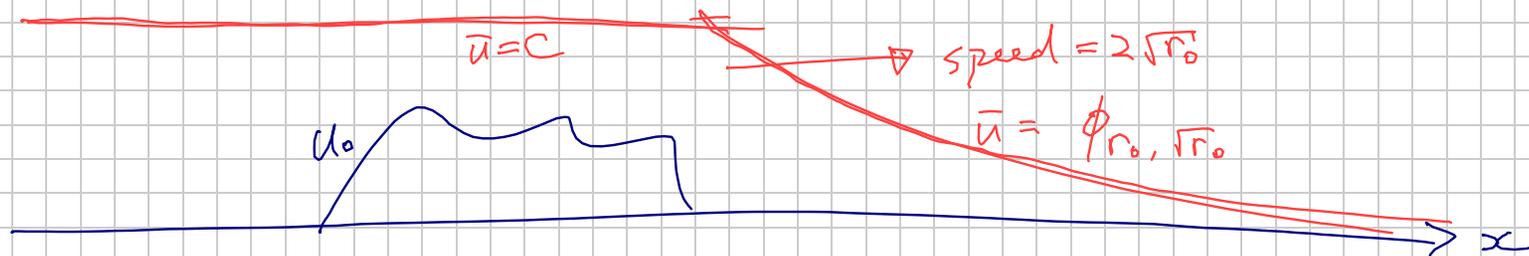
$$= e^{-\lambda(x-ct)} [c\lambda - \lambda^2 - r_0 + \varepsilon] - e^{-(\lambda+\varepsilon)(x-ct)} [c(\lambda+\varepsilon) - (\lambda+\varepsilon)^2 - r_0 + \varepsilon]$$

$$= -e^{-(\lambda+\varepsilon)(x-ct)} [c\varepsilon - 2\lambda\varepsilon - \varepsilon^2] = -e^{-(\lambda+\varepsilon)(x-ct)} \varepsilon [c - 2\lambda - \varepsilon] \leq 0$$

$$(\eta p)_t - (\eta p)_{xx} - \eta p(r_0 - \eta p) \leq \eta p(-\varepsilon + \eta p) \leq \eta p(-\varepsilon + \eta) \leq 0.$$

Pf of Thm A (a) :  $c > 2\sqrt{r_0} \Rightarrow \lim_{t \rightarrow \infty} \sup_{x > ct} |u(x,t)| = 0$ .

Consider the generalized supersolution  $\bar{u}(x,t) = \min \left\{ \sup_{\mathbb{R}} u_0, e^{-\sqrt{r_0}(x-2\sqrt{r_0}t)} \right\}$   
 WLOG, we may translate  $u_0$  to ensure  $0 \leq u_0(x) \leq \bar{u}(x,0)$



$$\Rightarrow 0 \leq u(x,t) \leq \bar{u}(x,t) \quad \forall x \in \mathbb{R}, t > 0$$

For  $c > 2\sqrt{r_0}$ ,

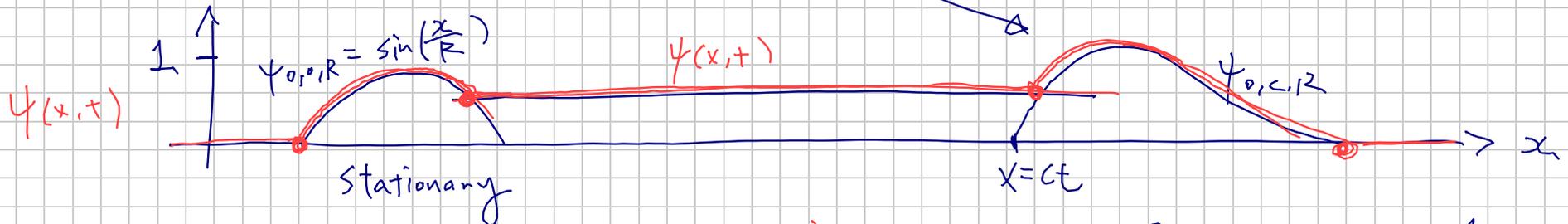
$$\lim_{t \rightarrow \infty} \sup_{x > ct} u(x,t) \leq \lim_{t \rightarrow \infty} \sup_{x > ct} \bar{u}(x,t) \leq \lim_{t \rightarrow \infty} e^{-\sqrt{r_0}(c-2\sqrt{r_0})t} = 0$$

This proves (a).

Pf of Thm A (b) :  $0 < c < 2\sqrt{r_0} \Rightarrow \liminf_{t \rightarrow \infty} \inf_{0 < x < ct} u(x,t) > 0$

Since  $0 < c < 2\sqrt{r_0}$ , we may choose  $R$  large and  $\eta$  small, (and  $\alpha = 0$ )  
 so that  $0 > -r_0 + \frac{c^2}{4} + \frac{1}{R^2} + \eta$  and  $0 > -r_0 + \frac{1}{R^2} + \eta$

$\Rightarrow \eta \psi_{0,0,R}$  and  $\eta \psi_{0,c,R}$  are subsol. by small



$\Rightarrow \eta \psi(x,t)$  ( $\psi$  defined in red) is subsol for  $\eta > 0$  small.

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Given a nonnegative, nontrivial sol  $u(x,t)$  of (F-KPP).

Strong max. prin.  $\Rightarrow u(x,t) > 0 \quad \forall x \in \mathbb{R}$ .

Choose  $\eta$  small enough s.t.  $u(x,t) \geq \eta \psi(x,t) \quad \forall x \in \mathbb{R}$ .

Comparison principle  $\Rightarrow u(x,t) \geq \eta \psi(x,t) \quad \forall x \in \mathbb{R}, \forall t \geq 1$

This proves (b).

## Spatially periodic environments

$$\begin{cases} u_t - u_{xx} = u(r(x) - u), \\ u(x, 0) \text{ compactly supported.} \end{cases}$$

If  $r(x) \equiv r_0$ , then  $\tilde{u} = e^{-\lambda x + \mu t}$   
 ( $\mu = \lambda^2 + r_0$ )

Solve  $\begin{cases} \tilde{u}_t - \tilde{u}_{xx} = r_0 \tilde{u} & x \in \mathbb{R}, t \in \mathbb{R} \\ \text{for each } t, \tilde{u}(x, t) \sim e^{-\lambda x} \text{ for } x \gg 1. \end{cases}$

$v = e^{\mu t} = e^{\lambda x} \tilde{u}$  solves  $\begin{cases} v_t - v_{xx} + 2\lambda v_x = (\lambda^2 + r_0)v & x \in \mathbb{R}, t \in \mathbb{R} \\ v(\cdot, t) \in L^\infty(\mathbb{R}) & t \in \mathbb{R} \end{cases}$

Note that  $\lambda^2 + r_0$  is the p.e.v. and  $c^* = \inf_{\lambda > 0} \frac{\lambda^2 + r_0}{\lambda}$ .

If  $r(x)$  is periodic in  $x$ , one uses  $e^{-\lambda x + \mu t} \psi(x) = e^{-\lambda(x - \frac{\mu(x)}{\lambda} t)} \psi(x)$

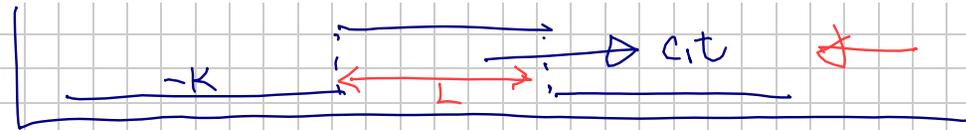
where  $\mu = \mu(\lambda)$  and  $\psi(x)$  is the p.e.v. and p.p.f. of

$\begin{cases} -\psi_{xx} + 2\lambda \psi_x = (\lambda^2 + r(x))\psi + \mu\psi & \text{in } \mathbb{R} \\ \psi \text{ is periodic in } x. \end{cases}$

This suggests that  $c_x = \inf_{\lambda > 0} \frac{\mu(\lambda)}{\lambda}$ .

[Freidlin Gärtner (1979); Weinberger (2002); Berestycki-Hamel-Nadin (2008)]

## § Shifting Environments



$$\begin{cases} u_t - u_{xx} = u(g(x-ct) - u) & x \in \mathbb{R}, t > 0 \\ u(x, 0) = u_0(x) \text{ is compactly supported in } \mathbb{R} \end{cases}$$

Motivated by the poleward movement of isotherms

[Potapov-Lewis (2004)] and [Berestycki-Diekmann-Nagelkerke-Zegeling (2009)]

considered the case  $v(x,t) - u = g(x-ct) - u = \begin{cases} 1-u & ct < x < ct+L \\ -k & \text{otherwise} \end{cases}$

Changing variable  $y = x - ct$ , we obtain

$$\tilde{u}_t - \tilde{u}_{yy} - c_1 \tilde{u}_y = \begin{cases} \tilde{u}(1-\tilde{u}) & 0 < y < L, t > 0 \\ -k\tilde{u} & y \notin [0, L], t > 0 \end{cases}$$

The long-time dynamics is equivalent to the bounded domain problem

$$\begin{cases} u_t - u_{yy} - c_1 u_y = u(1-u) & y \in [0, L], t > 0 \\ u_y - k_+ u = 0 & y = 0, t > 0 \\ u_y - k_- u = 0 & y = L, t > 0 \end{cases} \quad \text{where } k_{\pm} = \frac{-c_1 \pm \sqrt{c_1^2 + 4k}}{2}$$

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By lecture 1, the population can persist on the moving patch if and only if  $\mu_1 < 0$ , where  $\mu_1 = \mu_1(c_1, L, k)$

is the principal eigenvalue of 
$$\begin{cases} -\psi'' - c_1 \psi' = \psi + \mu_1 \psi & 0 < y < L \\ \psi'(0) - k_+ \psi(0) = \psi'(L) - k_- \psi(L) = 0 \end{cases}$$

Proposition (Berestycki et al.) For each  $0 < c_1 < 2$  and  $k > 0$ ,

there exists  $L_{\text{crit}} > 0$  such that the population persists iff

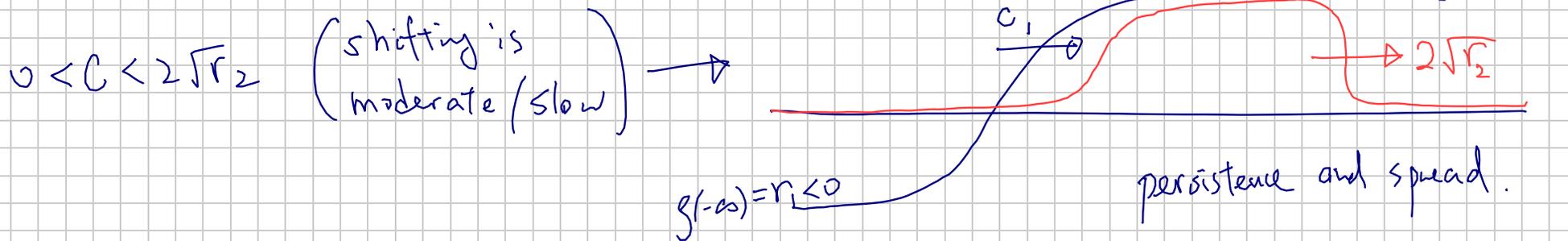
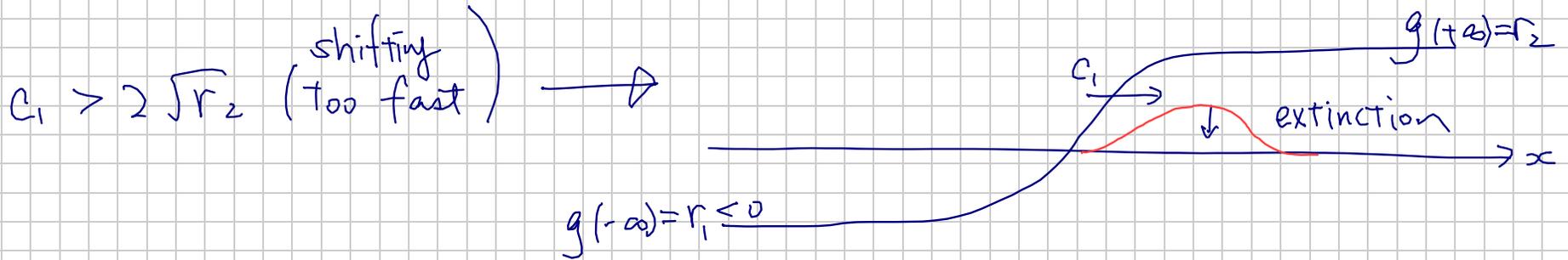
$$L > L_{\text{crit}} := \frac{1}{\sqrt{1 - \left(\frac{c_1}{2}\right)^2}} \arctan \left( \frac{2\sqrt{1 - \left(\frac{c_1}{2}\right)^2} \sqrt{\frac{1}{k} + \left(\frac{c_1}{2}\right)^2}}{1 - k - \frac{c_1^2}{2}} \right)$$

Another situation was considered in [Li-Bewick-Shang-Fapan (2014)]

Thm B  $r(x,t) = g(x-c_1 t)$ ,  $g$  monotone increasing,  $g(-\infty) = r_1 < 0 < g(+\infty) = r_2$

(a)  $c_1 > 2\sqrt{r_2} \Rightarrow$  (extinction)  $\lim_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} u(x,t) = 0$

(b)  $0 < c_1 < 2\sqrt{r_2} \Rightarrow$  (persistence + spreading at  $2\sqrt{r_2}$ )  $\left\{ \begin{array}{l} \lim_{t \rightarrow \infty} \sup_{x > (2\sqrt{r_2} + \varepsilon)t} u(x,t) = 0 \\ \liminf_{t \rightarrow \infty} \inf_{(c_1 + \varepsilon)t < x < (2\sqrt{r_2} - \varepsilon)t} u(x,t) > 0 \end{array} \right. \quad \forall \varepsilon > 0$



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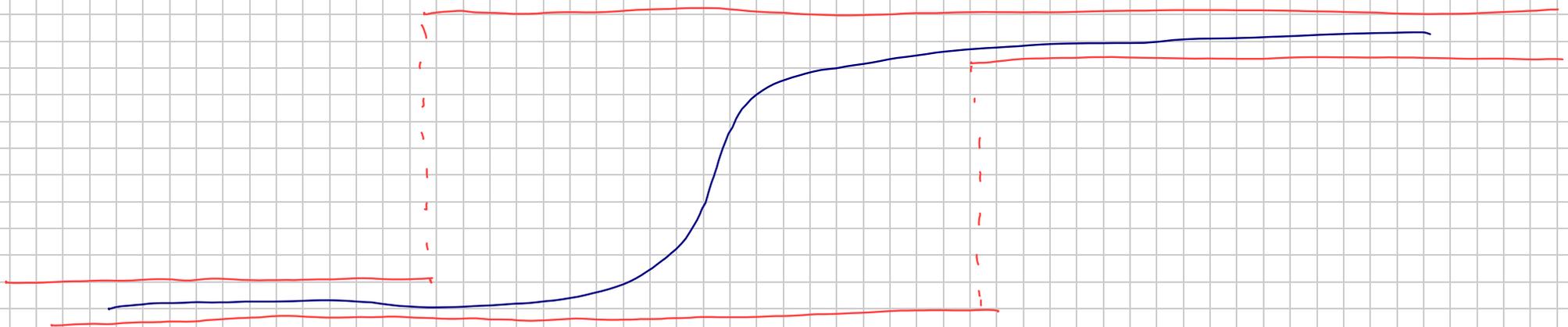
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We consider the special case  $r(x,t) = \begin{cases} r_2 & x \geq c_1 t \\ r_1 & x < c_1 t \end{cases}$   $r_1 < 0 < r_2$

In general,  $r(x,t) = g(x - c_1 t)$  can be approximated by similar step functions.



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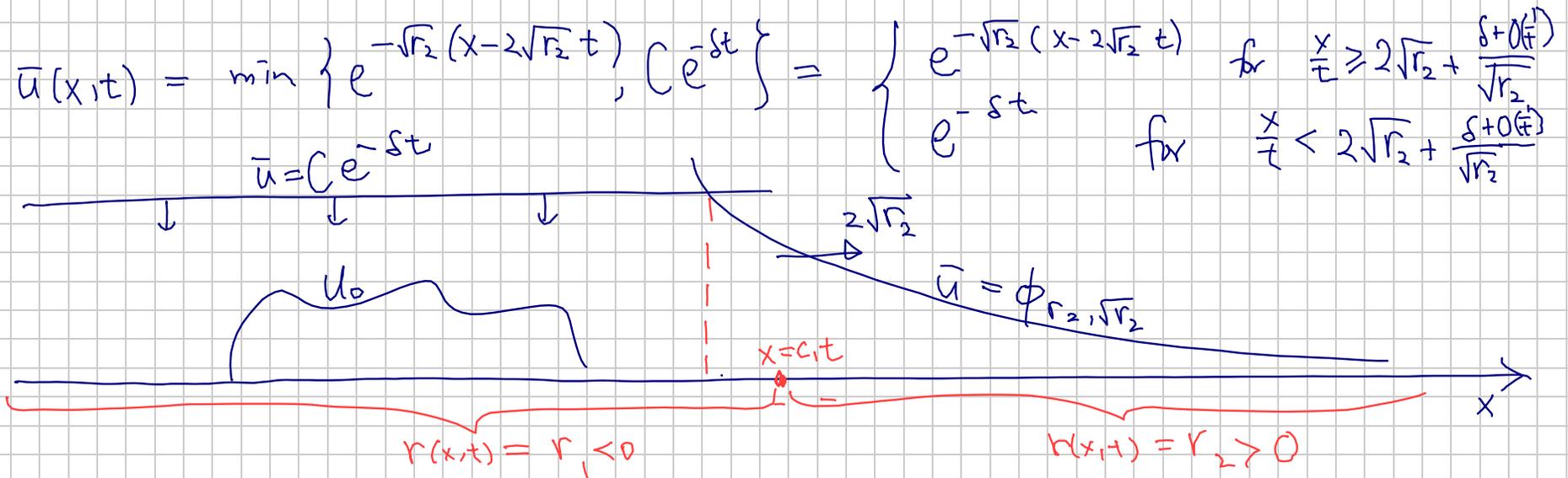
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In general,  $r(x,t) = g(x-c_1 t)$  can be approximated by similar step functions.

Pf of (a) Construct the supersolution. Let  $\delta = \min\{\sqrt{r_2}(c_1 - 2\sqrt{r_2}), -\frac{r_1}{2}\}$



Another situation was considered in [Li-Bewick-Shang-Fagan (2014)]

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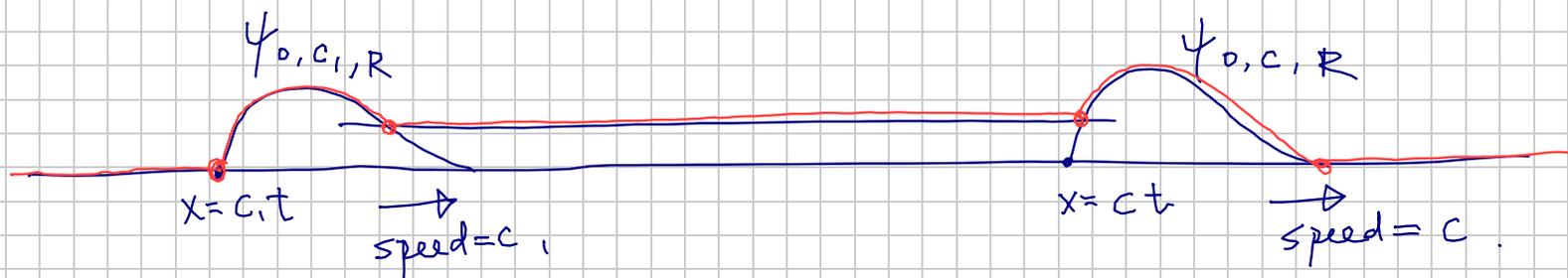
(a)  $c_1 > 2\sqrt{r_2} \Rightarrow$  (extinction)  $\lim_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} u(x,t) = 0$ .

(b)  $0 < c_1 < 2\sqrt{r_2} \Rightarrow$  (persistence + spreading at  $2\sqrt{r_2}$ )

$$\left\{ \begin{array}{l} \lim_{t \rightarrow \infty} \sup_{x > (2\sqrt{r_2} + \varepsilon)t} u(x,t) = 0 \quad \forall \varepsilon > 0 \\ \liminf_{t \rightarrow \infty} \inf_{(c_1 + \varepsilon)t < x < (2\sqrt{r_2} - \varepsilon)t} u(x,t) > 0 \quad \forall 0 < \varepsilon < 1. \end{array} \right.$$

Pf of (b) is similar as in  $v(x,t) \equiv v_0$ , let  $0 < c_1 < 2\sqrt{r_2}$

Fix  $c \in (c_1, 2\sqrt{r_2})$ , and  $R \gg 1$ , define  $\psi(x,t)$  by



Then for  $\eta > 0$  small,  $\underline{u}(x,t) = \eta \psi(x,t)$  is subsolution.

We omit the details.

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See also [T. Yi & Zhao (2020)] for generalization to monotone dynamical systems "sandwiched" between two limiting homogeneous KPP systems, where one is "positive" and the other one is "negative".

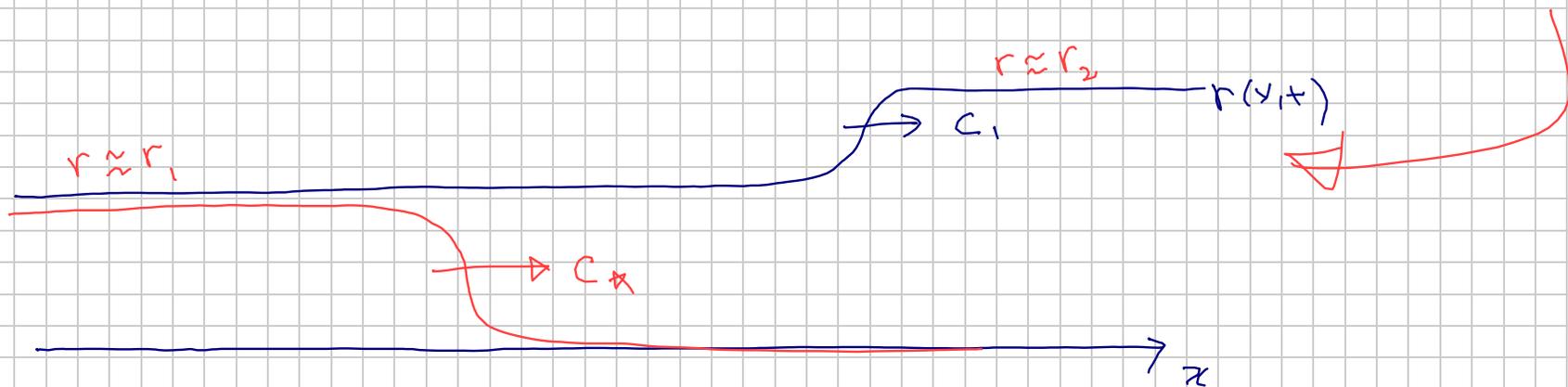
## Shifting positive environment and nonlocal pulling

Consider the case  $r(x,t) = g(x-c_1t)$ , where  $g$  is increasing,  
and  $0 < r_1 < r_2$ , where  $r_1 = g(-\infty)$ ,  $r_2 = g(+\infty)$ .

•  $c_* \in [2\sqrt{r_1}, 2\sqrt{r_2}]$

•  $c_1 = 0$  or small  $\rightarrow c_* = 2\sqrt{r_2}$

•  $c_1 \gg 1 \rightarrow c_* = 2\sqrt{r_1}$



## § Shifting positive environment and nonlocal pulling

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and  $0 < r_1 < r_2$ , where  $r_1 = g(-\infty)$ ,  $r_2 = g(+\infty)$ .

Thm C [L.-Yu (2021)]

$$c_x = \begin{cases} 2\sqrt{r_2} & \text{if } 0 \leq c_1 \leq 2\sqrt{r_2} \\ \frac{c_1}{2} - \sqrt{r_2 - r_2} + \frac{r_1}{\frac{c_1}{2} - \sqrt{r_2 - r_1}} & \text{if } 2\sqrt{r_2} < c_1 < 2(\sqrt{r_2 - r_1} + \sqrt{r_1}) \\ 2\sqrt{r_1} & \text{if } c_1 \geq 2(\sqrt{r_2 - r_1} + \sqrt{r_1}). \end{cases}$$

In cases 1 and 3,  $c_x$  is determined by the environment where the transition front is located.  $\rightarrow$  locally-pulled

In case 2,  $c_x$  is influenced by the speed of the shifting env.



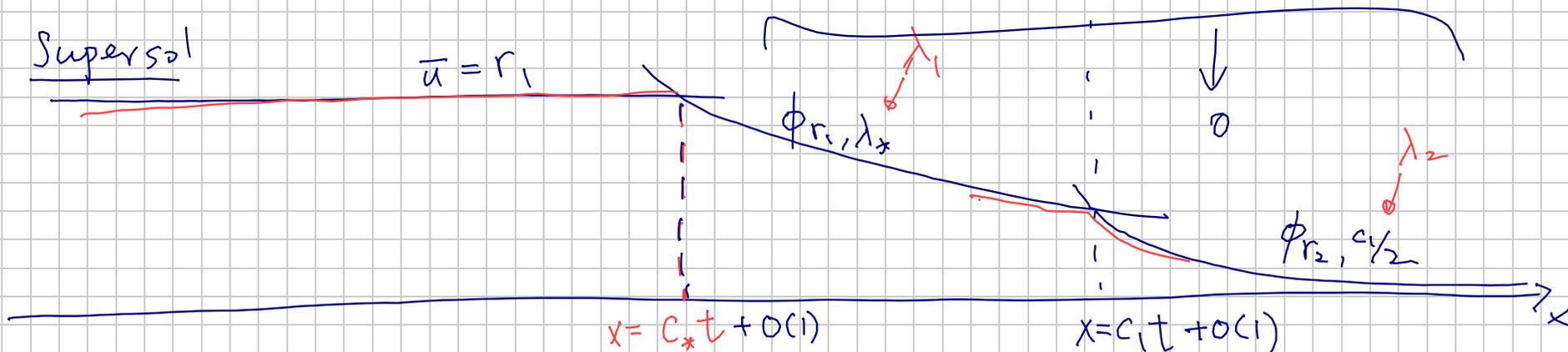
pf We only sketch the proof of the case  $2\sqrt{r_2} < c_1 < 2(\sqrt{r_2 - r_1} + \sqrt{r_1})$

$$r(-\infty, t) = r_1$$

$$r(+\infty, t) = r_2$$

Supersol

$$\bar{u} = r_1$$



where  $c_* = \lambda_* + \frac{r_1}{\lambda_*}$  and  $\lambda_* = \frac{c_1}{2} - \sqrt{r_2 - r_1} \in (0, \sqrt{r_1})$

check at  $\underline{x = c_1 t}$ ,

$$\left\{ \begin{array}{l} 0 > \partial_x \phi_{r_1, \lambda_*} \geq \partial_x \phi_{r_2, c_1/2} \\ \phi_{r_1, \lambda_*} = \phi_{r_2, c_1/2} \end{array} \right. \quad (\text{exercise}).$$

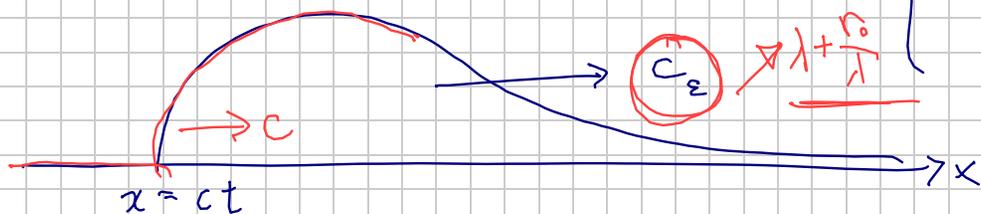
Remark  $(\lambda_1, \lambda_2) = (\lambda_*, c_1/2)$  is "optimized" among all "admissible" choices of  $\lambda_1 \in (0, \sqrt{r_1}]$  and  $\lambda_2 \in (0, \sqrt{r_2}]$  to produce the slowest possible supersol  $\bar{u}(x, t)$ .

Subsol Given  $\lambda \in (0, \sqrt{r_0})$  and any  $\varepsilon > 0$  suff small such that

$$\lambda < \sqrt{r_0 - \varepsilon} \quad \text{and} \quad 0 < \varepsilon < \frac{r_0 - \varepsilon}{\lambda} - \lambda$$

Let  $C = C_\varepsilon = \lambda + \frac{r_0 - \varepsilon}{\lambda}$ , then  $\varepsilon < C - 2\lambda$ .

Define  $p(x, t) = p_{r_0, \lambda, \varepsilon}(x, t) = \begin{cases} e^{-\lambda(x-ct)} - e^{-(\lambda+\varepsilon)(x-ct)} & \text{for } x-ct > 0 \\ 0 & \text{for } x-ct \leq 0. \end{cases}$



Note that  $\sup p \leq 1$ .

Claim For  $0 < \eta \leq \varepsilon$ ,  $(\eta p)_t - (\eta p)_{xx} - (\eta p)(r_0 - \eta p) \leq 0$ , in gen. sense.

Check  $p_t - p_{xx} - (r_0 - \varepsilon)p$

$$= e^{-\lambda(x-ct)} [c\lambda - \lambda^2 - r_0 + \varepsilon] - e^{-(\lambda+\varepsilon)(x-ct)} [c(\lambda+\varepsilon) - (\lambda+\varepsilon)^2 - r_0 + \varepsilon]$$

$$= -e^{-(\lambda+\varepsilon)(x-ct)} [c\varepsilon - 2\lambda\varepsilon - \varepsilon^2] = -e^{-(\lambda+\varepsilon)(x-ct)} \varepsilon [c - 2\lambda - \varepsilon] \leq 0$$

$$(\eta p)_t - (\eta p)_{xx} - \eta p(r_0 - \eta p) \leq \eta p(-\varepsilon + \eta p) \leq \eta p(-\varepsilon + \eta) \leq 0.$$

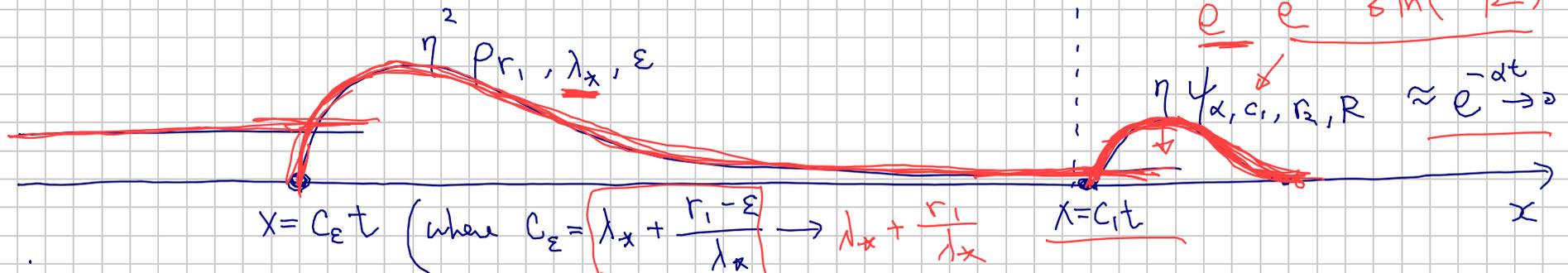
pf We only sketch the proof of the case  $2\sqrt{r_2} < c_1 < 2(\sqrt{r_2 - r_1} + \sqrt{r_1})$

$r(-\infty, t) = r_1$

$\rightarrow c_1$

$r(+\infty, t) = r_2$

Subsolution Define  $\psi(x, t)$  by



$x = c_\varepsilon t$  (where  $c_\varepsilon = \lambda_x + \frac{r_1 - \varepsilon}{\lambda_x} \rightarrow \lambda_x + \frac{r_1}{\lambda_x}$ )  $x = c_1 t$

Fix ①  $\lambda_x = \frac{c_1}{2} - \sqrt{r_2 - r_1} \in (0, \sqrt{r_1})$  and  $\varepsilon > 0$  small  $\implies p_{r_1, \lambda_x, \varepsilon}$  is subsol.

②  $p_{r_1, \lambda_x, \varepsilon} \Big|_{x=c_1 t} = \exp(-\lambda_x(c_1 - c_\varepsilon)t) (1 + o(1)) \rightarrow$  take  $\alpha = \lambda_x(c_1 - c_\varepsilon)$ .

③ Verify that  $\alpha > -r_2 + \frac{c_1^2}{4}$  (exercise)

then choose  $R \gg 1$  s.t.  $\alpha > -r_2 + \frac{c_1^2}{4} + \frac{1}{R^2}$

$\implies$  For  $\varepsilon, \eta > 0$  small,  $\eta^2 p_{r_1, \lambda_x, \varepsilon}$  and  $\eta \psi_{\alpha, c_1, r_2, R}$  are subsol.

$\implies$  spreading speed  $\geq c_2 \quad \forall \varepsilon > 0$

## Shifting positive environment and nonlocal pulling

Consider the case  $r(x,t) = g(x - c_1 t)$ , where  $g$  is increasing,  
and  $0 < r_1 < r_2$ , where  $r_1 = g(-\infty)$ ,  $r_2 = g(+\infty)$ .

Thm C

$$c_x = \begin{cases} 2\sqrt{r_2} & \text{if } 0 \leq c_1 \leq 2\sqrt{r_2} \\ \frac{c_1}{2} - \sqrt{r_2 - r_2} + \frac{r_1}{2 - \sqrt{r_2 - r_1}} & \text{if } 2\sqrt{r_2} < c_1 < 2(\sqrt{r_2 - r_1} + \sqrt{r_1}) \\ 2\sqrt{r_1} & \text{if } c_2 \geq 2(\sqrt{r_2 - r_1} + \sqrt{r_1}). \end{cases}$$

- Remarks
1. The phenomenon was first found by [Holzer-Scheel SIMA 2014],  
by looking at the moving coordinate  $y = x - c_1 t$  and using eigenvalue method.
  2. The name "nonlocal-pulling" was introduced in [Girardin-Lam 2019],  
where it is treated by super/subsol method.
  3. Using Hamilton-Jacobi equations, one can treat the  
general case:  $r\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon}\right) \xrightarrow{\varepsilon \rightarrow 0} R\left(\frac{x}{t}\right)$   
for any piecewise constant  $R$ . See [L-Yu] for  
precise conditions.
  4. See also [Berestycki-Nadin, Mem. AMS (2022)].

Remarks 4. See [Faye-Giulietti-Holzer, DCDS-s (2022)]  
for the case of shifting diffusivity.

5. In [Berestycki-Nadin, Mem. AMS (2022)],  
the Hamilton-Jacobi Method was combined with  
homogenization ideas to treat very general heterogeneity.

We close by briefly describing the Hamilton-Jacobi Approach.

Consider  $u^\varepsilon(x,t) = u\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon}\right)$  and  $r^\varepsilon(x,t) = r\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon}\right) \rightarrow \begin{cases} r_2 & \frac{x}{\varepsilon} > c, \\ r_1 & \frac{x}{\varepsilon} < c. \end{cases}$

Then 
$$\begin{cases} \partial_t u^\varepsilon - \varepsilon \partial_{xx} u^\varepsilon = \frac{1}{\varepsilon} u^\varepsilon (r^\varepsilon - u^\varepsilon) \\ u^\varepsilon(x,0) = u_0\left(\frac{x}{\varepsilon}\right) \end{cases} \quad \begin{matrix} x \in \mathbb{R}, t > 0 \\ x \in \mathbb{R} \end{matrix}$$



WKB- Ansatz  $W^\varepsilon(x,t) = -\varepsilon \log u^\varepsilon(x,t) \Leftrightarrow u^\varepsilon(x,t) = \exp\left(-\frac{W^\varepsilon(x,t)}{\varepsilon}\right)$

then 
$$\begin{cases} \partial_t W^\varepsilon - \varepsilon \partial_{xx} W^\varepsilon + |\partial_x W^\varepsilon|^2 + r^\varepsilon - u^\varepsilon = 0 \\ W(x,0) = \begin{cases} 0 & x < 0 \\ \infty & x > 0 \end{cases} \end{cases} \quad x \in \mathbb{R}, t > 0$$

Suppose  $W^\varepsilon(t,x) \rightarrow w(t,x)$  locally uniformly,

then  $w$  can be determined as follows:

$w(x,t) = \max\{J(x,t), 0\}$ , where  $J$  is the unique viscosity sol of 
$$\begin{cases} \partial_t J + |\partial_x J|^2 + r_2 - (r_2 - r_1) \chi_{\frac{1}{2}x \leq ct} = 0 \\ J(x,0) = \begin{cases} 0 & x < 0 \\ \infty & x > 0 \end{cases} \end{cases} \quad \text{in } \mathbb{R} \times (0, \infty)$$

WKB- Ansatz  $w^\varepsilon(x,t) = -\varepsilon \log u^\varepsilon(x,t) \iff u^\varepsilon(x,t) = \exp\left(-\frac{w^\varepsilon(x,t)}{\varepsilon}\right)$

$w(t,x) = \lim_{\varepsilon \rightarrow 0} w^\varepsilon(x,t)$  can be determined as follows:

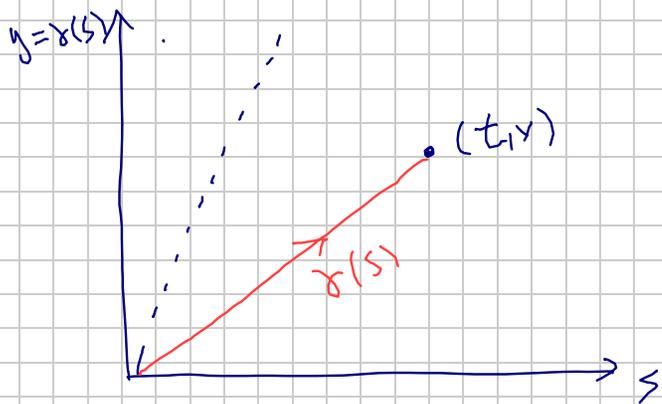
$w(x,t) = \max\{J(x,t), 0\}$ , where  $J$  is the unique viscosity sol of

$$\begin{cases} \partial_t J + |\partial_x J|^2 + r_2 - (r_2 - r_1) \chi_{\{x \leq ct\}} = 0 \\ J(x,0) = \begin{cases} 0 & x > 0 \\ \infty & x < 0 \end{cases} \end{cases} \text{ in } \mathbb{R} \times (0, \infty)$$

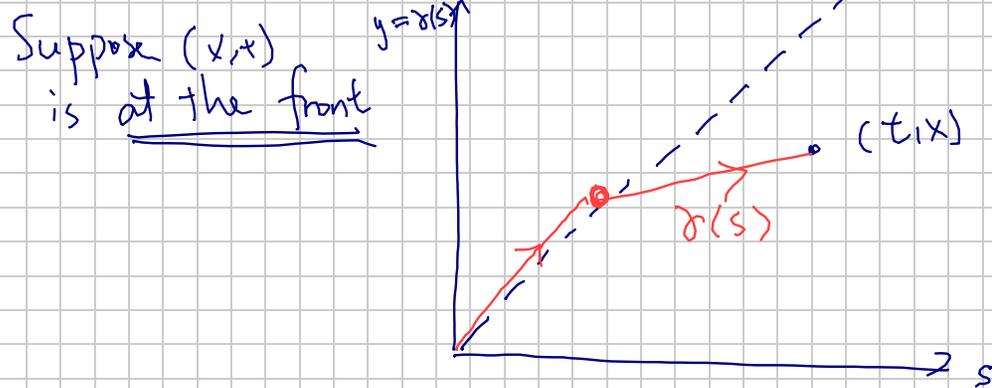
By [Evans-Souganidis (1989)],  $J(x,t)$  can be determined by an optimization prob.

$$J(x,t) = \inf_{\substack{\delta \in W^{1,\infty}([0,t]) \\ \delta(t)=x, \delta(0)=0}} \left\{ \int_0^t \frac{|\dot{\delta}(s)|^2}{4} - r_2 + (r_2 - r_1) \chi_{\{\delta(s) \leq cs\}} ds \right\}$$

when  $C_1$  is too large



when  $C_1$  is not too large



In fact,

$$J(x,t) = \begin{cases} \frac{t}{4} \left( \frac{x^2}{t^2} - 4r_2 \right) & \text{for } \frac{x}{t} \geq c_1 \\ \left( \frac{c_1}{2} - \sqrt{r_2 - r_1} \right) (x - c_2 t) & \text{for } c_1 - 2\sqrt{r_2 - r_1} \leq \frac{x}{t} < c_1 \\ \frac{t}{4} \left( \frac{x^2}{t^2} - 4r_1 \right) & \text{for } 0 \leq \frac{x}{t} < c_1 - 2\sqrt{r_2 - r_1} \\ -tr_1 & \end{cases}$$

See [Lin-Lin-L., DCDS-A (2020)] for explicit calculations.

→ Spreading speed is one of  $2\sqrt{r_2}$ ,  $2\sqrt{r_1}$ , or  $c_2$ .

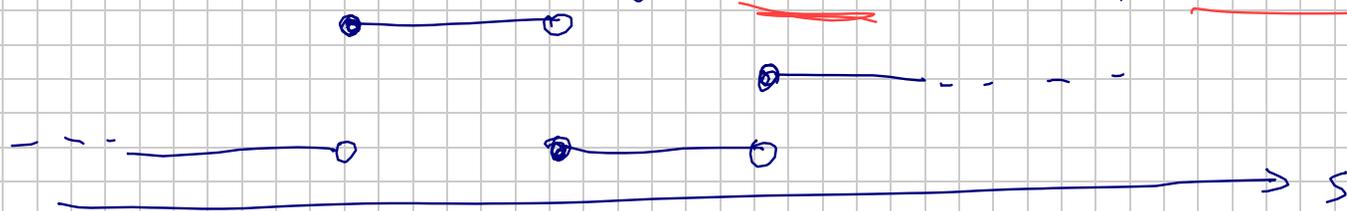
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- More recently, [Berestycki-Nadin, Mem. AMS, in press] applied the HJ approach, where the Hamiltonian is defined by homogenization ideas, to treat very general heterogeneous environments.

- In [L., -Yu (2021), submitted], we used the theory of HJ with discontinuous Hamiltonian to treat general shifting environments:

where  $r\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon}\right) \rightarrow \underline{R}\left(\frac{x}{\varepsilon}\right)$ ,

with  $s \mapsto R(s)$  being monotone, or piecewise constant...



- For locked waves, see [Berestycki-Fang, J.D.E. (2018)].
- Entire solutions?