

Physics 5300, Theoretical Mechanics Spring 2015

Quiz 2 Solutions

Given: Friday Jan 23

Problem 1 Write down the potential energy $U(\phi)$ of a simple pendulum (mass m , length l) in terms of the angle ϕ between the pendulum and the vertical. (Choose the zero of U at the bottom.) Show that for small angles, U has the Hooke law form $const + \frac{1}{2}kx^2$. What is k ?

Solution: The height of the pendulum above its lowest point is given by

$$h = l - l \cos \phi = l(1 - \cos \phi) \quad (1)$$

Thus we have

$$U = mgh = mgl(1 - \cos \phi) \quad (2)$$

We have

$$\cos \phi = 1 - \frac{\phi^2}{2!} + \dots \quad (3)$$

Thus we get

$$U = mg \frac{\phi^2}{2} \quad (4)$$

Writing this as $\frac{1}{2}k\phi^2$, we get

$$k = mgl \quad (5)$$

Problem 2 A mass on the end of a spring is oscillating with an angular frequency ω . At $t = 0$, its position is $x_0 > 0$ and I give it a kick so that it moves back towards the origin and executes simple harmonic motion with amplitude $2x_0$. Find its position as a function of time in the form

$$x(t) = A \cos(\omega t - \delta) \quad (6)$$

Solution: We have

$$x(t) = A \cos(\omega t - \delta) \quad (7)$$

At $t = 0$, the position is x_0 . Thus

$$x_0 = A \cos(-\delta) = A \cos \delta \quad (8)$$

The amplitude is $2x_0$, thus

$$A = 2x_0 \quad (9)$$

Thus

$$\cos \delta = \frac{x_0}{2x_0} = \frac{1}{2} \quad (10)$$

Thus

$$\delta = \pm \frac{\pi}{3} \quad (11)$$

These two choices give

$$x = 2x_0 \cos(\omega t + \frac{\pi}{3}) \quad (12)$$

and

$$x = 2x_0 \cos(\omega t - \frac{\pi}{3}) \quad (13)$$

respectively. Now we compute the velocity at $t = 0$. In the first case we have

$$\dot{x}(t = 0) = -2x_0\omega \sin(\frac{\pi}{3}) \quad (14)$$

while in the second case we have

$$\dot{x}(t = 0) = -2x_0\omega \sin(-\frac{\pi}{3}) = 2x_0\omega \sin(\frac{\pi}{3}) \quad (15)$$

We are given that this initial velocity is negative (since it is towards the origin). Thus we must take the first possibility, and we get

$$x(t) = 2x_0 \cos(\omega t + \frac{\pi}{3}) \quad (16)$$