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// file: eigen_test.cpp
//
// Program to test the GSL eigenvalue/eigenvector routines
//
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//
// Revision history:
//   01/04/04  original version, translated from eigen_test.cpp
//
// Notes:
// * Uses the GSL functions for computing eigenvalues
//   and eigenvectors of matrices.  The basic flowchart is:
//   * define names for matrices and vectors
//   * allocate space for these matrices and vector
//   * load the matrix to be diagonalized (pointed to by Amat_ptr)
//   * find the eigenvalues and eigenvectors with gsl_eigen_symmv
//   * sort the results and print them out
// * Based on the documentation for the GSL library under
//   "Eigensystems" and Chap. 15 of "Computational Physics"
//   by Landau and Paez.
// * As a convention (advocated in "Practical C"), we'll append
//   "_ptr" to all pointers.
// * We've added two calls to "clock" to time the calculation.
//
// To do:
// * Output to a file, suitable for plotting
//
//*****
// include files
#include <iostream>          // note that .h is omitted
#include <iomanip>           // note that .h is omitted
using namespace std;
#include <time.h>
#include <gsl/gsl_eigen.h>  // include the appropriate GSL header file

//***** main program *****
int
main ()
{
  clock_t start, end;      // start and stop times
  int dimension;          // dimension of the matrices and vectors
  double hilbert;         // an entry in a Hilbert matrix

  gsl_matrix *Amat_ptr;    // original gsl matrix to process
  gsl_vector *Eigval_ptr;  // gsl vector with eigenvalues
  gsl_matrix *Eigvec_ptr;  // gsl matrix with eigenvectors
  gsl_eigen_symmv_workspace *worksp; // the workspace for gsl

  // the following two objects are for output only
  double eigenvalue;      // one of the eigenvalues of the matrix
  gsl_vector *eigenvector_ptr; // one of the eigen vectors of the matrix

  // pick the dimension of the matrix
  cout << "Enter the dimension of the matrix: ";
  cin >> dimension;

  // allocate space for the vectors, matrices, and workspace
  Amat_ptr = gsl_matrix_alloc (dimension, dimension);
  Eigval_ptr = gsl_vector_alloc (dimension);
  Eigvec_ptr = gsl_matrix_alloc (dimension, dimension);
  worksp = gsl_eigen_symmv_alloc (dimension);
  eigenvector_ptr = gsl_vector_alloc (dimension);
  eigenvalue = 0;

  // Load the Hilbert matrix pointed to by Amat_ptr
  for (int i = 0; i < dimension; i++)
  {

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    for (int j = 0; j < dimension; j++)
    {
        hilbert = 1. / ((float) (i + j + 1)); // i, j start at 0
        gsl_matrix_set (Amat_ptr, i, j, hilbert);
    }
}

// Find the eigenvalues and eigenvectors of the real, symmetric
// matrix pointed to by Amat_ptr.  It is partially destroyed
// in the process.  The eigenvectors are pointed to by
// Eigvec_ptr and the eigenvalues by Eigval_ptr.

start = clock ();        // start the clock to time the next routine
gsl_eigen_symmv (Amat_ptr, Eigval_ptr, Eigvec_ptr, worksp);
end = clock ();          // stop the clock and print the elapsed time

cout << " Finding the eigenvalues/vectors took " << fixed
      << setprecision(3)
      << (double) (end - start) / (double) CLOCKS_PER_SEC
      << " seconds\n";

// sort the eigenvalues and eigenvectors in ascending order
gsl_eigen_symmv_sort (Eigval_ptr, Eigvec_ptr, GSL_EIGEN_SORT_ABS_ASC);

// print out the results
// comment starting here when running large matrices
for (int i = 0; i < dimension; i++)
{
  eigenvalue = gsl_vector_get (Eigval_ptr, i);
  gsl_matrix_get_col (eigenvector_ptr, Eigvec_ptr, i);

  cout << "eigenvalue=" << scientific << eigenvalue << endl;

  cout << "eigenvector=\n";
  for (int j = 0; j < dimension; j++)
  {
    cout << scientific << gsl_vector_get (eigenvector_ptr, j) << endl;
  }
}
// end the comment here when running large matrices

// free the space used by the vector and matrices and workspace
gsl_matrix_free (Eigvec_ptr);
gsl_vector_free (Eigval_ptr);
gsl_matrix_free (Amat_ptr);
gsl_vector_free (eigenvector_ptr);
gsl_eigen_symmv_free (worksp);

return (0);              // successful completion
}

//*****

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