# LING3701/PSYCH3371: Lecture Notes 9 Syntactic Grammars for Human Languages

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### 9.1 We can use rules to model human languages like English

Human languages have rich category types, that can be seen in conjunctions [Sag et al., 1985].

First, observe that natural languages use different argument structures for different verbs:

- They sleep. one argument ahead (intransitive)
- They find pets. one argument ahead and one argument behind (transitive)
- They give people pets. one argument ahead, two arguments behind (ditransitive)

Next, observe natural languages *coordinate* conjunctions (combine like types):  $\langle \alpha \rangle \rightarrow \langle \alpha \rangle$  and  $\langle \alpha \rangle$ .

- [ $_{\beta}$  [ $_{\beta}$  They sleep] and [ $_{\beta}$  they find pets]]. sounds ok ( $\beta$  is sentence)
- They find [ $\gamma$  [ $\gamma$  people] and [ $\gamma$  pets]]. sounds ok ( $\gamma$  is noun phrase)
- \*They find [ $\gamma$  [ $\beta$  they sleep] and [ $\gamma$  pets]]. sounds wrong; conjuncts must match

Now, allowable conjunctions give us insight into the category structure of language:

- They [ $_{\delta}$  [ $_{\delta}$  sleep] and [ $_{\delta}$  find pets]]. sounds ok ( $\delta$  is verb phrase)
- They  $[\eta [\eta \text{ find}] \text{ and } [\eta \text{ give people}]]$  pets. sounds ok (but what's  $\eta$ ?)

Transitive verbs (find) match type with ditransitive verb + indirect object (give people)! Both lack argument ahead and behind – it seems types are defined by missing arguments!

## 9.2 Formal rules [Ajdukiewicz, 1935, Bar-Hillel, 1953]

Formalize set of categories C as follows – clauses with various unmet requirements:

- 1. every U is in C, for some set U of primitive categories;
- 2. every  $C \times O \times C$  is in C, for some set O of type-combining operators;
- 3. nothing else is in C

Define primitive categories  $U = \{N, V\}$ :

• N: noun-headed category with no missing arguments (noun phrase)

• V: verb-headed category with no missing arguments (sentence)

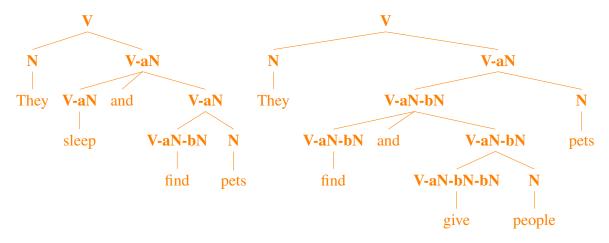
### Define type-combining operators $O = \{-a, -b\}$ :

- $\langle \alpha \mathbf{a}\beta \rangle$ :  $\alpha$  lacking  $\beta$  argument ahead (e.g. V-aN for intransitive  $\delta$  above)
- $\langle \alpha \mathbf{b}\beta \rangle$ :  $\alpha$  lacking  $\beta$  argument behind (e.g. V-aN-bN for transitive  $\eta$  above)

Now we can define **'context-free' rules** *R* over these categories:

- $\langle \alpha \rangle \rightarrow \langle \beta \rangle \langle \alpha \mathbf{a} \beta \rangle$ : argument attachment ahead
- $\langle \alpha \rangle \rightarrow \langle \alpha \text{-} \mathbf{b} \beta \rangle \langle \beta \rangle$ : argument attachment behind
- $\langle \alpha \rangle \rightarrow \langle \alpha \rangle$  and  $\langle \alpha \rangle$ : conjunction

These three rules model all of the above sentences:



Also note that the parents in these rules all have simpler types than the children. This means for any lexicon (constraining types at tree leaves), the set of categories C is finite.

#### 9.3 Non-local rules [Gazdar et al., 1985, Pollard and Sag, 1994]

Natural languages may also use non-local dependencies.

In English, these show up in topicalization, which seem to use a gap '\_' at one argument:

• These pets, you say they found \_.

These coordinate as well, but our test shows categories with gaps differ from those without:

- These pets, you [ $_{\delta}$  [ $_{\delta}$  say they found \_] and [ $_{\delta}$  think \_ gave people joy]]. sounds ok
- \*These pets, you [ $_{\delta}$  [ $_{V-aN}$  say they found pets] and [ $_{\delta}$  think \_ gave people joy]]. wrong

We can model this by adding a **new type-combining operator** for non-local dependencies:

•  $\langle \alpha - \mathbf{g}\beta \rangle$ :  $\alpha$  lacking non-local  $\beta$  argument (e.g. V-aN-gN for intransitive  $\delta$  above) and adding rules to **introduce** non-local dependencies:

•  $\langle \alpha - \mathbf{g}\beta \rangle \rightarrow \langle \alpha - \mathbf{a}\beta \rangle$ : introduce non-local dependency to argument ahead

•  $\langle \alpha - \mathbf{g}\beta \rangle \rightarrow \langle \alpha - \mathbf{b}\beta \rangle$ : introduce non-local dependency to argument behind

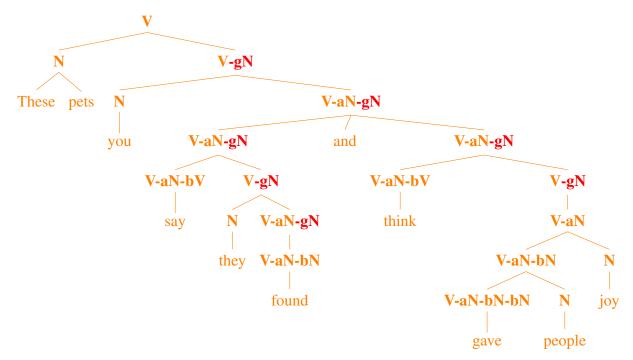
and adding rules to **attach** non-local dependencies:

•  $\langle \alpha \rangle \rightarrow \langle \beta \rangle \langle \alpha \textbf{-g} \beta \rangle$ : non-local dependency attachment

and modifying existing rules to **propagate** non-local dependencies  $\psi_m \in \{-\mathbf{g}\} \times C$ :

- $\langle \alpha \psi_{1..M} \rangle \rightarrow \langle \beta \psi_{1..m} \rangle \langle \alpha \cdot \mathbf{a} \beta \psi_{m+1..M} \rangle$ : argument attachment ahead, with propagation
- $\langle \alpha \psi_{1..M} \rangle \rightarrow \langle \alpha \cdot \mathbf{b} \beta \psi_{1..m} \rangle \langle \beta \psi_{m+1..M} \rangle$ : argument attachment behind, with propagation

Here's the analysis:



Note that M above is unbounded, so our rules no longer guarantee a finite set of categories.

(Any number of arguments may be extracted and propagated up from children.)

Some use evidence like this to argue language isn't context-free but mildly context-sensitive [Shieber, 1985, Joshi, 1985, Steedman, 2000].

In practice, though, we can just constrain category sets to combinations seen in training data.

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