

CONNECTIONS ON ASSOCIATED VECTOR BUNDLES

Ivo Terek

Quick summary on G -torsors, associated vector bundles and associated connections. Discussion on direct definition of ∇^A in terms of local gauges; independence of local gauge. Lastly, R^{∇^A} versus F_A .

1 G -torsors

Let's quickly introduce the language of G -torsors, as it will be useful for the discussion later.

Definition 1

A set X is called a (left) G -torsor if it is equipped with a free and transitive action $G \curvearrowright X$. Equivalently, it is a G -set for which the enriched map

$$G \times X \ni (x, g) \mapsto (x, g \cdot x) \in X \times X$$

is an isomorphism.

Remark. Right G -torsors are defined on a similar way and the theory is unchanged, as a left G -torsor can be changed into a right G -torsor, and vice-versa. Affine spaces with translation vector space V are nothing more than right V -torsors.

Given $x', x'' \in X$, there is a unique element $g \in G$ such that $x'' = g \cdot x'$. We will denote it by x''/x' . So, on a G -torsor, one can "multiply" elements of G by elements of X , but one cannot multiply two elements of X . What one can do, instead, is to "divide" elements of X to obtain elements in G . The division notation is precise, because all algebraic manipulations you think should hold, will hold.

Proposition 1

Let X be a G -torsor, $x', x'', x''' \in X$ and $g \in G$. Then:

(a) $\frac{x'''}{x''} \cdot \frac{x''}{x'} = \frac{x'''}{x'}$.

(b) $\frac{x'}{x'} = e$.

$$(c) \left(\frac{x''}{x'} \right)^{-1} = \frac{x'}{x''}.$$

$$(d) \frac{g \cdot x''}{x'} = g \cdot \frac{x''}{x'}.$$

$$(e) \frac{x''}{g \cdot x'} = \frac{x''}{x'} \cdot g^{-1}.$$

Proof:

(a) Compute

$$\left(\frac{x'''}{x''} \cdot \frac{x''}{x'} \right) \cdot x' = \frac{x'''}{x''} \cdot \left(\frac{x''}{x'} \cdot x' \right) = \frac{x'''}{x''} \cdot x'' = x''''.$$

(b) Obvious.

(c) Compute

$$\left(\frac{x''}{x'} \right)^{-1} \cdot x'' = \left(\frac{x''}{x'} \right)^{-1} \cdot \left(\frac{x''}{x'} \cdot x' \right) = \left(\left(\frac{x''}{x'} \right)^{-1} \cdot \left(\frac{x''}{x'} \right) \right) \cdot x' = e \cdot x' = x'.$$

(d) Compute

$$\left(g \cdot \frac{x''}{x'} \right) \cdot x' = g \cdot \left(\frac{x''}{x'} \cdot x' \right) = g \cdot x''.$$

(e) Use the previous items:

$$\frac{x''}{g \cdot x'} = \left(\frac{g \cdot x'}{x''} \right)^{-1} = \left(g \cdot \frac{x'}{x''} \right)^{-1} = \frac{x''}{x'} \cdot g^{-1}.$$

□

2 Review

We work on the smooth category. Let $\pi: P \rightarrow M$ be a principal G -bundle, and $\rho: G \rightarrow \text{GL}(V)$ be a representation of the Lie group G on a vector space V . Given $g \in G$ and $v \in V$, we'll write gv for $\rho(g)v$. Then we have a right action $(P \times V) \circlearrowright G$ given by $(p, v) \cdot g = (p \cdot g, g^{-1}v)$. The quotient $E(P, \rho) = P \times_{\rho} V \doteq (P \times V)/G$ (written as E , for short) turns out to be a manifold. Elements of E are equivalence classes $[p, v]$, subject to the rule $[p \cdot g, v] = [p, gv]$. Since the action $P \circlearrowright G$ is fiber-preserving, the projection $P \times V \ni (p, v) \mapsto \pi(p) \in M$ induces a projection $\pi_E: E \rightarrow M$. The fibers $\pi_E^{-1}(x)$ will be vector spaces, all isomorphic to V , by using that each P_x is a G -torsor. Namely, we write

$$[p', v'] + [p'', v''] \doteq \left[p', v' + \frac{p''}{p'} v'' \right] \quad \text{and} \quad \lambda [p, v] \doteq [p, \lambda v].$$

The scalar multiplication doesn't require explanation, but for the sum, the idea is that one cannot add (p', v') and (p'', v'') if $p' \neq p''$. In the quotient, if $p', p'' \in P_x$, we may write that

$$[p'', v''] = \left[p' \frac{p''}{p'}, v'' \right] = \left[p', \frac{p''}{p'} v'' \right],$$

and this last expression is admissible to add with $[p', v']$.

Proposition 2

The above operations are well-defined.

Proof: Let's verify that the sum is well-defined first. Replace p' and v' with $p' \cdot g'$ and $(g')^{-1}v'$, and similarly for p'' and v'' . Then compute

$$\begin{aligned} \left[p' \cdot g', (g')^{-1}v' + \frac{p'' \cdot g''}{p' \cdot g'} (g'')^{-1}v'' \right] &= \left[p' \cdot g', (g')^{-1}v' + (g')^{-1} \frac{p''}{p'} v'' \right] \\ &= \left[p' \cdot g', (g')^{-1} \left(v' + \frac{p''}{p'} v'' \right) \right] \\ &= \left[p', v' + \frac{p''}{p'} v'' \right]. \end{aligned}$$

For the scalar multiplication, take $[p, v] \in \pi_E^{-1}(x)$, $\lambda \in \mathbb{R}$, replace p with $p \cdot g$, v with $g^{-1}v$, and compute

$$[p \cdot g, \lambda g^{-1}v] = [p \cdot g, g^{-1}(\lambda v)] = [p, \lambda v],$$

since the representation ρ takes values in $\text{GL}(V)$. \square

To get trivializations for E in terms of trivializations for P , one proceeds as follows: let (U, Φ) be a principal G -chart, where $U \subseteq M$ is open. So $\Phi: \pi^{-1}[U] \rightarrow U \times G$ has the form $\Phi(p) = (\pi(p), \Phi_G(p))$, with G -equivariant $\Phi_G: \pi^{-1}[U] \rightarrow G$. We set $\Phi^E: \pi_E^{-1}[U] \rightarrow U \times V$ via $\Phi^E[p, v] = (\pi(p), \Phi_G(p)v)$.

Proposition 3

Φ^E is a well-defined VB-chart for E with inverse $(\Phi^E)^{-1}: U \times V \rightarrow \pi_E^{-1}[U]$ given by $(\Phi^E)^{-1}(x, v) = [\Phi^{-1}(x, e), v]$.

Proof: First, take $[p, v] \in \pi_E^{-1}[U]$, and replace p and v with $p \cdot g$ and $g^{-1}v$. Now

$$(\pi(p \cdot g), \Phi_G(p \cdot g)g^{-1}v) = (\pi(p), \Phi_G(p)gg^{-1}v) = (\pi(p), \Phi_G(p)v),$$

as required, since Φ_G is G -equivariant. Next, we have that

$$\Phi^E[\Phi^{-1}(x, e), v] = (\pi\Phi^{-1}(x, e), \Phi_G(\Phi^{-1}(x, e))v) = (x, ev) = (x, v),$$

as well as

$$[\Phi^{-1}(\pi(p), e), \Phi_G(p)v] = [\Phi^{-1}(\pi(p), e)\Phi_G(p), v] = [\Phi^{-1}(\pi(p), \Phi_G(p)), v] = [p, v].$$

So, what we claim to be $(\Phi^E)^{-1}$, indeed is. Finally, let's show that restrictions of Φ^E to fibers of π_E are linear isomorphisms.

- Linearity.

$$\begin{aligned}
 \Phi^E([p', v'] + [p'', v'']) &= \Phi^E \left[p', v' + \frac{p''}{p'} v'' \right] \\
 &= \left(\pi(p'), \Phi_G(p') \left(v' + \frac{p''}{p'} v'' \right) \right) \\
 &= \left(\pi(p'), \Phi_G(p') v' + \Phi_G(p') \frac{p''}{p'} v'' \right) \\
 &= \left(\pi(p'), \Phi_G(p') v' + \Phi_G \left(p' \frac{p''}{p'} \right) v'' \right) \\
 &= (\pi(p'), \Phi_G(p') v' + \Phi_G(p'') v'') \\
 &= (\pi(p'), \Phi_G(p') v') + (\pi(p''), \Phi_G(p'') v'') \\
 &= \Phi^E[p', v'] + \Phi^E[p'', v''],
 \end{aligned}$$

using that Φ_G is G -equivariant and $\pi(p') = \pi(p'')$. Also:

$$\begin{aligned}
 \Phi^E(\lambda[p, v]) &= \Phi^E[p, \lambda v] = (\pi(p), \Phi_G(p) \lambda v) \\
 &= (\pi(p), \lambda \Phi_G(p) v) = \lambda (\pi(p), \Phi_G(p) v),
 \end{aligned}$$

using that ρ takes values in $GL(V)$ and that the vector space structure on the fiber $\{\pi(p)\} \times V$ is the obvious one, happening only on the V -factor.

- Injectivity. Assume that $\Phi^E[p, v] = (\pi(p), 0)$. This means that $\Phi_G(p)v = 0$. But $v \mapsto \Phi_G(p)v$ is an isomorphism (because ρ takes values in $GL(V)$), so this immediately gives that $v = 0$.
- Surjectivity. Assume given $(\pi(p), v) \in \{\pi(p)\} \times V$. Then we clearly have that $\Phi^E[p, \Phi_G(p)^{-1}v] = (\pi(p), \Phi_G(p) \Phi_G(p)^{-1}v) = (\pi(p), v)$.

□

Proceeding, to understand local sections s of E properly, we'll use local gauges for P . Namely, on some open set $U \subseteq M$, fix a local gauge $\psi: U \rightarrow P$. Writing the section s as $s(x) = [\psi(x), s_\psi(x)]$ (this can be arranged for since $s(x) \in E_x$ and $\psi(x) \in P_x$), we obtain a bijective correspondence between local sections $s: U \rightarrow E$ and functions $s_\psi: U \rightarrow V$ — to be regarded as matter fields. The gauge group $\mathcal{G}(P)$ acts not only on P by evaluation, but also on E . We set $\Phi \cdot [p, v] = [\Phi(p), v]$.

Proposition 4

The action $\mathcal{G}(P) \curvearrowright E$ is well-defined.

Proof: Replace p and v with $p \cdot g$ and $g^{-1}v$. Then

$$[\Phi(p \cdot g), g^{-1}v] = [\Phi(p) \cdot g, g^{-1}v] = [\Phi(p), v],$$

since $\Phi \in \mathcal{G}(P)$ is G -equivariant.

□

With this in place, $\mathcal{G}(P)$ acts on local sections of E as well, pointwise. To express how this happens relative to a local gauge, recall that $\mathcal{G}(P) \cong \mathcal{C}^\infty(P, G)^G$ as follows: since $\Phi(p)$ and p are on the same fiber, there is $\sigma_\Phi(p) \in G$ such that $\Phi(p) = p \cdot \sigma_\Phi(p)$. Moreover, the G -equivariance relation, $\Phi(p \cdot g) = \Phi(p) \cdot g$, now implies that we have $(p \cdot g) \cdot \sigma_\Phi(p \cdot g) = (p \cdot \sigma_\Phi(p)) \cdot g$, so $\sigma_\Phi(p \cdot g) = g^{-1}\sigma_\Phi(p)g$. The correspondence is $\Phi \leftrightarrow \sigma_\Phi$.

Proposition 5

Let s be a local section of E , $\Phi \in \mathcal{G}(P)$, and ψ be a local gauge for P . Then we have

$$(\Phi \cdot s)(x) = [\psi(x), \sigma_\Phi(\psi(x))s_\psi(x)].$$

Proof: Directly compute

$$\begin{aligned} (\Phi \cdot s)(x) &= \Phi[\psi(x), s_\psi(x)] = [\Phi(\psi(x)), s_\psi(x)] \\ &= [\psi(x) \cdot \sigma_\Phi(\psi(x)), s_\psi(x)] = [\psi(x), \sigma_\Phi(\psi(x))s_\psi(x)]. \end{aligned}$$

□

3 Differential forms

Recall that if Q is a smooth manifold and we have an action $G \curvearrowright Q$ which is free and proper (so Q/G is a smooth manifold), then $\Omega^k(Q/G) \cong \Omega_{\text{hor}}^k(Q)^G$, where $\Omega_{\text{hor}}^k(Q)^G$ consists of all the G -invariant horizontal k -forms. Here, horizontal means that the differential form produces zero whenever one of its arguments is in the kernel of the derivative of the quotient projection $Q \rightarrow Q/G$. In our setting, similar arguments work, considering V -valued forms instead. Since the principal G -bundle $P \rightarrow M$ is such that $P/G \cong M$, we have that $\Omega_{\text{hor}}^k(P, V)^\rho \cong \Omega^k(M, E)$. Suggestively, each $\omega \in \Omega_{\text{hor}}^k(P, V)^\rho$ satisfies $R_g^*\omega = \rho(g^{-1}) \circ \omega$ and ω produces zero whenever one of its arguments is horizontal (relative to the fixed $A \in \Omega^1(P, \mathfrak{g})$).

4 Connections

Assume that the principal bundle $\pi: P \rightarrow M$ is equipped with an Ehresmann connection. That is, a 1-form $A \in \Omega^1(P, \mathfrak{g})$ such that $A(X^\#) = X$ for all $X \in \mathfrak{g}$ (where $X^\# \in \mathfrak{X}(P)$ stands for the action field generated by X) and $R_g^*A = \text{Ad}(g^{-1}) \circ A$, for all $g \in G$, where $R_g: P \rightarrow P$ is the right action of the element g . Choosing such A is equivalent to choosing a horizontal distribution $\mathcal{H} \hookrightarrow TP$ with $TP = \mathcal{H} \oplus \mathcal{V}$, where $\mathcal{V}_p = \ker d\pi_p$ is the natural vertical distribution of the bundle, and $d(R_g)_p[\mathcal{H}_p] = \mathcal{H}_{p \cdot g}$. The correspondence is $A \leftrightarrow \ker A$. The restriction of $d\pi_p$ gives an isomorphism $\mathcal{H}_p \cong T_{\pi(p)}M$.

Proposition 6

Given $\gamma: [0, 1] \rightarrow M$ with $\gamma(0) = x$ and $\gamma(1) = y$, for each $p \in P_x$ there is a unique horizontal lift $\gamma_p^h: [0, 1] \rightarrow P$ with $\gamma_p^h(0) = p$.

Proof: Since $P \rightarrow M$ is a bundle and $[0, 1]$ is contractible, there is a lift $\tilde{\gamma}: [0, 1] \rightarrow P$ of γ , which is not, in general, horizontal. So, we must correct it. Let's solve a differential equation for $g: [0, 1] \rightarrow G$ making $\alpha(t) \doteq \tilde{\gamma}(t) \cdot g(t)$ horizontal. We have that

$$\dot{\alpha}(t) = d(\mathbf{R}_{g(t)})_{\tilde{\gamma}(t)}(\dot{\tilde{\gamma}}(t)) + d(\mathcal{O}_{\tilde{\gamma}(t)})_{g(t)}(\dot{g}(t))$$

by the chain rule, but the second term can be simplified, by using the general relation $\mathcal{O}_{p \cdot g} = \mathcal{O}_p \circ L_g$:

$$\dot{\alpha}(t) = d(\mathbf{R}_{g(t)})_{\tilde{\gamma}(t)}(\dot{\tilde{\gamma}}(t)) + d(\mathcal{O}_{\alpha(t)})_e(g(t)^{-1}\dot{g}(t)).$$

This reads

$$\dot{\alpha}(t) = d(\mathbf{R}_{g(t)})_{\tilde{\gamma}(t)}(\dot{\tilde{\gamma}}(t)) + (g(t)^{-1}\dot{g}(t))_{\alpha(t)}^\#.$$

Apply A to obtain

$$0 = \text{Ad}(g(t)^{-1})A_{\tilde{\gamma}(t)}(\dot{\tilde{\gamma}}(t)) + g(t)^{-1}\dot{g}(t).$$

So, simplifying Ad , we consider the initial value problem for g :

$$\begin{cases} \dot{g}(t) = -A_{\tilde{\gamma}(t)}(\dot{\tilde{\gamma}}(t))g(t) \\ g(0) = e \end{cases}$$

This system has a unique solution defined for all $t \in [0, 1]$. □

With this, we define $\Pi_\gamma^A: P_x \rightarrow P_y$ by $\Pi_\gamma^A(p) = \gamma_p^h(1)$. This is called the parallel transport operator along γ , induced by A .

Proposition 7

- (a) $\Pi_\gamma^A: P_x \rightarrow P_y$ is G -equivariant.
- (b) $\Pi_{\gamma*\eta}^A = \Pi_\eta^A \circ \Pi_\gamma^A$, where $*$ denotes concatenation and the initial point of η equals the terminal point of γ .
- (c) $(\Pi_\gamma^A)^{-1} = \Pi_{\gamma^\leftarrow}^A$, where $\gamma^\leftarrow(t) = \gamma(1-t)$ is γ travelled in the reverse order.
- (d) If $\Phi \in \mathcal{G}(P)$, then $\gamma_{\Phi(p)}^{h,A}(t) = \Phi(\gamma_p^{h,\Phi^*A}(t))$. Hence $\Pi_\gamma^{\Phi^*A} = \Phi^{-1} \circ \Pi_\gamma^A \circ \Phi$.

Proof:

- (a) This is a general consequence of the fact that $\gamma_{p \cdot g}^h(t) = \gamma_p^h(t) \cdot g$ for all $t \in [0, 1]$. Indeed, for $t = 0$ we have that $\gamma_p^h(0) \cdot g = p \cdot g$, and $t \mapsto \gamma_p^h(t) \cdot g$ is horizontal, since $\ker A$ is G -invariant (so that the derivative of \mathbf{R}_g takes horizontal vectors to horizontal vectors).

- (b) Clear.
- (c) Follows from (b).
- (d) If \mathcal{H}^A and \mathcal{H}^{Φ^*A} are the horizontal distributions of A and Φ^*A , recall that we have the relation $d\Phi_p[\mathcal{H}_p^{\Phi^*A}] = \mathcal{H}_{\Phi(p)}^A$, for all $p \in P$. For $t = 0$, we have that $\Phi(\gamma_p^{h, \Phi^*A}(0)) = \Phi(p)$. And moreover, we have that

$$\frac{d}{dt} \Big|_{t=0} \Phi(\gamma_p^{h, \Phi^*A}(t)) = d\Phi_{\gamma_p^{h, \Phi^*A}(t)}(\dot{\gamma}_p^{h, \Phi^*A}(t))$$

is A -horizontal. This establishes the relation between horizontal lifts. Now plug $t = 1$ to conclude that $\Pi_\gamma^A(\Phi(p)) = \Phi(\Pi_\gamma^{\Phi^*A}(p))$, as required. □

Keeping this notation, every parallel transport operator also acts on E . Namely, we define $\Pi_\gamma^{E,A}: E_x \rightarrow E_y$ by $\Pi_\gamma^{E,A}[p, v] = [\Pi_\gamma^A(p), v]$.

Proposition 8

$\Pi_\gamma^{E,A}$ is well-defined.

Proof: Replace p with $p \cdot g$ and v with $g^{-1}v$. Then

$$[\Pi_\gamma^A(p \cdot g), g^{-1}v] = [\Pi_\gamma^A(p) \cdot g, g^{-1}v] = [\Pi_\gamma^A(p), v],$$

as required. □

To explore things further, we'll use the expressions for A relative to a local gauge $\psi: U \rightarrow P$. The pull-back ψ^*A is denoted simply by $A_\psi \in \Omega^1(U, \mathfrak{g})$. Generally, we know that parallel transport operators between fibers of a vector bundle allow us to reconstruct the covariant derivative ∇ . We'll use the $\Pi_\gamma^{E,A}$ to define a connection ∇^A on E , as follows:

- (1) Pick $x \in M$ and $v \in T_xM$. Take a curve $\gamma: [0, 1] \rightarrow M$ with $\gamma(0) = x$. For each $t \in [0, 1]$, write $\gamma_t = \gamma|_{[0,t]}$
- (2) Take a (local) section s of E . Then $s(\gamma(t)) \in E_{\gamma(t)}$ for all $t \in [0, 1]$. Then transport it back: $(\Pi_{\gamma_t}^{E,A})^{-1}(s(\gamma(t))) \in E_x$.
- (3) Take the derivative:

$$\frac{d}{dt} \Big|_{t=0} (\Pi_{\gamma_t}^{E,A})^{-1}(s(\gamma(t))).$$

Proposition 9

Relative to ψ , if $\dot{\gamma}(0) = \mathbf{v}$, we have

$$\left. \frac{d}{dt} \right|_{t=0} (\Pi_{\gamma_t}^{E,A})^{-1}(s(\gamma(t))) = [\psi(x), d(s_\psi)_x(\mathbf{v}) + \rho_*(A_\psi(\mathbf{v}))s_\psi(x)].$$

Proof: We clearly have

$$(\Pi_{\gamma_t}^{E,A})^{-1}s(\gamma(t)) = (\Pi_{\gamma_t}^{E,A})^{-1}[\psi(\gamma(t)), s_\psi(\gamma(t))] = [(\Pi_{\gamma_t}^A)^{-1}\psi(\gamma(t)), s_\psi(\gamma(t))],$$

but since $(\Pi_{\gamma_t}^A)^{-1}\psi(\gamma(t)) \in P_x$ for all t , there is $g: [0, 1] \rightarrow G$ such that

$$(\Pi_{\gamma_t}^A)^{-1}\psi(\gamma(t)) = \psi(x) \cdot g(t)$$

for all $t \in [0, 1]$. This immediately gives that

$$(\Pi_{\gamma_t}^{E,A})^{-1}s(\gamma(t)) = [\psi(x), g(t)s_\psi(\gamma(t))].$$

Now, γ_0 is the constant curve x , meaning that the corresponding parallel transport operator is the identity, and thus $g(0) = e$. We will also need to find $\dot{g}(0) \in \mathfrak{g}$, since

$$\left. \frac{d}{dt} \right|_{t=0} (\Pi_{\gamma_t}^{E,A})^{-1}s(\gamma(t)) = [\psi(x), d(s_\psi)_x(\mathbf{v}) + \rho_*(\dot{g}(0))s_\psi(x)]$$

by the product rule (and recalling that the juxtaposition $g(t)s_\psi(\gamma(t))$ was a shorthand for $\rho(g(t))s_\psi(\gamma(t))$). Taking derivatives at 0, we immediately see that

$$\psi(x) \cdot g(t) = (\Pi_{\gamma_t}^A)^{-1}\psi(\gamma(t)) \implies \dot{g}(0)_{\psi(x)}^\# = \left. \frac{d}{dt} \right|_{t=0} (\Pi_{\gamma_t}^A)^{-1}\psi(\gamma(t)),$$

but differentiating this last expression on the right requires the little usual trick: define

$$F(s, t) = \Pi_{\gamma_s}^A((\Pi_{\gamma_t}^A)^{-1}\psi(\gamma(t)))$$

and note that $\psi(\gamma(t)) = F(t, t)$, and compute

$$d\psi_x(\mathbf{v}) = \frac{\partial F}{\partial t}(0, 0) + \frac{\partial F}{\partial s}(0, 0) = \dot{g}(0)_{\psi(x)}^\# + \left. \frac{d}{dt} \right|_{t=0} \Pi_{\gamma_t}^A(\psi(x)).$$

Since the curve $t \mapsto \Pi_{\gamma_t}^A(\psi(x))$ is horizontal, applying A to everything gives that $A_\psi(\mathbf{v}) = \dot{g}(0)$, as required. \square

In particular, such expression depends on $\gamma(0)$ and $\dot{\gamma}(0)$, but not on γ itself. So if, again, $\dot{\gamma}(0) = \mathbf{v} \in T_x M$, we define

$$\nabla_{\mathbf{v}}^A s = \left. \frac{d}{dt} \right|_{t=0} (\Pi_{\gamma_t}^{E,A})^{-1}(s(\gamma(t))),$$

and if $\mathbf{X} \in \mathfrak{X}(M)$, we also define $\nabla_{\mathbf{X}}^A s$. Relative to ψ , we write $\nabla_{\mathbf{X}}^A s = [\psi, \nabla_{\mathbf{X}}^A s_\psi]$, where

$$\nabla_{\mathbf{X}}^A s_\psi = d(s_\psi)(\mathbf{X}) + \rho_*(A_\psi(\mathbf{X}))s_\psi.$$

So $\nabla^A = d + \rho_* A_\psi$. For this reason, A_ψ is called the Christoffel form of A relative to ψ .

Proposition 10
 ∇^A is a Koszul connection on E .

Proof: All the properties are local, so we may verify them with a local gauge ψ , as usual. The expression for $\nabla_X^A s_\psi$ is clearly additive in X and s_ψ , and $\mathcal{C}^\infty(M)$ -linear in the variable X . Let's verify the Leibniz rule. Let $f \in \mathcal{C}^\infty(M)$. Clearly $(fs)_\psi = fs_\psi$, so

$$\begin{aligned} \nabla_X^A(fs_\psi) &= d(fs_\psi)(X) + \rho_*(A_\psi(X))(fs_\psi) \\ &= X(f)s_\psi + fd(s_\psi)(X) + f\rho_*(A_\psi(X))s_\psi \\ &= X(f)s_\psi + f\nabla_X^A s_\psi, \end{aligned}$$

□

Remark. A shorter argument: $\nabla^A = d + \rho_* A_\psi$ equals a connection (d) plus a tensor ($\rho_* A_\psi$), so it is a connection.

Last three remarks:

- If \mathcal{F} is a smooth endofunctor of the category of finite-dimensional real vector spaces and linear maps (smooth means that the action on the level of morphisms is smooth), then for each $\rho: G \rightarrow \text{GL}(V)$ we get $\mathcal{F}\rho: G \rightarrow \text{GL}(\mathcal{F}V)$, and so we can form the associated bundle $P \times_{\mathcal{F}\rho} \mathcal{F}V$. But \mathcal{F} also acts fiberwise on the associated vector bundle $P \times_\rho V$, producing $\mathcal{F}(P \times_\rho V)$. These two bundles are isomorphic simply because they are described by the same cocycles (relative to trivializations induced by principal G -charts for P). If $\tau_{\alpha\beta}$ is an element of the cocycle, then $\rho \circ \tau_{\alpha\beta}$ is an element of the cocycle defining $P \times_\rho V$. And the associativity law $\mathcal{F} \circ (\rho \circ \tau_{\alpha\beta}) = (\mathcal{F} \circ \rho) \circ \tau_{\alpha\beta}$ holds. If \mathcal{F} is a multivariable smooth functor, a similar argument applies. So, for example, the associated vector bundle to P under the dual representation of ρ is in fact the dual of the associated vector bundle to P under ρ . And so on.
- Generally, if V carries a linear G -structure, then we have an induced G -structure on $\text{Fr}(E)$, which is parallel relative to ∇^A . Here's one concrete example: if we take a covariant k -tensor $T \in (V^*)^{\otimes k}$ on V which is T invariant, then we have $T^E \in \Gamma((E^*)^{\otimes k})$ defined by $T_x^E([p, v_1], \dots, [p, v_k]) = T(v_1, \dots, v_k)$ (it is well-defined). Now, suppressing ρ and ρ_* , differentiating the G -invariance relation $T(gv_1, \dots, gv_k) = T(v_1, \dots, v_k)$ relative to the variable g and evaluating at $X \in \mathfrak{g}$, we obtain

$$\sum_{i=1}^n T(v_1, \dots, Xv_i, \dots, v_k) = 0.$$

This means that, choosing a local gauge ψ for P , we have

$$\begin{aligned} \sum_{i=1}^n T^E(s_1, \dots, \nabla_X^A s_i, \dots, s_k) &= \sum_{i=1}^n T(s_{1,\psi}, \dots, \nabla_X^A s_{i,\psi}, \dots, s_{k,\psi}) \\ &= \sum_{i=1}^n T(s_{1,\psi}, \dots, d(s_{i,\psi})(X) + \rho_*(A_\psi(X))s_{i,\psi}, \dots, s_{k,\psi}) \end{aligned}$$

$$\begin{aligned}
 &= \sum_{i=1}^n T(s_{1,\psi}, \dots, d(s_{i,\psi})(\mathbf{X}), \dots, s_{k,\psi}) \\
 &= \mathbf{X}(T(s_{1,\psi}, \dots, s_{k,\psi})) \\
 &= \mathbf{X}(T^E(s_1, \dots, s_k)),
 \end{aligned}$$

for all $\mathbf{X} \in \mathfrak{X}(M)$ and (local) sections s_1, \dots, s_k of E . This means that $\nabla^A T^E = 0$. In particular, a G -invariant inner product on V (which always exists when G is compact, by Weyl's unitary trick) induces a parallel fiber metric on E .

- If we denote ∇^A by $\nabla^{A,\rho}$, and noting that if E has a connection, then $\mathcal{F}E$ also inherits one (usually by requiring some structure to be parallel — e.g., connections in hom-bundles are characterized by making the evaluation map parallel), then it turns out that $\mathcal{F}(\nabla^{A,\rho}) = \nabla^{A,\mathcal{F}\rho}$ by default, so there is no ambiguity when writing things like $\nabla^A T^E$ as in the previous item.

5 Gauge independence of direct definition of ∇^A

Often, one defines ∇^A on E by choosing a local gauge $\psi: U \rightarrow P$ and declaring

$$\nabla_{\mathbf{X}}^A s = [\psi, d(s_\psi)(\mathbf{X}) + \rho_*(A_\psi(\mathbf{X}))s_\psi].$$

Then it is necessary to check that this definition is independent of ψ . So, let's make a change of gauge $\psi \mapsto \psi' = \psi \cdot g$, where $g: U \rightarrow G$ is a physical gauge transformation. More precisely, $\psi'(x) = \psi(x) \cdot g(x)$ for all $x \in U$.

Proposition 11

- $s_{\psi \cdot g} = g^{-1}s_\psi$.
- $d(s_{\psi \cdot g})_x(\mathbf{v}) = -\rho_*((g^*\Theta)_x(\mathbf{v}))\rho(g(x)^{-1})s_\psi(x) + \rho(g(x)^{-1})d(s_\psi)_x(\mathbf{v})$.
- $d(\psi \cdot g)_x(\mathbf{v}) = d(R_{g(x)})_{\psi(x)}(d\psi_x(\mathbf{v})) + (g^*\Theta)_x(\mathbf{v})_{\psi(x) \cdot g(x)}^\#$, for all $x \in U$ and $\mathbf{v} \in T_x M$.
- $A_{\psi \cdot g} = \text{Ad}(g^{-1}) \circ A_\psi + g^*\Theta$.

Remark. Above, $\Theta \in \Omega^1(G, \mathfrak{g})$ is the left-invariant Maurer-Cartan form on G , given by $\Theta_a(\mathbf{w}) = d(L_{a^{-1}})_a \mathbf{w}$. Occasionally, we'll just write $a^{-1}\mathbf{w}$.

Proof:

- $s = [\psi \cdot g, s_{\psi \cdot g}] = [\psi, g s_{\psi \cdot g}]$ implies that $s_\psi = g s_{\psi \cdot g}$, and the conclusion follows.
- The usual trick of separating variables works: define $F(x, y) = \rho(g(x)^{-1})s_\psi(y)$ and note that $s_{\psi \cdot g}(x) = F(x, x)$, so

$$d(s_{\psi \cdot g})_x(\mathbf{v}) = (\partial_1 F)_{(x,x)}(\mathbf{v}) + (\partial_2 F)_{(x,x)}(\mathbf{v}).$$

But

$$(\partial_2 F)_{(x,x)}(\mathbf{v}) = \rho(g(x)^{-1})d(s_\psi)_x(\mathbf{v}),$$

and

$$\begin{aligned} (\partial_1 F)_{(x,x)}(\mathbf{v}) &= d\rho_{g(x)^{-1}}(-g(x)^{-1}dg_x(\mathbf{v})g(x)^{-1})s_\psi(x) \\ &= -d\rho_{g(x)^{-1}}((g^*\Theta)_x(\mathbf{v})g(x)^{-1})s_\psi(x) \\ &= -\rho_*((g^*\Theta)_x(\mathbf{v}))\rho(g(x)^{-1})s_\psi(x). \end{aligned}$$

We're using the standard formulas for the derivative of the inversion in any Lie group, the chain rule to differentiate $\rho \circ R_{g(x)^{-1}} = R_{\rho(g(x)^{-1})} \circ \rho$ (because ρ is a homomorphism) at the identity $e \in G$, and that multiplication in $GL(V)$ is the restriction of a linear map $\mathfrak{gl}(V) \rightarrow \mathfrak{gl}(V)$ (so its derivative is itself).

- (c) The usual trick works again: define $F(x, y) = \psi(x) \cdot g(y)$, note that $\psi'(x) = F(x, x)$, so

$$d(\psi')_x(\mathbf{v}) = (\partial_1 F)_{(x,x)}(\mathbf{v}) + (\partial_2 F)_{(x,x)}(\mathbf{v}).$$

But

$$(\partial_1 F)_{(x,x)}(\mathbf{v}) = d(R_{g(x)})_{\psi(x)}(d\psi_x(\mathbf{v})),$$

and

$$\begin{aligned} (\partial_2 F)_{(x,x)}(\mathbf{v}) &= d(\mathcal{O}_{\psi(x)})_{g(x)}(dg_x(\mathbf{v})) \\ &= d(\mathcal{O}_{\psi(x) \cdot g(x)})_e((d(L_{g(x)})_{g(x)}^{-1}dg_x(\mathbf{v}))) \\ &= d(\mathcal{O}_{\psi(x) \cdot g(x)})_e((g^*\Theta)_x(\mathbf{v})) \\ &= (g^*\Theta)_x(\mathbf{v})_{\psi(x) \cdot g(x)}^\#. \end{aligned}$$

- (d) From (c), we have that

$$\begin{aligned} (A_{\psi \cdot g})_x(\mathbf{v}) &= A_{\psi(x) \cdot g(x)}(d(\psi \cdot g)_x(\mathbf{v})) \\ &= A_{\psi(x) \cdot g(x)}(d(R_{g(x)})_{\psi(x)}(d\psi_x(\mathbf{v})) + (g^*\Theta)_x(\mathbf{v})_{\psi(x) \cdot g(x)}^\#) \\ &= A_{\psi(x) \cdot g(x)}(d(R_{g(x)})_{\psi(x)}(d\psi_x(\mathbf{v}))) + (g^*\Theta)_x(\mathbf{v}) \\ &= (R_{g(x)}^*A)_{\psi(x)}(d\psi_x(\mathbf{v})) + (g^*\Theta)_x(\mathbf{v}) \\ &= \text{Ad}(g(x)^{-1})(A_{\psi(x)}(d\psi_x(\mathbf{v}))) + (g^*\Theta)_x(\mathbf{v}) \\ &= \text{Ad}(g(x)^{-1})((A_\psi)_x(\mathbf{v})) + (g^*\Theta)_x(\mathbf{v}). \end{aligned}$$

□

Now everything is in place. Since

$$[\psi \cdot g, d(s_{\psi \cdot g}) + \rho_*(A_{\psi \cdot g})s_{\psi \cdot g}] = [\psi, g(d(s_{\psi \cdot g}) + \rho_*(A_{\psi \cdot g})s_{\psi \cdot g})],$$

there is only one computation left to do. Let's carry ρ , x and \mathbf{v} in full detail.

$$\rho(g(x)) (d(s_{\psi \cdot g})_x(\mathbf{v}) + \rho_*((A_{\psi \cdot g})_x(\mathbf{v}))s_{\psi \cdot g}(x)) =$$

$$\begin{aligned}
 &= \rho(g(x)) \left(-\rho_*((g^*\Theta)_x(\mathbf{v}))\rho(g(x)^{-1})s_\psi(x) + \rho(g(x)^{-1})d(s_\psi)_x(\mathbf{v}) \right. \\
 &\quad \left. + \rho_*(\text{Ad}_{g(x)^{-1}}(A_\psi)_x(\mathbf{v}) + (g^*\Theta)_x(\mathbf{v}))\rho(g(x)^{-1})s_\psi(x) \right) \\
 &\stackrel{(\dagger)}{=} \rho(g(x)) \left(\rho(g(x)^{-1})d(s_\psi)_x(\mathbf{v}) + \rho_*(\text{Ad}_{g(x)^{-1}}(A_\psi)_x(\mathbf{v}))\rho(g(x)^{-1})s_\psi(x) \right) \\
 &\stackrel{(\ddagger)}{=} d(s_\psi)_x(\mathbf{v}) + \rho_*((A_\psi)_x(\mathbf{v}))s_\psi(x),
 \end{aligned}$$

where in (\dagger) we cancel all the terms with Θ , and in (\ddagger) we use that ρ is a homomorphism and $g(x)\text{Ad}_{g(x)^{-1}}((A_\psi)_x(\mathbf{v}))g(x)^{-1} = (A_\psi)_x(\mathbf{v})$.

6 Curvature

The curvature of $A \in \Omega^1(P, \mathfrak{g})$ is $F_A \in \Omega^2(P, \mathfrak{g})$ given by

$$F_A = dA + \frac{1}{2}[A, A]$$

or, more explicitly, $F_A(\mathbf{X}, \mathbf{Y}) = dA(\mathbf{X}, \mathbf{Y}) + [A(\mathbf{X}), A(\mathbf{Y})]$, for all $\mathbf{X}, \mathbf{Y} \in \mathfrak{X}(P)$. If we have coordinates (x^μ) for the base manifold, and a local gauge ψ , all on some open set $U \subseteq M$, then we have $F_{A,\psi} = \psi^*(F_A) \in \Omega^2(U, \mathfrak{g})$, and we set $F_{\mu\nu} = F_{A,\psi}(\partial_\mu, \partial_\nu)$. Then, we have

$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu + [A_\mu, A_\nu],$$

where $A_\mu = (A_\psi)(\partial_\mu)$. Note that $A_\mu, F_{\mu\nu}$ are smooth functions on U , valued on \mathfrak{g} . When G is abelian, $[A_\mu, A_\nu] = 0$. It remains to establish what is the relation between R^{∇^A} and F_A . We do this using ψ .

Proposition 12

$$R^{\nabla^A}(\partial_\mu, \partial_\nu)s_\psi = \rho_*(F_{\mu\nu})s_\psi.$$

Proof: It's a direct computation:

$$\begin{aligned}
 R^{\nabla^A}(\partial_\mu, \partial_\nu)s_\psi &= \nabla_{\partial_\mu}^A \nabla_{\partial_\nu}^A s_\psi - \nabla_{\partial_\nu}^A \nabla_{\partial_\mu}^A s_\psi \\
 &= \nabla_{\partial_\mu}^A (\partial_\nu s_\psi + \rho_*(A_\nu)s_\psi) - \nabla_{\partial_\nu}^A (\partial_\mu s_\psi + \rho_*(A_\mu)s_\psi) \\
 &= \partial_\mu \partial_\nu s_\psi + \rho_*(A_\mu)\partial_\nu s_\psi + \partial_\mu[\rho_*(A_\nu)s_\psi] + \rho_*(A_\mu)\rho_*(A_\nu)s_\psi \\
 &\quad - \partial_\nu \partial_\mu s_\psi + \rho_*(A_\nu)\partial_\mu s_\psi - \partial_\nu[\rho_*(A_\mu)s_\psi] - \rho_*(A_\nu)\rho_*(A_\mu)s_\psi \\
 &= \rho_*(A_\mu)\partial_\nu s_\psi + \rho_*(\partial_\mu A_\nu)s_\psi + \rho_*(A_\nu)\partial_\mu s_\psi \\
 &\quad - \rho_*(A_\nu)\partial_\mu s_\psi - \rho_*(\partial_\nu A_\mu)s_\psi - \rho_*(A_\mu)\partial_\nu s_\psi + \rho_*([A_\mu, A_\nu])s_\psi \\
 &= \rho_*(\partial_\mu A_\nu)s_\psi - \rho_*(\partial_\nu A_\mu)s_\psi + \rho_*([A_\mu, A_\nu])s_\psi \\
 &= \rho_*(\partial_\mu A_\nu - \partial_\nu A_\mu + [A_\mu, A_\nu])s_\psi \\
 &= \rho_*(F_{\mu\nu})s_\psi,
 \end{aligned}$$

as required. □

Remark. It's not clear how to write such an expression without relying on a local gauge. If $X \in \mathfrak{g}$, trying to define $\rho_*(X)[p, v]$ as $[p, \rho_*(X)v]$ doesn't work, as replacing p and v with $p \cdot g$ and $\rho(g^{-1})v$ leads to $[p, \rho_*(\text{Ad}_g(X))v]$ instead.

7 Arbitrary associated fiber bundles

Essentially everything that happened here can be done replacing ρ and V with a manifold F and an action $G \curvearrowright F$. We have that $(P \times F) \curvearrowright G$ via $(p, y)g = (pg, g^{-1}y)$, and $P \times_G F = (P \times F)/G$ is a manifold whose elements are classes $[p, y]$. This is a locally trivial fiber bundle with typical fiber F , and local trivializations $(U, \tilde{\Phi})$ are constructed from principal G -charts (U, Φ) for P , via $\tilde{\Phi}[p, y] = (\pi(p), \Phi_G(p)y)$, as before (it is well-defined). Inverses are $\tilde{\Phi}^{-1}(x, y) = [\Phi^{-1}(x, e), y]$. Restrictions to fibers are diffeomorphisms onto F . One can locally define horizontal lifts (but the domains pay the price: given $x \in M$ and $\gamma[0, 1] \rightarrow M$ with $\gamma(0) = x$, the map $y \mapsto \gamma_y^h(t)$ is not necessarily defined for all $y \in (P \times_G F)_y$ and/or $t \in [0, 1]$). And so on.

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