## AFFINE MODIFICATIONS ON CURVATURE

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If *M* is a smooth manifold, then the space Conn(TM) of affine connections on the tangent bundle of *M* is an affine space, whose associated translation space is the space of type (1,2)-tensor fields on *M*, i.e., sections of the vector bundle  $[T^*M]^{\otimes 2} \otimes TM$  over *M*. For any  $\nabla \in \text{Conn}(TM)$ , we have  $\tau^{\nabla}$ ,  $R^{\nabla}$ , and  $\text{Ric}^{\nabla}$ . Let's see how each of them behaves when we add a tensor field *A* to  $\nabla$ . Write:

- $\widetilde{A}$  for (twice) the skew-symmetrization of A, i.e.,  $\widetilde{A}_X Y = A_X Y A_Y X$ .
- $A_{\tau^{\nabla}}$  for the type (1,3)-tensor field given by  $(X, Y, Z) \mapsto A_{\tau^{\nabla}(X, Y)}Z$ .
- $\operatorname{tr}_1^1(A)$  for the 1-form defined by  $\operatorname{tr}_1^1(A)(Y) = \operatorname{tr}(AY)$ , as well as  $\operatorname{tr}_1^1(A_{\tau\nabla})$  for the type (0, 2)-tensor field given by  $\operatorname{tr}_1^1(A_{\tau\nabla})(Y, Z) = \operatorname{tr}(X \mapsto A_{\tau\nabla(X,Y)}Z)$ .
- [A, A] for the commutator given by  $[A, A](X, Y) = 2[A_X, A_Y]$ .
- $d^{\nabla}A$  for the exterior derivative (computed with the aid of  $\nabla$ ) of the tensor *A* regarded a End(*TM*)-valued 1-form.
- div<sup>∇</sup> for the ∇-divergence of *A*, i.e., the (0,2)-tensor field defined by the trace div<sup>∇</sup>(*A*)(*X*, *Y*) = tr(*Z* → (∇<sub>*Z*</sub>*A*)(*X*, *Y*)).
- $\operatorname{tr}(A \circ A)$  for the map  $(Y, Z) \mapsto \operatorname{tr}(AZ \circ A_Y)$ .
- $\nabla \omega$  is given by  $(X, Y) \mapsto [\nabla_X \omega] Y$  (in this order of arguments), for each 1-form  $\omega$  on M.

## Theorem

(i)  $\tau^{\nabla + A} = \tau^{\nabla} + \widetilde{A}$ .

(ii) 
$$R^{\nabla + A} = R^{\nabla} + d^{\nabla}A + [A, A]/2$$
.

(iii) 
$$\operatorname{Ric}^{\nabla+A} = \operatorname{Ric}^{\nabla} + \operatorname{div}^{\nabla} A - \nabla \operatorname{tr}_{1}^{1}(A) + \operatorname{tr}_{1}^{1}(A) \circ A - \operatorname{tr}(A \circ A) + \operatorname{tr}_{1}^{1}(A_{\tau^{\nabla}}).$$

## **Proof:**

(i) This is the easiest one to establish, as expected:

$$\tau^{\nabla + A}(X, Y) = (\nabla + A)_X Y - (\nabla + A)_Y X - [X, Y]$$
  
=  $\nabla_X Y + A_X Y - \nabla_Y X - A_Y X - [X, Y]$   
=  $\tau^{\nabla}(X, Y) + \widetilde{A}_X Y.$ 

(ii) This is a slightly longer brute-force computation. First we compute

$$(\nabla + A)_X (\nabla + A)_Y Z = \nabla_X \nabla_Y Z + \nabla_X A_Y Z + A_X \nabla_Y Z + A_X A_Y Z$$

as well as

$$(\nabla + A)_{[X,Y]}Z = \nabla_{[X,Y]}Z + A_{[X,Y]}Z$$

so that

$$R^{\nabla+A}(X,Y)Z = R^{\nabla}(X,Y)Z + [A_X,A_Y]Z + (*),$$

where

$$(*) = \nabla_X A_Y Z + A_X \nabla_Y Z - \nabla_Y A_X Z - A_Y \nabla_X Z - A_{[X,Y]} Z.$$

It remains to see that the above expression indeed equals  $(d^{\nabla}A)(X,Y)Z$ . But

$$(\mathbf{d}^{\nabla} A)(X,Y)Z = (\nabla_X(A_Y) - \nabla_Y(A_X) - A_{[X,Y]})Z$$
  
=  $\nabla_X A_Y Z - A_Y \nabla_X Z - \nabla_Y A_X Z + A_X \nabla_Y Z - A_{[X,Y]} Z,$ 

as required, by definition of exterior derivative.

(iii) It suffices to compute traces in the first variable of  $d^{\nabla}A$  and [A, A]/2. Let's do a coordinate computation<sup>1</sup>. Fix  $Y = \partial_r$  and  $Z = \partial_s$ . First, we have that

$$\begin{split} [A_{\partial_j}, A_{\partial_r}]\partial_s &= A_{\partial_j}A_{\partial_r}\partial_s - A_{\partial_r}A_{\partial_j}\partial_s \\ &= A_{\partial_j}(A_{rs}^k\partial_k) - A_{\partial_r}(A_{js}^k\partial_k) \\ &= (A_{rs}^kA_{jk}^i - A_{js}^kA_{rk}^i)\partial_i, \end{split}$$

so that contracting j = i yields

$$\operatorname{tr}(X \mapsto [A_X, A_{\partial_r}]\partial_s) = A_{rs}^k A_{ik}^i - A_{is}^k A_{rk}^i = (\operatorname{tr}_1^1(A))_k A_{rs}^k - A_{is}^k A_{rk}^i.$$

Hence tr( $X \mapsto [A_X, A_Y]Z$ ) = tr<sub>1</sub><sup>1</sup>(A) $A_YZ$  – tr( $AZ \circ A_Y$ ) for general Y and Z, by tensoriality. Lastly, we focus on the exterior derivative of A. Namely, recall that

$$(\mathbf{d}^{\nabla}A)_{jrs}^{\ i} = A_{rs;j}^{i} - A_{js;r}^{i} + \tau_{jr}^{k}A_{ks}^{i},$$

where  $\tau_{ir}^k$  are the coordinate components of  $\tau^{\nabla}$ . Now, contract j = i to obtain

$$(\mathbf{d}^{\nabla}A)_{irs}^{i} = (\mathbf{div}^{\nabla}A)_{rs} - \mathbf{tr}_{1}^{1}(A)_{s;r} + \tau_{ir}^{k}A_{ks'}^{i}$$

as required.

**Remark.** The torsion  $\tau$ : Conn $(TM) \to \Gamma([T^*M]^{\wedge 2} \otimes TM)$  is an affine map, whose associated linear part is (twice) skew-symmetrization. The Riemann map  $\nabla \mapsto R^{\nabla}$  and the Ricci map  $\nabla \mapsto \operatorname{Ric}^{\nabla}$ , in turn, are not affine (as we have obtained terms which are manifestly quadratic in the variable *A*, in the expressions for the differences  $R^{\nabla + A} - R^{\nabla}$  and  $\operatorname{Ric}^{\nabla + A} - \operatorname{Ric}^{\nabla}$ ).

<sup>&</sup>lt;sup>1</sup>If you see a quick(er) way to do this without coordinates, let me know.